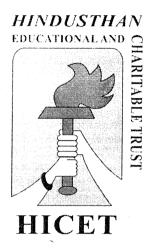
HINDUSTHAN COLLEGE OF ENGINEERING AND TECHNOLOGY

(An Autonomous Institution Affiliated to Anna University, Chennai)
(Approved by AICTE, New Delhi, Accredited by NAAC with 'A' Grade)
Coimbatore - 641 032.

B.E. MECHATRONICS ENGINEERING



CHOICE BASED CREDIT SYSTEM

Revised Curriculum and Syllabus for the Odd Semester

Academic year 2023-24

(Academic Council Meeting Held on 19.06.2023)



CURRICULUM R2022





Hindusthan College of Engineering and Technology (An Autonomous Institution, Affiliated to Anna University, Chennai

(An Autonomous Institution, Affiliated to Anna University, Chennai Approved by AICTE, New Delhi& Accredited by NAAC with 'A' Grade)
Valley Campus, Pollachi Highway, Coimbatore, Tamil Nadu.



DETAILS OF CHANGES CARRIED OUT IN CURRICULUM & SYLLABUS

CBCS PATTERN

UNDERGRADUATE PROGRAMMES

B.E. MECHATRONICS ENGINEERING (UG)

REGULATION-2022

For the students admitted during the academic year 2023-2024 and onwards

SEMESTER I

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY									
1	22MA1101	Matrices and Calculus	BSC	3	1	0	4	4	40	60	100
2	22ME1201	Engineering Drawing	ESC	1	4	0	3	5	40	60	100
		THEORY WITH LAB CO	MPONEN'	Γ							
3	22HE1151	English for Engineers	HSC	2	0	2	3	4	40	60	100
4	22PH1151	Physics for Non-Circuit Engineering	BSC	2	0	2	3	4	50	50	100
5	22IT1151	Python Programming and practices	ESC	2	0	2	3	4	50	50	100
		EEC COURSES (SI	E/AE)								
6	22HE1072	Entrepreneurship & Innovation	AEC	1	0	0	1	1	100	0	100
7	22HE1073	Introduction to Soft Skills	SEC	1	0	0	0	1	100	0	100
		MANDATORY COU	RSE								
8.	22MC1093/ 22MC1094	தமிழர் மரபு / Heritage of Tamils	MC	2	0	0	1	2	100	0	100
9.	22MC1095	Universal Human Values	MC	2	0	0	0	2	40	60	100
			TOTAL	15	5	6	18	27	470	330	800

SEMESTER II

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY									
1	22MA2101	Complex Analysis and Differential Equations	BSC	3	1	0	4	4	40	60	100
2	22PH2102	Applied Mechanics	BSC	2	0	0	2	2	40	60	100
3	22CY2101	Environmental Studies	ESC	2	0	0	2	2	40	60	100
THI	EORY WITH	LAB COMPONENT	,							L	
4	22HE2151	Effective Technical Communication	HSC	2	0	2	3	4	50	50	100
5	22CY2152	Applied Chemistry	BSC	2	0	2	3	4	50	50	100

6	-22MT2251	Fundamentals of Mechatronics	PCC	2	()	2	3	4	50	50	100
	,	PRACTICAL COUR	RSES				-	•			
7	22ME2001	Engineering Practices	ESC	0	()	4	2	4	60	40	100
		EEC COURSES (SE	/AE)			*************					The state of the s
8	22HE2071	Design Thinking	AEC	1	0	2	2	3	100	0	100
9	22HE2073	Soft Skills and Aptitude -I	SEC]	0	0	1	1	100	0	100
		MANDATORY COU	RSE						4		
10.	22MC2094/ 22MC2095	தமிழரும் தொழில் நுட்பமும் / Tamils and Technology	MC	2	0	0	1	2	100	0	100
11.	22MC2093	NCC */NSS / YRC / Sports / Clubs / Society Service - Enrollment (Common)	MC	adn pers dev	niss sona elop erga	ion, ality ome	in nt p	anyo and orogra	enrol one o char amme or abo	f the acter s and	-
			TOTAL	17	1	12	23	30	630	370	1000

SEMESTER III

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY									
1	22MA3105	Fourier Series and Transforms	BSC	3	l	0	4	4	40	60	100
2	22MT3201	Industrial Motor Control	ESC	3	0	0	3	3	40	60	100
3	22MT3202	Solid and Fluid Mechanics	PCC	3	1	0	4	4	40	60	100
4	22MT3203	Digitronics	PCC	3	1	0	4	4	40	60	100
		THEORY WITH LAB CO	MPONEN	Г			1				,
5	22MT3251	Manufacturing Process	PCC	2	0	2	3	4	50	50	100
1.		PRACTICAL					L				
6	22MT3001	Industrial Motor Control Lab	ESC	0	0	4	2	4	60	40	100
7 .	22MT3002	Solid and Fluid Mechanics Lab	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	/AE)								
8	22HE3071	Soft Skills and Aptitude -II	SEC	1	0	0	1	1	100	0	100
9	22MT3072	Home Automation	AEC	0	0	4	2	4	60	40	100
•		MANDATORY COU	RSE								
10	22MC3091	Essence of Indian Traditional Knowledge	MC	l))	0	1	0	100	100
			TOTAL	16	3	14	25	33	490	510	1000



SEMESTER IV

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
-		THEORY			•			,	i	-	
1	22HE4101	IPR and Start-ups	HSC	2	0	0	2	2	40	60	100
2	22MT4201	Processor and controller	PCC	3	0	0	3	3	40	60	100
3	22MT4202	Metrology and Measurements	PCC	3	0	0	3	3	40	60	100
4	22MT4203	Theory of Machines	PCC	3	l	0	4	4	40	60	100
		THEORY WITH LAB CO	MPONEN'	Г	,						
5	22MT4251	Sensors and Transducers	PCC	2	0	2	3	4	50	50	100
6	22MT4252	Fluid Power System	PCC	2	0	2	3.	4	50	50	100
		PRACTICAL	L								
7	22MT4001	Processor and controller Laboratory	PCC	0	0	4	2	4	60	40	100
8	22MT4002	CAD Laboratory	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	/AE)								
9	22HE4071	Soft Skills and Aptitude -III	SEC	1	0	0	1	1	100	0	100
		MANDATORY COU	JRSE	1	1						
10	22MC4091	Indian Constitution	MC	1	0	0	0	1	0	100	100
	• .		TOTAL	17	1	12	23	30	480	520	1000

SEMESTER V

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY							L		
1	22MT5201	Machine Design	PCC	3	1	0	4	4	40	60	100
2	22MT5202	Control System	PCC	3	0	0	3	3	40	60	100
3	22MT53XX	Professional Elective-1	PEC	3	0	0	3	3	40	60	- 100
4	22MT53XX	Professional Elective-2	PEC	3	0	0	3	3	40	60	100
5	22MT53XX	Professional Elective-3	PEC	3	0	0	3	3	40	60	100
		THEORY WITH LAB CO	MPONEN	Г			•	•			
6	22M/T5251	Embedded System with C	PCC	2	0	2	3	4	50	50	100
		PRACTICAL		•							
7	22MT5001	Computer Aided Analysis Laboratory	PCC	0	0	4	2	4	60	40	100
	EEC COURSES (SE/AE)										
8	22HE5071	Soft Skills -4/Foreign languages	SEC	1	0	0	1	1	100	0	100
			TOTAL	18	0	6	21	25	410	390	800

SEMESTER VI

S. No	Course Code	Course Title	Category	I.	Т	P	С	ТСР	CIA	ESE	Total
		THEORY	The second secon	-	***************************************		-				
1	22MT6201	Industrial Automation	PCC	3	0	0	3	3	40	60	100
2	22HE6101	Professional Ethics	HSC	3	0	0	3	3	40	60	100
3	22MT63XX	Professional Elective-4	PEC	3	0	0	3	3	40	60	100
4	22MT63XX	Professional Elective-5	PEC	3	0	0	3	3	40	60	100
5	22XX64XX	Open Elective – 1*	OEC	3	0	0	3	3	40	60	100
6	22XX64XX	Open Elective – 2*	OEC	3	0	0	3	3	40	60	100
		PRACTICAL	3	k		-	L				
7	22MT6001	Industrial Automation Laboratory	PCC	0	0	4	2	4	60	40	100
8	22MT6002	CAM Laboratory	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	/AE)	·							
9.	22HE6071	Soft Skills – 5	SEC	2	0	0	2	2	100	0	100
			TOTAL	20	0	8	24	28	460	440	900

SEMESTER VII

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY	*								
1	22MT7201	Virtual Instrumentation	PCC	3	0	0	3	3	40	60	100
2	22MT7202	Robotics and Machine Vision	PCC	3	1	0	4	. 4	40	60	100
3	22MT73XX	Professional Elective-6	PEC	3	0	0	3	3	40	60	100
4	22XX74XX	Open Elective – 3*	OEC	3	0	0	3	3	40	60	100
5	22XX74XX	Open Elective – 4*	OEC	3	0	0	3	3	40	60	100
		PRACTICAL									
6	22MT7001	Robotics Laboratory	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	AE)								
7	22MT7701	Internship*	SEC	0	0	0	2	2	100	0	100
			TOTAL	- 1	1	- 1	20	22	1	340	700
* - vac	Four weeks ation/placeme	internship carries 2 credit and it will nt training and same will be evaluated in S	be done emester V	in II.	be	fore	S	emes	ter \	/I su	mmer

SEMESTER VIII

S. No	Course Code	Course Title	Category	L	T	P	C	ТСР	CIA	ESE	Total
		EEC COURSES	S (SE/AE)								
1	22MT8901	Project Work/Granted Patent	SEC	0	0	20	10	20	100	0	100
		A Cho	TOTAL	0	0	20	10	20	100	0	100

Note:

- 1. As per the AICTE guideline, in Semester I, II, III & IV NCC one credit subject is added as Value Added Course with Extra Credit. Further, the students' who enrolled his/her name in HICET NCC and Air Wing are eligible to undergo this subject. The earned extra credits printed in the Consolidated Mark sheet as per the regulation.
- 2. NCC course level 1 & Level 2 will be added in the list of open elective subjects in the appropriate semester. Further, the students' who have opted NCC subjects in Semester I, II, III & IV are eligible to undergo NCC Open Elective Subjects.
- 3. The above-mentioned NCC Courses will be offered to the students who are going to be admitted in the Academic Year 2022 23.

OPEN ELECTIVE I AND II (EMERGING TECHNOLOGIES)

To be offered for the students other than CSE, IT, AI&ML, ECE & BIOMEDICAL

S. NO.	COURSE	COURSE TITLE	CATE GORY	1	ERIO R WE		TOTAL CONTACT	CREDITS
	CODE	COURSE TITLE	GOKI	L	T	P	PERIODS	
1	22AI6451	Artificial Intelligence and Machine Learning Fundamentals	OEC	2	0	2	4	3
2	22CS6451	Blockchain Technology	OEC	2	0	2	4	3
3	22EC6451	Cyber security	OEC	2	0	2	. 4	3
4	22EC6452	IoT Concepts and Applications	OEC	2	0	2	4	3
5	22IT6451	Data Science and Analytics	OEC	2	0	2	4	3
6	22BM6451	Augmented and Virtual Reality	OEC	2	0	2	4	3

OPEN ELECTIVE I AND II

To be offered for the students other than AUTO, AERO, AGRI, MECH, MCTS, CIVIL, EEE, CHEMICAL, FOOD TECH, E&I

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY		ERIO R WE		TOTAL CONTACT PERIODS	CREDITS
1	22AE6401	Space Science	OEC	3				2
				<u> </u>	0	0	3	3 .
2	22MT6401	Introduction to Industrial Engineering	OEC	3	0	0	3	3
3	22MT6402	Industrial Safety and Environment	OEC	3	0	0	3	3
4	22CE6401	Climate Change and its Impact	OEC	3	0	0	3	3
5	22CE6402	Environment and Social Impact Assessment	OEC	3	0	0	3	3
6	22ME6401	Renewable Energy System	OEC	3	0	0	3	3
7	22ME6402	Additive Manufacturing systems	OEC	3	0	0	3	3
8	22EI6401	Introduction to Industrial Instrumentation and Control	OEC	3	0	0	3	3
9	22EI6402	Graphical Programming using Virtual Instrumentation	OEC	3	0	0	3	3
10	22AU6401	Fundamentals of Automobile Engineering	OEC	3	0	0	3	3
11	22AU6402	Automotive Vehicle Safety	OEC	3	0	0	3	3
12	22EE6401	Digital Marketing	OEC	3	0	0	3	3
13	22EE6402	Research Methodology	OEC	3	0	0	3	3
14	22FT6401	Traditional Foods	OEC	3	0	0	3	3
15	22AG6401	Urban Agriculture and Organic Farming	OEC	3	0	0	3	3
16	22CH6401	Biomass and Biorefine	OEC	3	0	0	3	3

Note: Non-Circuit Departments can accircuit branches

ive course in the above list to offer for the

OPEN ELECTIVE III

Students shall choose any one of the open elective courses such that the course content or title not belong to their own programme.

(Note: Each programme in our institution is expected to provide one course only)

And desired the same of the sa	S. NO.	COURSE	COURSE TITLE	CATE GORY	PE PEI	CRIO R WE	DS EEK	TOTAL CONTACT	CREDITS
OTHER DESIGNATION		CODE	COURSE TITLE	GORI	L	T	P	PERIODS	
	1	22MT7401	Project Management (Must in the list)	OEC	3	0	0	. 3	3

OPEN ELECTIVE IV

S. NO.	COURSE	COURSE TITLE	CATE GORY		ERIO R WE		TOTAL CONTACT	CREDITS
110.	CODE	COURSE TITLE	GOKI	L	T	P	PERIODS	
1	22LS7401	General studies for competitive examinations	OEC	3	0	0	3	3
2	22LS7402	Human Rights, Women Rights and Gender equity	OEC	3 .	0	0	3	3
3	22LS7403	Indian ethos and Human values	OEC	3	0	0	3	3
4	22LS7404	Financial independence and management	OEC	3	0	0	3	3
5	22LS7405	Yoga for Human Excellence	OEC	3	0	0	3	3
6	22LS7406	Democracy and Good Governance	OEC	3	0	0	3	3
7	22LS7407	NCC Level - II	OEC	3	0	0	3	3

PROFESSIONAL ELECTIVE COURSES: VERTICALS

Vertical I Information Systems	Vertical II Mechanical Engineering	Vertical III Management Studies	Vertical IV Manufacturing Process	Vertical V Vehicle Technology	Vertical VI Robotics and Automation
22MT5301 Database Management System	22MT5304 Composite Materials	22MT5307 Principles of Management	22MT5310 Non-Traditional Machining Techniques	22MT5313 Automobile System	22MT5316 Mobile Robotics
22MT5302 Data Science	22MT5305 Product Design and Development	22MT5308 Disaster Management	22MT5311 Computer Integrated Manufacturing	22MT5314 Automotive Electronics	22MT5317 Soft Robotics
22MT5303 Data Visualization	22MT5306 Applied Thermodynamics	22MT5309 Supply Chain Management	22MT5312 Flexible Manufacturing System	22MT5315 Electrical Vehicles	22MT5318 Micro Robotics
22MT6301 Cyber Safety	22MT6303 Non-Destructive Testing	22MT6305 Economics and Cost Management	22MT6307 Micro Manufacturing	22MT6309 Hybrid Vehicles	22MT6311 Textile Automation

22MT6302 Al for Mechatronics	22MT6304 Diagnostics Techniques	22MT6306 Digital Management	22MT6308 Industrial 4.0		
22MT7301 Optimization Techniques	22MT7302 Machineries in Agriculture	22MT7303 Marketing Management	22MT7304 Rapid Prototyping	22MT7305 Modern Vehicles Technology	22MT7306 Automatic System

Students are permitted to choose all Professional Electives from a particular vertical or from different verticals.

PROFESSIONAL ELECTIVE COURSES: VERTICALS

Details of Vertical I: Information Systems

S. NO.	COURSE	COURSE COURSE TITLE CATE CODE COURSE TITLE GORY		PERIODS PER WEEK			TOTAL CONTACT	CREDITS
110.	COBE	COURSE TILE	GORI	L	T	P	PERIODS	
1	22MT5301	Database Management System	PEC	-3	0	0	3	3
2	22MT5302	Data Science	PEC	3	0	0	3	3
3	22MT5303	Data Visualization	PEC	3	0	0	3	3
4	22MT6301	Cyber Safety	PEC	, 3	0	0	3	3
5	22MT6302	AI for Mechatronics	PEC	3	0	0	3	3
6	22MT7301	Optimization Techniques	PEC	3	0	0	3	3

Details of Vertical II: Mechanical Engineering

S. NO.	COURSE	COURSE TITLE	CATE	PERIODS PER WEEK			TOTAL CONTACT	CREDITS
	CODE	COUNSE TITLE	GOKI	L	T	P	PERIODS	
1	22MT5304	Composite Materials	PEC	3	0	0	3	3
2	22MT5305	Product Design and Development	PEC	3	0	0	3	3
3	22MT5306	Applied Thermodynamics	PEC	3	0	0	3	3
4	22MT6303	Non-Destructive Testing	PEC	3	0	0	3	3
5	22MT6304	Diagnostics Techniques	PEC	3	0	0	3	3
6	22MT7302	Machineries in Agriculture	PEC	3	0	0	3	3

Details of Vertical III: Management Studies

S. NO.	COURSE	COURSE TITLE	CATE GORY	PER WEEK			TOTAL CONTACT	CREDITS
		COUNCE TITLE	GORI	L	T	P	PERIODS	
1	22MT5307	Principles of Management	PEC	3	0	0	3	3
2	22MT5308	Disaster Management	PEC	3	0	0	3	3
3	22MT5309	Supply Chain Management	PEC	3	0	0	3	3
4	22WT6305	Economics and Cost Management	PEC	3	0	0	3	3

 5	22MT6306	Digital Management	PEC	3	0	0	3	3
6	22MT7303	Marketing Management	PEC	3	0	0	3	3

Details of Vertical IV: Manufacturing Process

S. NO.	COURSE		CATE GORY	PERIODS PER WEEK			TOTAL CONTACT	CREDITS	
NO.	CODE	COURSE TITLE	GORT	L	T	P	PERIODS		
personal desiration and the second	22MT5310	Non-Traditional Machining Techniques	PEC	3	0	0	3	3	
2	22MT5311	Computer Integrated Manufacturing	PEC	3	0	0	3	3	
3	22MT5312	Flexible Manufacturing System	PEC	3	0	0	3	3	
4	22MT6307	Micro Manufacturing	PEC	3	0	0	3	3	
5	22MT6308	Industrial 4.0	PEC	3	0	0	3	3	
6	22MT7304	Rapid Prototyping	PEC	3	0	0	. 3	3	

Details of Vertical V: Vehicle Technology

S. NO.	COURSE	COURSE TITLE	CATE	PEŔIODS PER WEEK			TOTAL CONTACT	CREDITS
NO.	CODE	COURSE TITLE	GOKI	L	T	P	PERIODS	
1	22MT5313	Automobile System	PEC	3	0	, 0	3	3
2	22MT5314	Automotive Electronics	PEC	3	0	0	3	3
3	22MT5315	Electrical Vehicles	PEC	3	Ó	0	3	3
4	22MT6309	Hybrid Vehicles	PEC	3	0	0	3	3
5	22MT6310	Unmanned Aerial Vehicles	PEC	3	0	0	3	3
6	22MT7305	Modern Vehicles Technology	PEC	3	0	0	3	3

Details of Vertical VI: Robotics and Automation

S. NO.	COURSE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT	CREDITS
	CODE	COURSE TITLE	GOKI	L	Τ.	P	PERIODS	
1	22MT5316	Mobile Robotics	PEC	3	0	0	3	3
2	22MT5317	Soft Robotics	PEC	3	0	0	3	3
3	22MT5318	Micro Robotics	PEC	3	0	0	. 3	3
4	22MT6311	Textile Automation	PEC	3	0	0	3	- 3
5	22MT6312	Factory Automation	PEC	3	0	0	3	. 3
6.	22MT7306	Automatic System	PEC	3	0	0	3	3

Enrollment for B.E. / B. TECH. (HONOURS) / Minor Degree (optional)

A student can also optionally register for additional courses (18 credits) and become eligible for the award of B.E. B. Tech. (Honours) or Minor Degree. For B.E. B. Tech. (Honours), a student shall register for the additional courses (18 credits) from semester V onwards. These courses shall be from the same vertical or a combination of different verticals of the same programme of study only. For minor degree, a student shall register for the additional courses (18 credits) from semester V onwards. All these courses have to be in a particular vertical from any one of the other programmes.

Clause 4.10 of Regulation 2022 is applicable for the Enrolment of B.E. / B. TECH. (HONOURS) / Minor Degree (Optional).

VERTICALS FOR MINOR DEGREE

• Heads are requested to provide one vertical from their program to offer for other program students to register for additional courses (18 Credits) to become eligible for the B.E./B.Tech. Minor Degree.

Note: Each programme should provide verticals for minor degree

S. NO.	COURSE	COURSE COURSE TITLE GORY			CRIO R WE		TOTAL CONTACT	CREDITS
NO.	CODE	COURSE HILE	GOKI	L	Т	P	PERIODS	1
1	22MT5601	Sem 5: Basics of Mechatronics System	MDC	3	. 0	0	3	3
2	22MT6601	Sem 6: Sensors and Interfacing	MDC	3	0	0	3	3
3	22MT6602	Sem6: Hydraulics and Pneumatics	MDC	3	0.	0	3	3
4	22MT7601	Sem 7: PLC and SCADA	MDC	3	0	0	3	3
5	22MT7602	Sem 7: Industrial Robotics	MDC	3	0	0	3	3
6	22MT8601	Sem 8: Design of Mechatronics System	MDC	3	0	0	3	3

^{*}MDC – Minor Degree Course

In addition to the above the following additional courses for Minor Degree can also be given to the student's common to all the branches.

Vertical I Fintech and Block Chain	Vertical II Entrepreneurship	Vertical III Environment and Sustainability
Finteen and block Chain	Entrepreneursmp	Environment and Sustamability
Financial Management	Foundations of Entrepreneurship	Sustainable infrastructure Development
Fundamentals of Investment	Introduction to Business Venture	Sustainable Agriculture and Environmental Management
Banking, Financial Services and Insurance	Team Building & Leadership Management for Business	Sustainable Bio Materials
Introduction to Blockchain and its Applications	Creativity & Innovation in Entrepreneurship	Materials for Energy Sustainability
Fintech Personal Finance and Payments	Principles of Marketing Management for Business	Green Technology
Introduction to Fintech	Human Resource Management for Entrepreneurs	Environmental Quality Monitoring and Analysis
	Financing New Business Ventures	·

VERTICALS FOR HONOURS DEGREE

Vertical I Industrial Automation	Vertical II Medical Mechatronics	Vertical III Applied Robotics
22MT5203	22MT5204	22MT5205
Concepts of Machines and Mechanisms	Robotics in Medicine	Robots and Systems in Smart Manufacturing
22MT6202 Drives and Actuators for Automation	- 22MT6204 Brain Computer Interface and its Applications	22MT6206 Medical Robotics
22MT6203	22MT6205	22MT6207
Power Electronics	Digital Image Processing	Agricultural Robotics and Automation
22MT7203	22MT7205	22MT7207
Advanced PLC	Radiological Equipment	Collaborative Robotics
22MT7204	22MT7206	22MT7208
Distributed Control System	Biomaterials	Robot Operating Systems
22MT8201	22MT8202	22MT8203
HMI & SCADA	Bionics	Humanoid Robotics

B.E (Hons) Mechatronics Engineering Specialization in Industrial Automation

S.No.	Course	Course Title	Category	F	Perio W	ds po eek	er	ТСР	CIA	ESE	Total
	Code			L	T	P	C				
1	22MT5203	Sem 5: Concepts of Machines and Mechanisms	PC	3	0	0	3	3	40	60	100
2	22MT6202	Sem 6: Drives and Actuators for Automation	PC	3	0	0	3	3	40	60	100
3	22MT6203	Sem 6: Power Electronics	PC	3	0	0	3	3.	40	60	100
4	22MT7203	Sem 7: Advanced PLC	PC	3	0	0	-3	3	40	60	100
5	22MT7204	Sem 7: Distributed Control System	PC	3	0	0	3	3	40	60	100
6	22MT8201	Sem 8: HMI & SCADA	PC	3	0	0	3	3	40	60	100

B.E. (Hons) Mechatronics Engineering Specialization in Medical Mechatronics

S.No.	Course	Course Title	Category	F	Perio W	ds p	er	ТСР	CIA	ESE	Total
	Code			L	T	P	C		-		·
1.	22MT5204	Sem 5: Robotics in Medicine	PC	3	0	0	3	3	40	60	100
2.	22MT6204	Sem 6: Brain Computer Interface and its Applications	PC	3	0	0	3	3	40	60	100
3.	22MT6205	Sem 6: Digital Image Processing	PC	3	0	0	3	3	40	60	100
4.	22MT7205	Sem 7: Radiological Equipments	PC	3	0	0	3	3	40	60	100
5.	22MT7206	Sem 7: Biomaterials	OF MIC COUNT	3	0	0	3	3	40	60	100
6.	22MT8202	Sem 8: Bionics	1	3	0	0	3	3	40	60	100

B.E (Hons) Mechatronics Engineering with Specialization in Applied Robotics

S.No.	Course Code	Course Title	Category	I	Perio W	ds p eek	er	ТСР	CIA	ESE	Total
,	Code			L	T	P	C				
1.	22MT5205	Sem 5: Robots and Systems in Smart Manufacturing	PC	3	0	0	3	3	40	60	100
2.	22MT6206	Sem 6: Medical Robotics	PC	3	0	0	3	3	40	60	100
3	22MT6207	Sem 6: Agricultural Robotics and Automation	PC	3	0	0	3	3	40	60	. 100
4.	22MT7207	Sem 7: Collaborative Robotics	PC -	3	0	0	3	3	40	60	100
5.	22MT7208	Sem 7: Robot Operating Systems	PC	3	0	0	3	3	40	60	100
6.	22MT8203	Sem 8: Humanoid Robotics	PC	3	0	0	3	3	40	60	100

Note: Each programme should provide verticals for Honours degree

SEMESTER-WISE CREDIT DISTRIBUTION

			B.E.	/ B.TEC	H. PRO	GRAM	MES			
S.No.	Course			C	redits p	er Semes	ster			Total
5.140.	Area	I	II	Ш	IV	V	VI	VII	VIII	Credits
1	HSC	3	3	-	2	-	3	-	-	11
2	BSC	7	9	4	-	-	-	-	-	20
3	ESC	6	4	5	-	-	-	-	-	. 15
4	PCC	-	3	13	20	12	7	9	-	64
5	PEC	-	-	_	-	9	9	-	-	18
6	OEC	-	-	-	-	-	3	9	-	12
7	EEC.	3	3	3	1	1	2	2	10	25
8	MCC		1	/	1					
	Total	19	22	25	23	22	24	20	10	165

CREDIT DISTRIBUTION R2022

Semester	I	II	Ш	IV	V	VI	VII	VIII	Total
Credits	18	23	25	23	•22	24	20	10	165

Chairman - Bos

Chairman - Bos

CHARGO COUNCIL HOER OF THE PARTY OF THE PART

Dean Academics
Dean (Academics)
HiCET

Principal

Programme	·	Course Code	Name of the Course	L	, T	P	C	
B.E./B.Tec	h	22MA1101	MATRICES AND CALCULUS (Common to all Branches)	3	1	0	4	
Course Objectiv	ve .	Impart the know Analyseanddiscu Evaluate the mu	aracteristic polynomial of a matrix and use eledge of sequences and series. assthemaximaandminimaofthefunctionsofs ltiple integrals and apply in solving problet ferential operator for vector function and the	everalvariabl ms.	es.	ring		
Uni			Description				ructional Hours	
t I	Matric	Δ¢				•	Tours	
1	Eigen v -Cayley	alues and Eigen	vectors – Properties of Eigen values and Eigen (excluding proof) - Reduction of a disformation.	igen vectors (quadratic fori	without pro	of) cal	12 ,	
II	Single Rolle's and Ma	Variate Calculu Theorem–Lagra claurin's Series.	s nge's Mean Value Theorem-Maxima and N	Minima-Tayl	or's		12	
III		ons of Several V derivatives-Total	ariables derivative, Jacobian, Maxima, minima and	d saddle poin	ts; Method o	of	12	
IV	Integral Double (exclud (Sphere Ellipsoi	ge multipliers Il Calculus integrals in Cart ing surface area) c, id, Tetrahedron)	esian coordinates—Area enclosed by plane – Triple integrals in Cartesian co-ordinates using Cartesian co-ordinates.	curves			12	
$\mathbf{v} \sim \mathbf{V}$	Gradier	Calculus nt, divergence an ent only) for cub	d curl; Green's theorem, Stoke's and Gausses only.	s divergence t	heorem		12	
				Total Instru	ctional Hou	ırs	60	
Course Outcome	ir C C w C	CO1: Compute Einto canonical form CO2: Apply the coco3: Compute parith two variables CO4: Evaluate mu	oncept of differentiation to identify the martial derivatives of function of several variety	ximum and mables and wri	ninimum val te Taylor's : ne.	ues of c	urve.	

TEXTBOOKS:

T1:G.B.ThomasandR.L.Finney, "CalculusandAnalyticalGeometry", 9th EditionAddisonWesleyPublishing Company, 2016.

T2: Erwin Kreyszig, "AdvancedEngineeringMathematics", John Wiley & Sons, 2019.

T3: K.P. Uma and S. Padma, "Engineering Mathematics I (Matrices and Calculus)", Pears on Ltd, 2022.

REFERENCEBOOKS:

R1-JerroldE.Marsden, Anthony Tromba, "Vector Calculus", W.H. Freeman, 2003

R2-StraussM.J,G.L.Brad leyand K.J.Smith, "Multivariablecalculus", PrenticeHall, 2002.

R3-VeerarajanT, "Engineering Mathematics", McGraw Hill Education(India)PvtLtd, NewDelhi, 2016.

PO& PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	3	3	-	-	-	-	-	-	2	2	1
CO2	3	3	3	2	2	-	-	-	-	-	-	2	2	2
CO3	3	3	3	2	3	-	-	-	-	-	-	2	2	2
CO4	3	3	3	3	3	-	-	-	-	-	-	2	2	3
CO5	3	3	3	3	3	-	_	-	-	-	-	2	1	2
AVG	3	3	3	2.6	2.8	-	-	-	-	-	-	2	1.8	2

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Dean (Academics)

HiCET

Prog	gramme	Course Cod		L	T	P	C
B.E./B.	Tech	22ME12	01 ENGINEERING DRAWING (AGRI, BME. (CHEM,,AERO, AUTO, CIVIL.MECH. MECT,FT,EEE)	1	4	0	3
		The lear	rner should be able				
		1. To gain	the knowledge of Engineer's language of expressing	g complete	e details al	bout objec	ts
(ourse	and cons	struction of conics and special curves.			,	
	bjective	To learn	about the orthogonal projections of straight lines an	d planes.			
0.	ojecuve	To acqu	ire the knowledge of projections of simple solid obje	ects in pla	in and elev	ation.	
		To learn	about the projection of sections of solids and develo	opment of	surtaces.		
		To study	the isometric projections of different objects.				
Unit			Description			Instructi	
						Hour	5
	PLANE	CURVES	to the state of th	larrant on	d		
	Importar	ice of engineer	ing drawing; drafting instruments; drawing sheets –	nayout an	u na	1.	1
I	folding	; Lettering and	dimensioning, BIS standards, scales. Geometrical co	IISH UCHOI	115, h.,	1.	á.
•	Engineer	ring Curves Co	nic sections –Construction of ellipse, parabolaand h	yperooia i	rowing		
			onstruction of cycloids and involutes of square and c	IICIE – DI	awing		
	of tanger	nts and normal	to the above curves.				
	PROJE	CTIONS OF I	POINTS, LINES AND PLANE SURFACES	of ctraight	lines		
	Introduc	ction to Orthog	raphic projections- Projection of points. Projection of	ne by rote	ntina	1.	2
П	inclined	to both the plan	nes, Determination of true lengths and true inclination	to both t	ung he	1.	_
	line meti	nod. Projection	of planes (polygonal and circular surfaces) inclined	to both ti	iiC		
			et method (First angle projections only).				
	PROJE	CTIONS OF S	lids like prisms, pyramids, cylinder and cone when t	he avic ic		1	2
111	Projection	on of simple so	nds like prisms, pyramids, cyrinder and cone when t	iic axis is			
	perpendi	icular and incli	ned to one plane by rotating object method.				
	SECTION	ON OF SOLID	S AND DEVELOPMENT OF SURFACES lids with their axis in vertical position when the cutt	tina nlane	ic		
	Sectioni	ng of simple so	incipal planes and perpendicular to the other – Obta	ining plane	shane	1	2
IV	inclined	toone of the pr	nt of lateral surfaces of simple and sectioned solids –	nnig aac - Prisms	Shape		-
	of sectio	n. Developmer	cone. Development of lateral surfaces of truncated s	eolids			
	pyramid	s, cynnder and	RTHOGRAPHIC PROJECTIONS	ionas.			
	ISOME	IRIC AND O	ojections simple and truncated solids such as - Prism	is nyram	ids		
* 7	Isomeur	c views and pro	bination of two solid objects in simple vertical posit	ions Free	hand	1	2
V	Cynnae	as, cones- com	iews from a pictorial drawing. Basics of drafting usi	no Auto(`AD		
	sketenin		iews from a pretorial drawing. Dasies of draiting dis				
	Sonware	•	Total II	struction	al Hours	6	60
		At the e	nd of the course, the learner will be able to				

At the end of the course, the learner will be able to

CO1: Understand and interpret the engineering drawings in order to visualize the objects and

draw the conics and special curves.

Course Outcome CO2: Draw the orthogonal projections of straight lines and planes.

CO3: Interpret the projections of simple solid objects in plan and elevation.

CO4: Draw the projections of section of solids and development of surfaces of solids.

CO5: Draw the isometric projections and the perspective views of different objects.

TEXT BOOK:

T1. K. Venugopal, V. Prabu Raja, "Engineering Drawing, AutoCAD, Building Drawings", 5thedition New Age International

Publishers, New Delhi 2016.

T2. K.V.Natarajan, "A textbook of Engineering Graphics", Dhanlaksmi Publishers, Chennai 2016.

REFERENCES:

R1. BasantAgrawal and C.M.Agrawal, "Engineering Drawing", Tata McGraw Hill Publishing company Limited, New Delhi, 2013.

R2. N.S. Parthasarathy, Vela Murali, "Engineering Drawing", Oxford University PRESS, India 2015.

CHAIRMAN, BOARD OF STUDIES

Chairman - Bos

MCT - HiCET



CO/PO		PO2	PO3	PO4	PO5		PO7	PO8	PO9		PO11	PO12	PSO-1	PSO-2
CO1	3	3	3	2	2	-	-	-	-	-	_	2	1	1
CO2	3	3	3	2	2	-	-	-	-	-	-	3	2	2
CO3	3	3	3	2	2	-	-	-		-		3	3	3
CO4	3	3	3	2	2	-	-	-	-	-	-	3	1	1
CO5	3	3	3	2	2	-	-	-	-	-	-	3	2	2
AVG	3	3	3	2	2	-	-	-	-	-	-	2.8	1.8	1.8

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS

MCT - HiCET



DEAN ACADEMICS

B.E./I	3.Tech 22HE	1151	ENGLISH FOR ENGINEERS	L2	T0	P2	C3
	I		(Common to all Branches)	1.2		1 2	C.J
	The stud	ent should be	20070 1300 2 m 3 m 3 m 3 m				
	irse 1.	To improve	e the communicative profic	iency of learn	ers.		
Obje	ective 2.	To help lear	mers use language effective	elv in professio	onal writing.		
	3.	•	e the skills of maintaining t		e e	rion	
	4.		e the professional life skills		,		
	5.		fficial communication etiqu				
Uni		70 mpart o	eta eviimenteativii ette	actic.		Inst	tructional
t	Description						Hours
1	Writing: proce environment. Pra	ess description actical Compo	s of Sentences, Functional n, Writing Checklist. Vo onent: Listening-Watchin ntroduction, formal & semi-	cabulary — g short videos	words on and answer		7÷2
II	Technical Writin Language Proficeonveying posit emoticons, abbreentertainment. It talksSpeaking- Skimming - Scar	g: ciency: Tense ive and nega eviations& act Practical Co Narrating a sl nning – Readir	s. Adjectives and adverbs. tive news), Formal and ronyms), reading comprehemponent: Listening-Control story or an event hang; Scientific Texts – Liters ositions, phrasal verbs. V	Writing: For informal emacension. Vocal mprehensions ppened in the try Texts.	mal letters (lett ail writing (usi bulary– words based on Tl eir life Reading	ing on ED g -	7+2
III	Congratulating, tools. Practical Constaminute Read to identify point of	warning and omponent:Listing-Reading of view and pe	apologizing letters, cloze stening-Listen to songs and feature articles (from news rrspective (opinion pieces, o	test. Vocabutest. I answer the quapers and madeditorials etc.)	ılary – words uestionsSpeakii igazines) -Readi	on 1g- ing	5+4
IV	agenda &minutes Practical Composhows Speaking	s, writing an o onent: Listeni g-Presentation	ect verb concord, Prefixes event report. Vocabulary- ing- Comprehensions based on a general topic	words on end on Talk of owith ppt. R	gineering proce rators or intervi- eading- Readi	ess.	5+4
V	Language Profice report (proposal & material Practical Geo/Discovery & control of the control of	ciency: Moda & progress) ,se I Component channel video	or Good Comprehension - al Auxiliaries, Active & p equencing of sentences Voi : Listening- Listening- tos Speaking- Preparing avelogues, technical blogs.	assive voice, cabulary —woi Comprehensio	Writing: Projects on engineering based on N	ng lat	6+3
				Total In	structional Hou	ırs	45
	After comple	tion of the co	urse the learner will be abl	e	mark.		

Course Outcome

CO1:Tocommunicateinaprofessional forum

CO2: To speak or write a content in the proficient language

CO3: To maintain and use appropriate one of the communication.

CO4:To read ,write and present in a professional way.

CO5:To follow the etiquettes in formal communication.

TEXTBOOKS:

T1- Norman Whitby, "Business Benchmark-Pre-intermediate to Intermediate", Cambridge University Press, 2016.T2-

Raymond Murphy, "Essential English Grammar", Cambridge UniversityPress,2019.

REFERENCEBOOKS:

R1- Meenakshi Raman and Sangeetha Sharma. "Technical Communication- Principles and Practice", Oxford University Press, 2009.

R2-RaymondMurphy, "English GrammarinUse"-4theditionCambridgeUniversityPress,2004.

R3-KamaleshSadanan"AFoundationCoursefortheSpeakersofTamil-Part-I&II". Orient Blackswan, 2010.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEANACADEMICS

PO& PSO		1	PO3			PO6	PO7	PO8				PO12	PSO1	PSO2
CO1	2					1	2	2	2	3	1	1	1	2
CO2	2	1			1	1	1	2	2	3		2		2
CO3	2	1			1	1	2	3	3	3		1	1 .	2
CO4	2	1				1	2	2	2	3	1	1		
CO5	2					1	1	2	3	3		1	1	2
Avg	2	1	-	-	1	1	1.6	2.2	2.4	3	1	1.2	1	2

Chairman, Board of Studies
Chairman - BoS
MCT - HiCET



DEAN ACADEMICS

Programme	Course Code	Name of the Course	L	ľ	1)	C
BE/B.Tech	22PH1151	PHYSICS FOR NON- CIRCUIT ENGINEERING 1-SEM (AFROAUTO.AGRICHEM.CIVIL.MECH.MCT&FT)	2	()	2	3
Course Objective	1.Gain knowled and applications 2. Enhance his 3.Understand th 4. Gain knowled	fundamental knowledge about properties of matter e concept of Wave optics lge about Quantum Physics.				
Unit	5. Acquire rund	amental knowledge of thermal physics which is related to the Description	z engn	neerm	8 bros	Instructional
Cint	I ACED AND	•				Hours
I	Spontaneous em Applications – propagation of li	FIBRE OPTICS assion and stimulated emission –Type of lasers – Nd:YA Holography – Construction and reconstruction of image ght through optical fibers – Derivation of numerical aperturation of optical fibers (based on refractive index and modes in).	s. Prine and a	nciple accep	and tance	
		of Wavelength and particle size using Laser				
П	Elasticity – Hoo Deteremination and experiment. Determination	ke's law - Poisson's ratio - Bending moment - Depression of Young's modulus of the material of the beam by Uniforn Twisting couple - torsion pendulum: theory and experiment of Young's modulus by uniform bending method				6
III	WAVE OPTIC Interference of I Michelson inter Diffraction grati Determination	of Rigidity modulus – Torsion pendulum S ight – air wedge –Thickness of thin paper -Testing of thick ferometer. Diffraction of light –Fraunhofer diffraction ng – Rayleigh's criterion of resolution power - resolving powof wavelength of mercury spectrum – spectrometer grating of thickness of a thin wire – Air wedge method	at sin ver of	gle s	lit –	6
IV	duality -concept	HYSICS ation –Compton effect: theory and experimental verification of wave function and its physical significance – Schrödinger and time dependent equations – particle in a one-dimension	's wav	e equ	ation	6
V	- Lee's disc meth	HYSICS energy –thermal conduction, convection and radiation – thermod: theory and experiment - conduction through compound rations: solar water heaters.				6
		Total Instructional Hours Total Lab Instructional Hours n of the course the learner will be able to d the advanced technology of LASER and optical communic	ration	in the	tield	
Course Outcome	of Engineering CO2: Illustrate the CO3: Discuss the CO4: Understand CO5: Develop the	the fundamental properties of matter e Oscillatory motions of particles d the advanced technology of Quantum Physics in the field of the technology of thermal physics in engineering field				
TEXT BOOK T1 - Rajen		hysics, Tata McGraw Hill Publishing Company Limited, Ne	w Del	hi, 20	17.	
		L., Engineering Physics, 8th edition, Dhanpat Rai Publication				Delhi, 2015.

REFERENCE BOOKS:

R1 - M.N Avadhanulu and PG Kshirsagar "A Text Book of Engineering physics" S. Chand and Company ltd., New

R2 - Dr. G. Senthilkumar "Engineering Physics - I" VRB publishers Pvt Ltd., 2021

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN CADEMICS

PO& PSO	PO1	PO2	РО3	PO4	PO5	PO6	PO7	РО8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	3	1	1	-	1		2	3 -	3	2
CO2	3	3	2	2	1	1	1	-	1	-	2	2	3	1
CO3	3	3	2	2	2	1	1	-	1	-	1	2	2	2
CO4	3	2	3	1	3	1	1	-	1	-	1	2	2	1
CO5	3	2	3	1	2	1	1	-	1	-	2	2	2	1
Avg	3	2.6	2.6	1.6	2.2	1	1	-]	-	1.6	2.2	2.4	1.4

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEANACADEMICS

Prog	ramme		Course Code	Name of the Course	1.	Τ,	P	C
B.E.	/B.Tech		22IT1151	PYTHON PROGRAMMING AND PRACTICES AGRI, CHEM, FT, AERO, AUTO, CIVILMECH, MECT, ECE, BME)	2	0	2	3
			The learner	should be able				
	ourse jective	1. 2. 3. 4. 5.	To read and v To develop P To use Pytho	basics of algorithmic problem solving write simple Python programs ython programs with conditionals and loops and to define n data structures — lists, tuples, dictionaries output with files in Python	: Pytho	n func	tions a	nd call them
Unit			•	Description			Ins	tructional
	AL COR	ІТН	MIC PROBL	EM SOLVING				Hours
				of algorithms (statements, state, control flow, functions	s) not	ation		5+4
				ogramming language), algorithmic problem solving, simpl				5.4
I	-		_	teration, recursion).		-		
				find the Greatest Common Divisor (GCD)oftwo	num	bers.		
			-	orm Matrix addition.		,		
				ONTROL FLOW				
				d precedence of operators, expressions, statements,	comn	ents;		5+4
				es and operators, conditional (if), alternative (if -else				
11	condition	al (i	f –elif-else); Ite	eration: state, while, for, break, continue, pass;				
	Simple a	lgor	ithms and pro	grams: Area of the circle, check the given year is Le	ар уе	ar or		
	not, Fact	toria	l of a Number	•				
	FUNCTI	ONS	S, STRINGS					
	Functions	s, pa	rameters and a	rguments: Fruitful functions: return values, local and glo	obal s	cope,		5+4
Ш	function	comp	position, recurs	sive functions. Strings: string slices, immutability, string	g func	tions		
***	and meth	ods,	string module.					
		_	_	orm Linear Search, Selection sort, Sum of all element	s in a	List,		
	Pattern l	-						
			LES, DICTIO					5+4
				slices, list methods, list loop, mutability, aliasing, clo	_			
IV	-			le assignment, tuple as return value; Dictionaries:	opera	tions		
			-	rocessing - list comprehension.				
		-	0	Manipulation, Finding Maximum in a List, String pr	ocessi	ng.		
			OULES, PACK		1			
\mathbf{V}				iles, reading and writing files, errors and exceptions	, nan	dling		9
			odules, packag					
	mustrati	ve p	rograms: Kea	ding writing in a file, word count, Handling Exception Total Instructi		Loure		45
		Λ+	the and of the		OHAL I	iours		43
				course, the learner will be able to gorithmic solutions to simple computational problems				
			_	e, execute by hand simple Python programs				
Co	ourse			imple Python programs for solving problems and Decom	nose s	Pytho	n nrom	ram into
Ou	tcome		nctions	imple 1 Julion programs for solving problems and Decom	pose a	тушо.	n prog	am mo
				compound data using Python lists, tuples, dictionaries				
			•	write data from/to files in Python Programs.				
TEXT	BOOKS:			The same of the sa				
		sum	and Fred I Dra	ake Ir. An Introduction to Python – Revised and undated for	c Pytho	n 362	Shrof	f Publishers

T1: Guido van Rossum and Fred L. Drake Jr, An Introduction to Python – Revised and updated for Python 3.6.2, Shroff Publishers, First

T2:S. Annadurai, S.Shankar, I.Jasmine, M.Revathi, Fundamentals of Python Programming, Mc-Graw Hill Education (India) Private Ltd, 2019.

Chairman, Board of Stypies
Chairman
MCT - HiCET



DEANACADEMICS Dean (Academics) HICET

REFERENCE BOOKS:

R1:CharlesDierbach. —Introduction to Computer Science using Python: A Computational Problem- Solving Focus, Wiley India Edition.2013.

R2:Timothy A. Budd. —Exploring Pythonl, Mc-Graw Hill Education (India) Private Ltd., 2015

R3:Robert Sedgewick, Kevin Wayne. Robert Dondero, —Introduction to Programming in Python: An Inter-disciplinary Approach. Pearson

India Education Services Pvt. Ltd., 2016

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
CO1	3	3	2	2	3	1						2	1	2
CO2	3	3	2	2	3	1				-		2	1	2
CO3	3	3	2	2	3	1		To the state of th				2	1	2
CO4	3	3	2	2	3	1						2	1	2
CO5	3	3	2	2	3	1						2	1	2
AVG	3	3	2	2	3	1	-	-	-	-	-	2	1	2

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HiCET



rogramme	Course Code	Name of the Course	L	T	P	С
B.E./B.Tech	22HE1072	ENTREPRENEURSHIP & INNOVATION	1	0	0	1
	The student s	(Common for all Branches) hould be made				
Course Objectives	 To rec To pla To ac 	uire the knowledge and skills needed to manage the decognize and evaluate potential opportunities to monetion specific and detailed method to exploit these opporquire the resources necessary to implement these planake students understand organizational performance a	ize these tunities. s.	innovatio		
Module		Description				
1	Entrepreneuria	l Thinking				
. 2	Innovation Ma	nagement				
3	Design Thinkin	g				
4	Opportunity Sp	ootting / Opportunity Evaluation				
5	Industry and M	larket Research				
.6		itegy and Business Models		* .		
. 7	Financial Forec	rasting				
8	Business Plans/	Business Model Canvas				
9	Entrepreneuria	l Finance				
10	Pitching to Rese	ources Providers / Pitch Deck				
11	Negotiating Dea	als				
12	New Venture C	reation				
13	Lean Start-ups					
14	Entrepreneuria	l Ecosystem				
15	Velocity Ventur	e				
		TOTAL INSTRU	JCTION	NAL HOU	RS	15
Course Outcome	CO1: Understa aspects. CO2: Understa CO3:Remembe CO4:Assess the attractiveness	e course, the learner will be able to ndthenatureofbusinessopportunities, resources, and indeed and the processes by which innovation is fostered, man reffectively and efficiently the potential of new busi market potential for a new venture, including custon	naged, ar ness opp ner need	nd commer portunities. , competit	rcialized. fors, and i	
		business model for a new venture, including revenue.	Margins	s, operation	18,	
	Working capital,	and investment				

TEXTBOOKS

T1: AryaKumar "Entrepreneurship—Creating and leading an Entrepreneurial Organization", Pearson, Second Edition (2012). T2: Emrah Yayici "Design Thinking Methodology", Artbiztech, First Edition (2016).

REFERENCEBOOKS

R1: Christopher Golis "Enterprise & Venture Capital", Allen &Unwin Publication, Fourth Edition (2007).

 $R2: Thomas Lock Wood \& Edger Papke ``Innovation by Design", Career\ Press. com, Second Edition (2017).$

R3: Jonathan Wilson "Essentials of Business Research", Sage Publication, FirstEdition(2010).

WEBRESOURCES

 $W1: \underline{https://blof.forgeforward.in/tagged/startup-lessons}$

W2: https://blof.forgeforward.in/tagged/entrepreurship

W3: https://blof.forgeforward.in/tagged/minimum-viable-product

W4: https://blof.forgeforward.in/tagged/minimum-viable-product

W5: https://blof.forgeforward.in/tagged/innovation

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Prograi	INTRODUCTION TO SOFT SKILLS 1. To develop and nurture the soft skills of the students through instruction, k demonstration and practice. 2. To enhance the students ability to deal with numerical and quantitative skills 3. To identify the core skills associated with critical thinking.		Course Title	L	T	P	C
BE/BTI	ЕСН	22HE1073	INTRODUCTION TO SOFT SKILLS	0	0	0	1
Cour Objecti	se ves: 2.	To enhance the are identify the control of the cont	nurture the soft skills of the students through instruction, knowled and practice. Students ability to deal with numerical and quantitative skills.			ition	
Unit			Description	Ins	truci Hou		ıl
1		on excellence Ospection, Skill	acquisition, consistent practice		2		
II S	Problem :	Solving - Critic	al Thinking- Lateral Thinking - Coding and Decoding – Man Out - Visual Reasoning - Sudoku puzzles - Attention		11		
HI a	Quantitati Addition and cube Multiplica ractions - Algebra a	roots - Vedic mation of 3 and hation of 5 and hation of 5 and hations functions	of bigger numbers - Square and square roots - Cubes aths techniques - Multiplication Shortcuts - igher digit numbers - Simplifications - Comparing and HCF and LCM - Divisibility tests shortcuts -		11		
IV F		nt Essentials Building - Impre	ssion Management		2		
$V \cap N$	Nouns and		erbs - Subject-Verb Agreement - Pronoun-Antecedent		4		
Course	CO1: CO2: CO3:	Students will ex	Total Instructional Hours alyze interpersonal communication skills. public speaking skills. emplify tautology, contradiction and contingency by logical thinking able to develop an appropriate integral form to solve all sorts of quantum contradiction.	ng. ıantit	30 ative		
Outcome:	CO4:	Students can pomeasurable achi Students will be	roduce a resume that describes their education, skills, experie evements with proper grammar, format and brevity. developed to acquire the ability to use English language with an enuse of grammar.				

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



DEAN ACADEMICS (S)
Dean (Academics)
HiCET

Programme Course code

22MC2093

Name of the course தமிழர்மரபு

L P S A 2 0 0 0

Unit

B.Tech

Description

Instructional Hours

அவகு | மொழி மற்றும் இலக்கியம் மொழிகள் - தமிழ் ஒரு செய்மொழி -இந்திய மொழிக் குடும்பங்கள் - திராவிட மொழிகள் - தமிழ் ஒரு செய்மொழி -தமிழ் செவ்விலக்கியங்கள் - சங்க இலக்கியத்தின் சமயச் சார்பற்ற தன்னம் - சங்க இலக்கியத்தில் பதிரதல் அறம் - திருக்குறளில் மேலாணமைக் கருத்திக்கள் -தமிழக் காப்பியங்கள் தவிழகத்தில் சமண பௌத்த சமயங்களின் தாக்கம் - பகதி இலக்கியம் ஆழ்வார்கள் மற்றும் நாயண்மார்கள் - சிற்றிலக்கியங்கள் - தமிழில் நவீன இலக்கியத்தின் வளர்கள் தவிழ் இலக்கிய வளர்ச்சியில் பார்தியார் மற்றும் பார்திதாசன் ஆகியோரின் பங்களிப்பு.

அல்கு B - மரபு - பான்ற ஒவியங்கள் முதல் நவீன ஒவியங்கள் வரை - சிற்பக் கலை - 3

நித்தல் நதல் நவீன திறபங்கள் வ**ரை -** ஐம்போன திலைகள் பழங்குடியினர் மற்றும் அவர்கள் தயாரிக்கும் **கைவினை**ப பொருடகள், பொய்மைகள் - தேர் செய்யல் கலை - சுடுமண் திறபங்கள் - நாட்டுப்பறத் தெய்வங்கள் -கும்ரிமுனையில் திருவள்ளுவர் **திவை - இசைக் கருவிகள் -** மிருதங்கம் பறை, வீணை, யாழ், நாத்ஸ்வரம் - த**மிழர்களின் சமூக** பொருளாதார வாழவில் கோவில்களின் பங்கு.

அவகு ## நாட்டுப்புறக் கலைகள் மற்றும் வீர விளையாட்டுகள் தெருக்கூதது, கரகாட்டம், வீல்ஓப்பாட்டு, கணியான கூத்த ஒயிலாட்டம், தோலபாவைக் கூத்து, சிவம்பாட்டம், வளரி, புலியாட்டம், தமிழர்களின் விளையாட்டுகள்.

அலகு IV தமிழர்களின் இனைக் கோட்பாடுகள் தமிழகத்தின் தாவரங்களும், விலங்குகளும் - தொல்காப்பியம் மற்றும் சங்க இலக்கியத்தில் அகம் மற்றும் புறக் கோட்பாடுகள் - தமிழர்கள் போற்றிய அறுக்கோட்பாடு - சங்ககாலத்தில் தமிழகத்தில் எழுத்தறிவும் கல்வியம் - சங்ககால நகரங்களும் துறை முகங்களும் - சங்ககாலத்தில் ஏற்றுமதி மற்றும் திறக்குமதி -கடல்கடந்த நாடுகளில் சோழர்களின் வெற்றி

அலகு V இந்திய தேசிய இயக்கம் மற்றும் இந்திய பண்பாட்டிற்குத் தமிழர்களின் பங்களிப்பு

தம்புகளை பங்களப்பு இந்திய விடுகளைப்போரில் தமிழர்களின் பங்கு - இந்தியாவின் பிறப்பகுதிகளில் தமிழப் பண்பாட்டின் தாக்கம் - சுயமரியாதை இயக்கம் - இந்திய மருகத்வத்தில், சித்த மருத்துவத்தின், பங்கு - கல்வெட்டுகள், கையெழுத்துப்படிகள் - தமிழப் புத்தகங்களின் அச்ச வரலாமு.

TEXT-CUM-REFERENCE BOOKS

- தமிழக வரவாறு மக்களும் பணபாடும் கே.கே. பிளளை (வெளியீடு: தமிழ்நாடு பாடதால் மற்றும் கல்வியியல் பணிகள் கழகம்).
- கணினித் தமிழ் முனைவர் இல சுந்தரம். (விகடன் பிரசுரம்).
 கீழடி வைகை நூக்கரையில் சங்ககால நகர நாகரிகம் (தொல்லியல் துறை வெளியீடு)
- பொருரை ஆற்றங்கரை நாகரிகம் (தொவ்வியல் துறை வெளியீடு)
- Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL (in print)
 Social Life of the Tamils The Classical Period (Dr.S.Singaravelu) (Published by: international institute of Tamil Studies.
- Historical Heritage of the Tamils (Dr.S.V.Subatamanian, Dr.K.D. Thirunavukkarasu) (Published by: International Institute of Tamil Studies).
- The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies.)
- Keeladi 'Sangam City Civilization on the banks of river Vaigai' (Jointly Published by: Department of Archaeology & Tamil Nadu Text Book and Educational Services Corporation, Tamil Nadu)
- Studies in the History of India with Special Reference to Tamil Nadu (Dr.K.K.Pillay) (Publishedby: The Author)
- Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Bookand Educational Services Corporation, Tamil Nadu)
- Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL) Reference Book.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS
Dean (Academics)
HiCET

TOTAL: 15 PERIODS

Program	me Course Code	Name of the Course	Ĺ	T	P	C
B.E./B.T	ech 22MC109 4	HERITAGE OF TAMIL	2	0	0	0
Course Objectiv	1. Int 2. Es 7e 3. To 4. Int	rner should be able to roduce students to the great History of Tamil liter tablish the heritage of various forms of Rock art a study and understand the various folk and Martia roduce students to Ancient Tamil concepts to und learn about the various influences or impacts of T	and Sculpture and arts of Tamil lerstand the rich	culture mess of Tamil		2.
Unit		Description				ctional urs
Lai Lit Lit Jai De	erature in Tamil- erature – Manag nism in Tamil an velopment of Mo	terature n India – Dravidian Languages – Tamil as a class Secular nature of Sangam Literature – Distributivement principles in Thirukural – Tamil epics and a Bakthi literature of Azhwars and Nayanmars – Sidern literature in Tamil – Contribution of Bharatlert Paintings to Modern Art – Sculpture	ve justice in Sa impacts of Bud Forms of mino	ngam dhism & poetry _	(6
He ten Ka Na	ro Stone to Mode nple car making - nyakumari, Maki dhaswaram - Ro	ern Sculpture – Bronze icons – Tribes and their hat – Massive Terracotta sculptures, Village deities, Tang of musical instruments – Mridangam, Parai, Yale of Temples in social and economic life of Tam	Thiruvalluvar st Zazh and		(5
The Sila	ambattam., Valai	attem, Villupattu. Kaniyan koothu, Oyilattam, Le i Tiger dance – Sports and Games of Tamils.	eather puppertry	,	(5
IV Flo Lite citi	erature – Aram c	Famils Famils – Aham and Puram Concept from Tholkaponcept of Tamils – Education and Literacy during angam age – Exporot and Import during Sangam	Sangam Age	- Ancient	•	<u> </u>
V Coroth	ntribution of Ta ntribution of Tan er parts of India	mils to Indian National Movement and Indian nils to Indian freedom struggle – The cultural influ- Self respect movement – Role of Siddha Medici ons & Manuscripts – Print History of Tamil book	uence of Tamiline in indigenor		(5
			Total Instruc	tional Hours	. 3	0
Course Outcome	CO1: Learn a CO2: Aware o CO3Apprecia CO4: Apprecia	the course, the learner will be able to about the works pertaining to Sangam age of our Heritage in art from Stone sculpture to Mocate the role of Folk arts in preserving, sustain ate the intricacies of Tamil literature that had exist and the contribution of Tamil Literature to Indian Contribution Indian Contribution Indian Contribution Indian Contribution Indian Con	ing and evolusted in the past.	ion of Tamil	culture.	

TEXTBOOKS:

T1: Social Life of Tamils (Dr.K.K.Pillay) A joint publication of TNTB & ESC and RMRL – (in print)

T2: Social Life of the Tamils - The Classical Period (Dr.S.Singaravelu) (Published by: International Institute of Tamil Studies.

T3: Historical Heritage of the Tamils (Dr.S.V.Subatamanian, Dr.K.D. Thirunavukkarasu)(Published by: International Institute of Tamil Studies).

REFERENCEBOOKS:

R1-The Contributions of the Tamils to Indian Culture (Dr.M.Valarmathi) (Published by: International Institute of Tamil Studies)

R2- Porunai Civilization (Jointly Published by: Department of Archaeology & Tamil Nadu Text Bookand Educational Services Corporation, Tamil Nadu)

R3-Journey of Civilization Indus to Vaigai (R.Balakrishnan) (Published by: RMRL) - Reference Book.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

	Programme	Course Code	Name of the Course L T	РС
	B,E./B.Tecl		UNIVERSAL HUMAN VALUES 2 0	0 0
	Course Objectives Unit	2. Tofacilitatethe towards happi existence. Suc towards value-	(COMMON TO ALL BRANCHES) I be made udents appreciate the essential complementarily between 'VALUES' and 'SKII piness and prosperity which are the core aspirations of all human beings, edevelopmentofaHolisticperspectiveamongstudentstowardslifeandprofession a ness and prosperity based on a correct understanding of the Human reality and ch a holistic perspective forms the basis of Universal Human Values and -based living in a natural way. lausible implications of such a Holistic understanding In terms of ethical huma utually fulfilling human behavior and mutually enriching interaction with Natural	LLS' to ensure as well as the rest of movement an conduct, are. Instructional
		Introduction to Valu		Hours
	I	Education)-Understar - Continuous Happine - Current Scenario -	Relationship and Physical Facility (Holistic Development and the Role of Inding Value Education - Self-exploration as the Process for Value Education ess and Prosperity – the Basic Human Aspirations - Happiness and Prosperity Method to Fulfill the Basic Human Aspirations man Being and Harmony in the Family	6
	II	Understanding Human between the Needs of	n being as the Co-existence of the Sell' and the Body - Distinguishing the Self and the Body - The Body as an Instrument of the Self - ony in the Self- Harmony of the Self with the Body - Programme to ensure ealth	6
	III	Harmony in the Fam Relationship'Trust' – Relationship'Respect' Understanding Harmo	tily – the Basic Unit of Human Interaction. Values in Human to Human the Foundational Value in Relationship Values in Human to Human – as the RightEvaluation only in the Society	6
	IV	among the Four Orc interacting units in al Holistic Perception of	ony in the Nature.Interconnectedness, self-regulation and Mutual Fulfillment ders of Nature- Understanding Existence as Co-existence of mutually Il pervasivespace Realizing Existence as Co-existence at All Levels The Harmony in Existence. Vision for the Universal Human Order	6
	, V ,	Natural Acceptance o Humanistic Education Professional Ethics Ho	folistic Understanding – a Look at Professional Ethics f Human Values Definitiveness of (Ethical) Human Conduct A Basis for h, Humanistic Constitution and Universal Human Order-Competence in holistic Technologies, Production Systems and Management Models-Typical for Transition towards Value-based Life and Profession	6
			Total Instructional Hours	30
	Course Outcome	CO1: To become more a CO2: To become more in Solutions.	, the learner will be able aware of holistic vision of life - themselves and their surroundings. responsible in life, in the Society and in handling problems with sustainable	
	(Socially responsib CO4: To able to apply w In handling proble	what have learnt to their own self in different day-to-day settings in real life an ems with sustainable solutions.	
	Reference R1.A Found 2 nd Revised R2.Teachers R Asthana, R3.JeevanV	Books: ation Course in Human Edition, Excel Books, I BandalforAFoundation GP Bagaria, 2 nd Revise idya: EkParichaya, AN	retence and capabilities for maintaining Health and Hygiene. New Delhi, 2019. ISBN 978-93-87034-47-1 onCourseinHumanValuesandProfessionalEthics,RRGaur, and Edition, Excel Books, New Delhi, 2019. ISBN 978-93-87034-53-2 Jagaraj, JeevanVidyaPrakashan, Amarkantak,1999. New Age Intl. Publishers, New Delhi, 2004.	
	•	Berning	STORE MIC COUNCIL	
•		, BOARD OF STUD Man - BoS	[] [] [] [] [] [] [] [] [] []	
		'- HICET	Dean (Academic HiCET	Joj

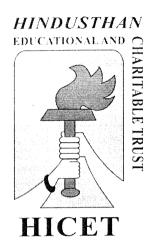
HINDUSTHAN COLLEGE OF ENGINEERING AND TECHNOLOGY

(An Autonomous Institution Affiliated to Anna University, Chennai)

(Approved by AICTE, New Delhi, Accredited by NAAC with 'A' Grade)

Coimbatore - 641 032.

B.E. MECHATRONICS ENGINEERING



CHOICE BASED CREDIT SYSTEM

Revised Curriculum and Syllabus for the odd semester
Academic year 2023-24
(Academic Council Meeting Held on 19.06.2023)



CURRICULUM R2022





Hindusthan College of Engineering and Technology
(An Autonomous Institution, Affiliated to Anna University, Chennai
Approved by AICTE, New Delhi& Accredited by NAAC with 'A' Grade) Valley Campus, Pollachi Highway, Coimbatore. Tamil Nadu.



DETAILS OF CHANGES CARRIED OUT IN CURRICULUM & SYLLABUS

CBCS PATTERN

UNDERGRADUATE PROGRAMMES

B.E. MECHATRONICS ENGINEERING (UG)

REGULATION-2022

For the students admitted during the academic year 2022-2023 and onwards

SEMESTER I

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	ClA	ESE	Total
		THEORY									1
1	22MA1101	Matrices and Calculus	BSC	3	1	0	4	4	40	60	100
2	22ME1201	Engineering Drawing	ESC	l	4	0	3	5	40	60	100
		THEORY WITH LAB CO	MPONEN'	Г		L				1	
3	22HE1151	English for Engineers	HSC	2	0	2	3	4	40	60	100
4	22PH1151	Physics for Non-Circuit Engineering	BSC	2	0	2	3	4	50	50	100
5	22IT1151	Python Programming and practices	ESC	2	0	2	3	4	50	50	100
		EEC COURSES (SI	E/AE)						***************************************		
6	22HE1071	Universal Human Values II	AEC	2	0	0	2	2	40	60	100
7	22HE1072	Entrepreneurship & Innovation	AEC	ĺ	0	0	1	1	100	0	100
		MANDATORY COU	RSE								
8.	22MC1091/ 22MC1092	தமிழரும் தொழில் நுட்பமும் / Indian Constitution	MC	2	0	0	0	2	100	0	100
			TOTAL	15	5	6	19	27	470	330	800

SEMESTER II

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY					•			•	
1	22MA2101	Complex Analysis and Differential Equations	BSC	3	1	0	4	4	40	60	100
2	22PH2102	Applied Mechanics	BSC	2	0	0	2	2	40	60	100
3	22CY2101	Environmental Studies	ESC	2	0	0	2	2	40	60	100
		THEORY WITH LAB CO.	MPONEN	T							
4	22HE2151	Effective Technical Communication	HSC	2	0	2	3	4	50	50	100
5	22CY2152	Applied Chemistry	BSC	2	0	2	3	4	50	50	100
6	22MT2251	Fundamentals of Mechatronics	PCC	2	0	2	3	4	50	50	100

		PRACTICAL COUF	RSES							THE SECTION AND ASSESSED.	
7	22ME2001	Engineering Practices	ESC	0	0	4	2	4	60	40	1()()
		EEC COURSES (SE	/AE)		•	4	+	•			Com attach stransversessesses
8	22HE2071	Design Thinking	AEC	1	0	2	2	3	100	0	100
9	22HE2072	Soft Skills -1	SEC	1	0	0	1	1	100	0	100
MANDATORY COURSE											
10.	22MC2091/ 22MC2092	தமிழர் மரபு / Heritage of Tamils	MC	2	0	0	0	2	100	0	100
11. 22MC2093 NCC */NSS / YRC / Sports / Clubs / Society Service - Enrollment (Common) NCC */NSS / YRC / Sports / Clubs / Society Service - Enrollment (Common) All students shall enroll, on admission, in anyone of the personality and character development programmes and undergo training for about 80 hours											
			TOTAL	17	1	12	22	30	630	370	1000

SEMESTER III

S. No	Course Code	Course Title	Category	L	T	P	С	ТСР	CIA	ESE	Total	
		THEORY			***************************************	•	4					
l	22MA3105	Fourier Series and Transforms	BSC	3	1	0	4	4	40	60	100	
2	22MT3201	Industrial Motor Control	ESC	3	0	0	3	3	40	60	100	
3	22MT3202	Solid and Fluid Mechanics	PCC	3	1	0	4	4	40	60	100	
4	22MT3203	Digitronics	PCC	3	1	0	4	4	40	60	100	
	THEORY WITH LAB COMPONENT											
5	22MT3251	Manufacturing Process	PCC	2	0	2	3	4	50	50	100	
		PRACTICAL										
6	22MT3001	Industrial Motor Control Lab	ESC	0	0	4	2	4	60	40	100	
7	22MT3002	Solid and Fluid Mechanics Lab	PCC	0	0	4	2	4	60	40	100	
		EEC COURSES (SE	/AE)									
8	22HE3071	Soft Skills and Aptitude -II	SEC	1	0	0	1	1	100	0	100	
9	22MT3072	Home Automation	AEC	0	0	4	2	4	60	40	100	
			TOTAL	15	3	14	25	32	490	410	900	

SEMESTER IV

S. No	Course Code	Course Title	Category	L	Т	P	C	ТСР	CIA	ESE	Total
		THEORY				-					
1	22HE4101	IPR and Start-ups	HSC	2	0	0	2	2	40	60	100
2	22MT4201	Processor and controller	PCC	3	0	0	3	3	40	60	100
3	22MT4202	Metrology and Measurements of MC	M ACC	3	0	0	3	3	.40	60	100
4	22MT4203	Theory of Machines	PCC	3	1	0	4	4	40	60	100

		THEORY WITH LAB CO	MPONEN	I							
5	22MT4251	Sensors and Transducers	PCC	2	. ()	2	3	4	50	50	100
6	22MT4252	Fluid Power System	PCC	2.	0	2	3	4	50	50	100
		PRACTICAL				•	•			•	
7	22MT4001	Processor and controller Laboratory	PCC	0	0	4	2	4	60	40	100
8	22MT4002	CAD Laboratory	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	E/AE)	•							
9	22HE4071	Soft Skills and Aptitude -II	SEC	1	0	0	1	1	100	0	100
			TOTAL	16	1	12	23	29	480	420	900

SEMESTER V

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY									
1	22MT5201	Machine Design	PCC	3	i	0	4	4	40	60	100
2	22MT5202	Control System	PCC	3	-0	0	3	3	40	60	100
3	22MT53XX	Professional Elective-1	PEC	3	0	0	3	3	40	60	100
4	22MT53XX	Professional Elective-2	PEC	3	0	0	3	3	40	60	100
5	22MT53XX	Professional Elective-3	PEC	3	0	0	3	3	40	60	100
		THEORY WITH LAB CO	MPONEN	Г			•				
6	22MT5251	Embedded System with C	PCC	2	0	2	3	4	50	50	100
		PRACTICAL								,	
7	22MT5001	Computer Aided Analysis Laboratory	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	/AE)								
8	22HE5071	Soft Skills -4/Foreign languages	SEC	1	0	0	1	1	100	0	100
			TOTAL	18	0	6	21	25	410	390	800

SEMESTER VI

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY									
. 1	22MT6201	Industrial Automation	PCC	3	0	0	3	3	40	60	100
2	22HE6101	Professional Ethics	HSC	3	0	0	.3	3	40	60	100
3	22MT63XX	Professional Elective-4	PEC	3	0	0	3	3	40	60	100
4	22MT63XX	Professional Elective-5	PEC	3	0	0	3	3	40	60	100
5	22XX64XX	Open Elective – 1*	OEC	3	0	0	3	3	40	60	100
6	22XX64XX	Open Elective – 2*	OEC	3	0	0	3	3	40	60	100
	•	PRACTICAL			1		L				-

7	22MT6001	Industrial Automation Laboratory	PCC	0	()	4	2	4	60	40	100	
8	22MT6002	CAM Laboratory	PCC	0	0	4	2	4	60	40	100	
	EEC COURSES (SE/AE)											
9.	22HE6071	Soft Skills – 5	SEC	2	0	0	2	2	100	0	100	
	·	TOTAL	20	0	8	24	28	460	440	900		

SEMESTER VII

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		THEORY			-			•	-		
1	22MT7201	Virtual Instrumentation	PCC	3	6	0	3	3	40	60	100
2	22MT7202	Robotics and Machine Vision	PCC	3	ı	0	4	4	40	60	100
3	22MT73XX	Professional Elective-6	PEC	3	0	0	3	3	40	60	100
4	22XX74XX	Open Elective – 3*	OEC	3	0	0	3	3	40	60	100
5	22XX74XX	Open Elective – 4*	OEC	3	0	0	3	3	40	60	100
	•	PRACTICAL				-					
6	22MT7001	Robotics Laboratory	PCC	0	0	4	2	4	60	40	100
		EEC COURSES (SE	E/AE)								
7	22MT7701	Internship*	SEC	0	0	0	2	2	100	0	100
			TOTAL	15	1	4	20	22	360	340	700
* -		internship carries 2 credit and it wil nt training and same will be evaluated in S			be	for	e S	emes	ter \	VI su	mme

SEMESTER VIII

S. No	Course Code	Course Title	Category	L	Т	P	С	ТСР	CIA	ESE	Total
		EEC COURSES	S (SE/AE)							,	
1	22MT8901	Project Work/Granted Patent	SEC	0	0	20	10	20	100	0	100.
		`	TOTAL	0	0	20	10	20	100	0	100

Note:

- 1. As per the AICTE guideline, in Semester I, II, III & IV NCC one credit subject is added as Value Added Course with Extra Credit. Further, the students' who enrolled his/her name in HICET NCC and Air Wing are eligible to undergo this subject. The earned extra credits printed in the Consolidated Mark sheet as per the regulation.
- 2. NCC course level 1 & Level 2 will be added in the list of open elective subjects in the appropriate semester. Further, the students' who have opted NCC subjects in Semester I, II, III & IV are eligible to undergo NCC Open Elective Subjects.
- 3. The above-mentioned NCC Courses will be offered to the students who are going to be admitted in the Academic Year 2022 23.



OPEN ELECTIVE I AND II (EMERGING TECHNOLOGIES)

To be offered for the students other than CSE, IT, AI&ML, ECE & BIO MEDICAL

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY		ERIO R WE		TOTAL CONTACT	CREDITS
	CODE	COOKSE TITLE	GORI	L	T	P	PERIODS	
1	22AI6451	Artificial Intelligence and Machine Learning Fundamentals	OEC	2	0	2	4	3
2	22CS6451	Blockchain Technology	OEC	2.	0	2	4	3
3	22EC6451	Cyber security	OEC	2	0	2	4	3
4	22EC6452	IoT Concepts and Applications	OEC	2	0	2	4	3
5	22IT6451	Data Science and Analytics	OEC	2	0	2	4	3
6	22BM6451	Augmented and Virtual Reality	OEC	2	0	2	4	3

OPEN ELECTIVE I AND II

To be offered for the students other than AUTO, AERO, AGRI, MECH, MCTS, CIVIL, EEE, CHEMICAL, FOOD TECH, E&I

S. NO.	COURSE		CATE GORY	PERIODS PER WEEK			TOTAL CONTACT	CREDITS
	0022	COUNSE TIPE	GOKI	L	T	P	PERIODS	
1	22AE6401	Space Science	OEC	3	0	0	3	3
2	22MT6401	Introduction to Industrial Engineering	OEC	3	0	0	3	3
3	22MT6402	Industrial Safety and Environment	OEC	3	0	0	3	-3
4	22CE6401	Climate Change and its Impact	OEC	3	0	0	3	3
5	22CE6402	Environment and Social Impact Assessment	OEC	3	0	0	3	3
6	22ME6401	Renewable Energy System	OEC	3	0	0	3	3
7	22ME6402	Additive Manufacturing systems	OEC	3	0	0	3	3
8	22EI6401	Introduction to Industrial Instrumentation and Control	OEC	3	0	0	3	3
9	22EI6402	Graphical Programming using Virtual Instrumentation	OEC	3	0	0	3	3
10	22AU6401	Fundamentals of Automobile Engineering	OEC	3	0	Ó	3	3
11	22AU6402	Automotive Vehicle Safety	OEC	3	0	0	3	3 .
12	22EE6401	Digital Marketing	OEC	3	0	0	3	3
13	22EE6402	Research Methodology	OEC	3	0	0	3	3
14	22FT6401	Traditional Foods	OEC	3	0	0	3	3
15	22AG6401	Urban Agriculture and Organic Farming	OEC	3	0	0	3	3
16	22CH6401	Biomass and Biorefinery	OEC	3	0	0	3	3

Note: Non-Circuit Departments can add one Open Elective course in the above list to offer for the circuit branches

OPEN ELECTIVE III

Students shall choose any one of the open elective courses such that the course content or title not belong to their own programme.

(Note: Each programme in our institution is expected to provide one course only)

S.	COURSE	COURSE TITLE	CATE GORY	PERIODS PER WEEK		DS EK	TOTAL CONTACT	CREDITS
	CODE	COOKSE TITEE	GOKI	L	T	P	PERIODS	
1	22MT7401	Project Management (Must in the hist)	OEC	3	0	0 .,	- 3	3

OPEN ELECTIVE IV

S. NO.	COURSE CODE		CATE GORY	PER WEEK			TOTAL CONTACT	CREDITS
		COCKSE TITLE	GORT	L	T	P	PERIODS	· ·
1	22LS7401	General studies for competitive examinations	OEC	3	0	0	3	3
2	22LS7402	Human Rights. Women Rights and Gender equity	OEC	3	0	0	3	3
3	22LS7403	Indian ethos and Human values	OEC	3	0	0	3	3
4	22LS7404	Financial independence and management	OEC	3	0	0	3	3
5	22LS7405	Yoga for Human Excellence	OEC	3	0	0	3	3
6	22LS7406	Democracy and Good Governance	OEC	3	0	0	. 3	3
7	22LS7407	NCC Level - II	OEC	3	0	0	3	3

PROFESSIONAL ELECTIVE COURSES: VERTICALS

Vertical I Information Systems	Vertical II Mechanical Engineering	Vertical III Management Studies	Vertical IV Manufacturing Process	Vertical V Vehicle Technology	Vertical VI Robotics and Automation
22MT5301 Database Management System	22MT5304 Composite Materials	22MT5307 Principles of Management	22MT5310 Non-Traditional Machining Techniques	22MT5313 Automobile System	22MT5316 Mobile Robotics
22MT5302 Data Science	22MT5305 Product Design and Development	22MT5308 Disaster Management	22MT5311 Computer Integrated Manufacturing	22MT5314 Automotive Electronics	22MT5317 Soft Robotics
22MT5303 Data Visualization	22MT5306 Applied Thermodynamics	22MT5309 Supply Chain Management	Flexible Manufacturing System	22MT5315 Electrical Vehicles	22MT5318 Micro Robotics
22MT6301 Cyber Safety	22MT6303 Non-Destructive Testing	22MT6305 Economics and Cost Management	22MT6307 Micro Manufacturing	22MT6309 Hybrid Vehicles	22MT6311 Textile Automation
22MT6302 AI for Mechatronics	22MT6304 Diagnostics Techniques	22MT6306 Digital Management	22MT6308 Industrial 4.0	22MT6310 Unmanned Aerial Vehicles	22MT6312 Factory Automation
22MT7301 Optimization Techniques	22MT7302 Machineries in Agriculture	22MT7303 Marketing Management	22MT7304 Rapid Prototyping	22MT7305 Modern Vehicles Technology	22MT7306 Automatic System

Students are permitted to choose all Professional Electives from a particular vertical or from different verticals.

PROFESSIONAL ELECTIVE COURSES: VERTICALS

Details of Vertical I: Information Systems

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT	CREDITS
			GONT	L	T	P	PERIODS	
1	22MT5301	Database Management System	PEC	3	0	0	3	3
2	22MT5302	Data Science	. PEC	3	0	0	3	3
3	22MT5303	Data Visualization	PEC	3	0	0	3	3
4	22MT6301	Cyber Safety	PEC	.3	()	0	3	3
5	22MT6302	AI for Mechatronics	PEC	3	0	0	3	3
6	22MT7301	Optimization Techniques	PEC	3	0	0	3	3

Details of Vertical II: Mechanical Engineering

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT	CREDITS
				L	T	P	PERIODS	
1	22MT5304	Composite Materials	PEC	3	0	0	3	3
2	22MT5305	Product Design and Development	PEC	3	0	0	3	3
3	22MT5306	Applied Thermodynamics	PEC	3	0	0	3	3
4	22MT6303	Non Destructive Testing	PEC	3	0	0	3	3
5	22MT6304	Diagnostics Techniques	PEC	3	0 .	0	3	3
6	22MT7302	Machineries in Agriculture	PEC	3	0	0	3	3

Details of Vertical III: Management Studies

S. NO.	COURSE CODE	COURSE TITLE	CATE GORY	PERIODS PER WEEK			TOTAL CONTACT	CREDITS
				L	T	P	PERIODS	
1	22MT5307	Principles of Management	PEC	3	0	0	3	3
2	22MT5308	Disaster Management	PEC	3	0	0	3	3
3	22MT5309	Supply Chain Management	PEC	3	0	0	3	. 3
4	122MT6305	Economics and Cost Management	PEC	3	Ó	0	3	3
5	22MT6306	Digital Management	PEC	3	0	0	3	3
6	22MT7303	Marketing Management	PEC	3	0	0	3	3



Details of Vertical IV: Manufacturing Process

S. NO.	COURSE CODE		CATE GORY		RIO R WE		TOTAL CONTACT	CREDITS
110.	CODE	COCKSE TITLE	GOKI	L	Т	P	PERIODS	
1	22MT5310	Non-Traditional Machining Techniques	PEC	3	0	0	3	3
2	22MT5311	Computer Integrated Manufacturing	PEC	3	0	0	3	3
3	22MT5312	Flexible Manufacturing System	PEC	3	0	0	3	3
4	22MT6307	Micro Manufacturing	PEC	3	0	0	3	3
5	22MT6308	Industrial 4.0	PEC	3	0	0	3	3
6	22MT7304	Rapid Prototyping	PEC	3	0	0	3	3

Details of Vertical V: Vehicle Technology

S. NO.	COURSE	COURSE TITLE	CATE GORY		RIO R WE		TOTAL CONTACT	CREDITS
110.	CODE	E COURSE TITLE		L	T	P	PERIODS	
1	22MT5313	Automobile System	PEC	3	0	0	3	3
2	22MT5314	Automotive Electronics	PEC	3	0	0	3	3
3	22MT5315	Electrical Vehicles	PEC	3	0	0	3	3
4	22MT6309	Hybrid Vehicles	PEC	3	0	0	3	3
. 5	22MT6310	Unmanned Aerial Vehicles	PEC	3	0	0	3	3
. 6	22MT7305	Modern Vehicles Technology	PEC	3	0	0	3	3

Details of Vertical VI: Robotics and Automation

S. NO.	COURSE	1	CATE GORY		RIO R WE		TOTAL CONTACT	CREDITS	
10.	CODE	COURSE TITLE	GUKI	L	T	P	PERIODS		
1	22MT5316	Mobile Robotics	PEC	3	0	0	3	3	
2	22MT5317	Soft Robotics	PEC	3	0	0	3	3	
3	22MT5318	Micro Robotics	PEC	3	0	0	3	3	
4	22MT6311	Textile Automation	PEC	3	0	0	3	3	
5	22MT6312	Factory Automation	PEC	3	0	0	3	3	
6.	22MT7306	Automatic System	PEC	3	0	0	3	3	

Enrollment for B.E. / B. TECH. (HONOURS) / Minor Degree (optional)

A student can also optionally register for additional courses (18 credits) and become eligible for the award of B.E. / B. Tech. (Honours) or Minor Decree. For B.E. / B. Tech. (Honours), a student shall register for the additional courses (18 credits from semester V onwards. These courses shall be from the same vertical or a combination of different same programme of study only. For

minor degree, a student shall register for the additional courses (18 credits) from semester V onwards. All these courses have to be in a particular vertical from any one of the other programmes.

Clause 4.10 of Regulation 2022 is applicable for the Enrolment of B.E. / B. TECH. (HONOURS) Minor Degree (Optional).

VERTICALS FOR MINOR DEGREE

• Heads are requested to provide one vertical from their program to offer for other program students to register for additional courses (18 Credits) to become eligible for the B.E./B.Tech. Minor Degree.

Note: Each programme should provide verticals for minor degree

S.	COURSE CODE		CATE GORY	1	CRIO R WI		TOTAL CONTACT	CREDITS
110.	CODE	COURSE TITLE	GOKI	L	Т	P	PERIODS	
I	22MT5601	Sem 5: Basics of Mechatronics System	MDC	3	0	0	3	3
2	22MT6601	Sem 6: Sensors and Interfacing	MDC	3	0	0	3	3
3	22MT6602	Sem6: Hydraulics and Pneumatics	MDC	3	0	0	3.	3
4	22MT7601	Sem 7: PLC and SCADA	MDC	3	0	0	3	3
5	22MT7602	Sem 7: Industrial Robotics	MDC	3	0	0	3	3
6	22MT8601	Sem 8: Design of Mechatronics System	MDC	3	0	0	3	3

^{*}MDC – Minor Degree Course

In addition to the above the following additional courses for Minor Degree can also be given to the student's common to all the branches.

Vertical I Fintech and Block Chain	Vertical II Entrepreneurship	Vertical III Environment and Sustainability
Financial Management	Foundations of Entrepreneurship	Sustainable infrastructure Development
Fundamentals of Investment	Introduction to Business Venture	Sustainable Agriculture and Environmental Management
Banking, Financial Services and Insurance	Team Building & Leadership Management for Business	Sustainable Bio Materials
Introduction to Blockchain and its Applications	Creativity & Innovation in Entrepreneurship	Materials for Energy Sustainability
1	Principles of Marketing Management for Business	Green Technology
mmiounchon io rimech	Human Resource Management for Entrepreneurs	Environmental Quality Monitoring and Analysis
1	Financing New Business Ventures	,

VERTICALS FOR HONOURS DEGREE

Vertical I Industrial Automation	Vertical II Medical Mechatronics	Vertical III Applied Robotics
22MT5203	22MT5204	22MT5205
Concepts of Machines and Mechanisms	Robotics m. Medicine	Robots and Systems in Smart Manufacturing
22MT6202	201/16204 CE	22MT6 20 6

Drives and Actuators for Automation	Brain Computer Interface and	Medical Robotics
	its Applications	
22MT6203	22MT6205	22MT6207
Power Electronics	Digital Image Processing	Agricultural Robotics and Automation
22MT7203	22MT7205	22MT7207
Advanced PLC	Radiological Equipment	Collaborative Robotics
22MT7204	22MT7206	22MT7208
Distributed Control System	Biomaterials	Robot Operating Systems
22MT8201	22MT8202	22MT8203
HMI & SCADA	Bionics	Humanoid Robotics

B.E (Hons) Mechatronics Engineering Specialization in Industrial Automation

S.No.	Course	Course Title	Category	F	Perio W	ds po eek	e r	ТСР	CIA	ESE	Total
	Code			L	T	P	С		A COLOR		
1	22MT5203	Sem 5: Concepts of Machines and Mechanisms	PC	3	0	0	3	3	40	60	100
2	22MT6202	Sem 6: Drives and Actuators for Automation	PC	3	0	0	3	3	40	60	100
3	22MT6203	Sem 6: Power Electronics	PC	3	0	0	3	3	40	60	100
4	22MT7203	Sem 7: Advanced PLC	PC	3	0	0	3	3	40	60	100
5	22MT7204	Sem 7: Distributed Control System	РС	3	0	0	3	3	40	60	100
6	22MT8201	Sem 8: HMI & SCADA	PC	3	0	0	3	3	40	60	100

B.E (Hons) Mechatronics Engineering Specialization in Medical Mechatronics

S.No.	Course	Course Title	Category	F	Perio W	ds p eek	er	ТСР	CIA	ESE	Total
	Code			L	T	P	C				
1.	22MT5204	Sem 5: Robotics in Medicine	PC	3	0	0	3	3	40	60	100
2.	22MT6204	Sem 6: Brain Computer Interface and its Applications	PC	3	0	0	3	3	40	60	100
3.	22MT6205	Sem 6: Digital Image Processing	РС	3	0	0	3	3	40	60	100
4.	22MT7205	Sem 7: Radiological Equipments	PC-	3	0	0	3	3	40	60	100
5.	22MT7206	Sem 7: Biomaterials	PC	3	0	0	3	3	40	60	100
6.	22MT8202	Sem 8: Bionics	PC	3	0	0	3	3	40	60	100



B.E (Hons) Mechatronics Engineering with Specialization in Applied Robotics

S.No.	Course Code	Course Title	Category	F	Perio W	ds p eek	er	ТСР	CIA	ESE	Total
	Code		- Annual Control	L	T	P	C]			
1.	22MT5205	Sem 5: Robots and Systems in Smart Manufacturing	PC	3	0	0	3	3	40	60	100
2.	22MT6206	Sem 6: Medical Robotics	PC	3	0	0	3	3	40	60	100
3.	22MT6207	Sem 6: Agricultural Robotics and Automation	PC	3	0	0	3	3	40	60	100
4.	22MT7207	Sem 7: Collaborative Robotics	PC	3	0	0	3	3	40	60	100
5.	22MT7208	Sem 7: Robot Operating Systems	PC	3	0	0	3	3	40	60	100
6.	22MT8203	Sem 8: Humanoid Robotics	PC	3	0	0	3	3	40	60	100

Note: Each programme should provide verticals for Honours degree

SEMESTER-WISE CREDIT DISTRIBUTION

, .	B.E. / B.TECH. PROGRAMMES													
S.No.	Course		Credits per Semester											
5.110.	Area	I	II	Ш	IV	V	VI	VII	VIII	Total Credits				
1	HSC	3	3	-	2	-	3	-	-	11				
2	BSC	7	9	4	-	-	-	-	-	20				
3	ESC	6	4	5		-	-	-	-	15				
4	PCC	-	3	13	20	12	7	9	-	64				
5	PEC	* -	-	-	-	9	9	-	-	18				
6	OEC	-	- -	-	-	-	3	9	-	12				
7	EEC	3	3	3	1	. 1	2	2	10	25				
8	MCC		√	✓	✓									
	Total	19	22	25	23	22	24	20	10	165				

CREDIT DISTRIBUTION R2022

Semester	I	И	Ш	IV	V	VI	VII	VIII	Total
Credits	19	22	25	23	22	24	20	10	165

Chairman BoS

Chairman - Bus MCT - HICET

Dean Academics

Dean (Academics)

Progra	ogramme Course Code Name of the Course L T						P	C
B.E	3		22MA3105	FOURIER SERIES AND TRANSFORMS (MECT, MECH)	3	1	0	4
Cour Objec		Th 1. 2. 3. 4. 5.	Apply the effect Apply the effect Apply Fourier		ndary	value į	problems.	
Unit				Description			Instruc Hou	
I	Diricl sine a	ilet's	R SERIES conditions- Gen osine series – Cha RY VALUE PRO	eral Fourier Series – Odd and Even Functions – Ha ange of Interval - Parseval's Identity - Harmonic an OBLEMS	lf rang alysis.	je	12	
П	equati	on o	f heat conduction	ations of one-dimensional wave equation - One din (excluding insulated edges).	nensio	nal	12	!
Ш	Gener infinit	al an	d Steady state so te and semicircul	•	tion in		12	
IV	Fourie of Sin Parsey	er Tra iple val'si	functions – Conv dentity(Statemen	ourier sine and cosine transforms – Properties - Tra olution Theorem (Statement only) – t only).	ınsforn	ns	12	
V	Z- Tra residu	ınsfo es) –	rms - Elementary	DIFFERENCE EQUATIONS properties – Inverse Z - transform (using partial frorem (excluding proof)– Solution of difference equation of the control of the cont	action lations	and	12	
				Total Instructio	nal Ho	ours	60	ı
Cours	se			urse, the learner will be able to e principles of Fourier series which helps them to s	olve pl	hysica	l problem	s of

Course Outcome

CO2: Employ Fourier series in solving the boundary value problems.

CO3: Understand Fourier series in solving the two-dimensional heat equations.

CO4: ApplyFourier transform techniques which extend its applications.

CO5: Illustrate the Z- transforms for analyzing discrete-time signals and systems.

TEXT BOOKS:

- T1 Erwin Kreyszig, "Advanced Engineering Mathematics", 10th Edition, Wiley India Private Ltd., New Delhi, 2018
- T2 Bali. N.P and Manish Goyal& Watkins, "Advanced Engineering Mathematics", 7th Edition, Laxmi Publications Pvt Ltd. 2007

REFERENCE BOOKS:

- R1 Veera Rajan. T.,"Transforms and Partial Differential Equations", Tata McGraw Hill Education Pvt. Ltd., Second reprint, New Delhi, 2012.
- R2 Grewal B.S., "Higher Engineering Mathematics", 44th Edition, Khanna Publishers, Delhi, 2018.
- R3 -Ramana. B.V., "Higher Engineering Mathematics", Tata McGraw Hill Publishing Company Limited, New Delhi, 2018.

PO& PSO	POI	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
COI	3	2	3	1	2		-	-	-	-	-	2	3	2
CO2	3	3	3	2	1	-	-		-	-	-	3	2	2
CO3	3	3	3	1	1	-	-	-	-	-	-	2	2	2
CO4	3	3	3	3	3	-	-	-	-	-	-	2	2	2
CO5	3	3	3	3	3	-	-	-	-	-	-	2	2	21
Avg	3	2.8	3	2	2	-	-	-	-	-	-	2.2	2.2	2/

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



Pr	ogramı B.E	gramme Course code Name of the course L B.E 22MT3201 INDUSTRIAL MOTOR CONTROL 3 The student should be made							
	Course bjectiv	5 TO SCIECT THE SUITABLE STAITING and DIAK	for industrial motors ting methods for electrical machin n of different Motors.		gies	for p	ower		
Uni	t	Description	a		In		tional		
	BASI	C CONTROL CIRCUIT COMPONENTS				Hou	irs		
I	AC sta	al Principles of Motor Control - Symbols and arters and DC starters (2 point 3 point) - ove of Circuits components and switches.	Schematic Diagrams – Manual crload relays - Relays, Contactor	Starters s- Basic	; C	9			
Ш	STAR Contro	C CONTROL CIRCUITS T - STOP Push Button Control - Multiple Publer - Jogging and Inching - Timing Relays - SecTING AND BRAKING METHODS	ısh Button Stations – Forward - quence Control	Reverse	ė .	9			
Ш	DOL S	Starter - Automatic Auto Transformer Starter. natic) Three Step Rotor Resistance Starter - Pl		atic and	i	9			
IV	DC she Constr	ND AC MOTORS unt Motor, De series motor, Single phase Induction and operation of synchronous motor, epper motors - Case Studies: Under water Mo	AC servomotor, Linear inductio			9			
V	Half ba	ER ELECTRONICS APPLICATIONS ridge and Full bridge: Single phase and Three arallel Inverter - Single phase and Three pion heating, UPS.	hase cyclo converters - Applic	ations	- '	9			
Ou	ourse tcome	CO1 Recognize the control circuit component CO2 Apply the control circuits in industrial racO3 Sketch the control circuits for Starting a CO4 Understand the basic operation of Moto CO5 Ability to choose the converters and inv	notor control nd Braking Methods rs and can select special motors f	_		45 purpo	ose.		
	T BOC		HTL: JEJE C.	201	-				
1 1	Stepne	n L. Herman, "Understanding Motor Controls	Inira Edition. Cengage Learning	ig, 201	/.				

- T2 M.H. Rashid, "Power Electronics: Circuits, Devices and Applications", Pearson Education, fourth Edition, New Delhi, 2014

REFERENCES:

- R1 Stephen L. Herman, "Industrial Motor Control" Seventh Edition, Cengage Learning, 2013
- R2 Bhattacharya.S.K & Brijinder Singh, "Control of Electrical Machines", 2nd Edition. New Age International (P) Ltd., New Delhi, 2010.
- R3 V.D. Singh and K.B. Khanchandani, "Power Electronics," 2nd Edition Mc Graw Hill India, 2013.

PO& PSO	PO1 ,	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	1	2									1	2	1
CO2	3	1	2									1	2	1
CO3	3	1	2	1								1	2	1
CO4	3	2	2	1	1	1			1 T Same .			1	2	1
CO5	3	2	2	1	1	1						1	2	1
Avg	3	1.4	2	1	1	1						1	2	1

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



Programme B.E	Course code 22MT3202 The student should	Name of the course L SOLID AND FLUID MECHANICS 3 d be made	T 1	-		<i>C</i> 4
Course Objective	and torsion.Apply these condAble to understaAble to understa	cepts of Forces. Equilibrium, Stress, Strain, Shear force, Benderets to simple problems in beams and Columns and the fundamentals of fluid flow. Indicate the effects of fluid flow through pipes. Indicate the types of turbines and pumps.		g mon		
Unit		Description	1		our	
I Elasticity of Shear F supported	of stress and strain – and elastic moduli – Force and Bending M I and cantilever bean		ot		+3	
Double Ir II in beams	ntegration method – - Short and long co	S AND COLUMNS Macaulay's method for computation of slopes and deflection olumns. Euler's theory; Assumptions, Derivation for Euler's conditions, Limitations of Euler's theory. Rankine formula for the conditions of Euler's theory.	's	9-	+3	
III Surface to Fluid versurbulent	ension – Capillarity – locity – Uniform and flow – Continuity ed			9	+	
Euler's ar IV .osses alo	nd Bernoulli's Equatong the flow - Cate	MEASUREMENT IN PIPE NETWORKS ions – Manometer, Venturi meter and orifice meter - Pressur gorisation into minor losses - Flow through circular pipes h equation – Friction factor – Pipes in series and parallel.		9-	+3	
V Introducti Governan	ce – Pumps - Centri	n of Turbines – Specific Speed – Turbine characteristics Spee fugal Pumps – Impeller Blade Profiles – Pump characteristic Pumps – Classification.		9-	+3	
		Total Instructional Hour mental concepts of deformation of solids and its effects on be- ects of shear stresses on beams and effect of load on columns.	ams		0 ply	•)
Outcome CC	O3 Explain the fundar O4 Describe the effec O5 Explain the types	mental concepts of fluid property and basic equations. (Under ts of fluid flow inside the pipes. (Understand) of turbines and pumps and calculating the efficiency (Apply)	·sta1	nd)		
R K Ban		Fluid Mechanics & Hydraulic Mechanics,- M/s. Laxmi Public	etic	ns (P	71.	td
T1 2010.	sai, A text book on i	ruid weenames & fryddaune weenames, - wws. Laxiii i ubile	au	1) 611	<i>,</i> L	ıu,

ΓE

T2 Er. R K Rajput, A Textbook of Strength of Materials (Mechanics of Solids) SI Units, S Chand Publishing, 2018

REFERENCES:

R1 Prof K. L. Kumar, 'Engineering Fluid Mechanics' SI units, S. Chand & Company Ltd, 2009.

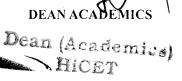
R2 Dr.R.K. Bansal, Strength of Materials, M/s. Laxmi Publications (P) Ltd, 2018.

PO& PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	1	2	3	3	1	1			1				1	
CO2	2	2	2	3	1								1 .	
CO3	2	-2		2				1					1	
CO4	1	1		1				1					1	
CO5	1	2				1		2					1	
Avg	1.4	1.8	2.5	2.25	1	1		1.33	1				1	

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET





Programi B.E	210111011105					C 4
Course Objectiv	e 2 To learn various co 3 To describe various 4 To familiarize the l	ne made ge about the fundamentals of logic gates ombinational and sequential circuits is flip-flops used in sequential circuits coasics of synchronous and asynchronous il concepts in mechatronics applications		ora		
Unit		Description			tructi Hour	
Minir I Minte Meth Level	nization Techniques: Boo erm - Maxterm - Sum of Pro od. Logic Gates: Logic Fund	IZATION TECHNIQUES lean Algebra - Simplification of Bool bduct - Product of Sum - Karnaugh Map - etions using Gates - NAND - NOR Implem ulti Output Gate Implementations	Quine McClusky		9+3	
II Half Multi	and Full Adders - Half and	Full Subtractors - Code Converters - End arry Look Ahead Adder - Magnitude Com	coder - Decoder - iparator.		9+3	
III Latch Up/D Minir	es - Flip-Flops SR, JK, D own Counters. Design of S), T, and Master - Slave. Asynchronous ynchronous Counters: State Diagram - S - Excitation Table and Maps - Modulo-n	tate Table - State		9+3	
IV Class	ifications of Memories - I	ROM Organization - RAM Organization Logic Array (PLA) - Programmable Arra (FPGA).	n. Programmable ay Logic (PAL) -		9+3	
V Digita Monit	oring and Control - Distrib	Management - FADEC. Industrial Autor uted Control Systems in Robotics - 3C - C tive Industry - Electronic Control Unit.	Communications,		9+3	
Course Outcome TEXT BOO T1 M. Mo	CO2 Develop combination CO3 Apply the minimizati CO4 Compare various pro CO5 Enumerate the applic OK: Orris Mano, Michel D. Cilet M Yarbrough, "Digital Logi	and to evaluate its function realizations usual and sequential circuit systems using floor techniques in sequential circuits grammable logic devices and its function ations of digital electronics in various fiet, "Digital Design", 5th Edition, Pearson to Applications and Design", 1st Edition,	lip flops Is I	Delh g, 2(60 i, 201 002.	2.

John F. Wakerly, "Digital Design", 4th Edition, PHI Learning Private Limited, New Delhi, 2006.

Thomas L. Floyd, "Digital Fundamentals", 8th Edition, PHI Learning Private Limited, New Delhi, 2003

Charles H.Roth. "Fundamentals of Logic Design", 7th Edition, Thomson Learning, 2003.

PO& PSO	PO1	PO2	РО3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	POII	PO12	PSO1	PSO2
CO1	3	3	3	3		3			2	3		3	3	3
CO2	3	3	3	3		3			2	3		3	3	3
CO3	3	3	3	3		3			2	3		3	3	3
CO4	3	3	3	3		3			2	3		3	3	3
CO5	3	3	3	3	3	3	3	2	3	3	3	3	2	3
Avg	3	3	3	3	3	3	3	2	2.2	2.8	3	3	3	3

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



4.	Programme Course code Name of the course L T B.E 22MT3251 MANUFACTURING PROCESS 2						
D.L		2	()	2	3		
Course Objective	The student should be made 1 To develop the knowledge about the casting and molding process 2 To list the fundamentals and various methods of manufacturing process 3 To choose the suitable welding process for manufacturability 4 To identify the different forming operations 5 To identify the finishing and Machining Process						
Unit	Description			truct			
				Hour 9	·s		
II Lathe I Shaper	HINING Machine - Lathe Operations - Drilling Machines - Reaming and Tapping Opera - Milling Machine. mental Components: Lathe - Facing, Step Turning and Taper Turning	itions - a.	•	6+4			
Weldin	PING elding - Gas Welding - Thermit Welding - Friction Welding - TIG & MIG W g Defects. mental Components: Lathe - Grooving, Thread Cutting and Knurling	⁷ elding -		6+2			
IV FORM Trimmi	ING Operations - Forging Operations - Extrusion and Types - Piercing - Pur	nching -		6+2			
FINISI Grindin V Equipm Equipm	HING OPERATIONS & CASE STUDIES lig - Lapping - Honing - Broaching - Case Study 1: Manufacturing the Agricultum lients - Case Study 2: Erection of Boilers - Case Study 3: Manufacturing the lients and Products. mental Components: Surface Grinding and Slot Cutting	e Sports		6+4			
Course Coutcome	CO1 Choose the suitable casting process based on the product requirements U2 Justify the most appropriate manufacturing process and material for a given U3 Interpret the different welding processes used in manufacturing U4 Design the process parameters for rolling and sheet metal operations U5 Perform a variety of Unconventional Machining Operations on manufacturing	n produc	ı L	30+1	5		

TEXT BOOK:

- Kalpak Jain, "Manufacturing Engineering and Technology", 4th Edition, Addison Wesley Congmen Pvt. Ltd.,
- Jain.R.K, "Production Technology: Manufacturing Processes, Technology and Automation", 17th Edition, Khanna Publishers, New Delhi, 2011..

REFERENCES:

- Hajra Choudhury, "Elements of Workshop Technology", Vol I and II, 3rd Edition, Media Promoters and Publishers Pvt. Ltd., Mumbai, 2012
- Sharma.P.C, "Production Technology: Manufacturing Processes", 7th Edition, S. Chand and Company Ltd., New R2 Delhi, 2008
- Chapman.W.A.J, "Workshop Technology Vol. I and II", 6th Edition, Arnold Publisher, New Delhi, 2006.

PO& PSO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3	3	3	2	3	2	2	1	2	2		1	1	1
CO2	3	2	2	2	3	2	2	1	2	2	1	1	1	1
CO3	3	2	2	1	2	2	2	. 1	2	2		1		1
CO4	3	2	2	1	2	2	2		1			1	1	1
CO5	3	2	2	2	2	2	2		2	2	2	1	1	3
Avg	3	2.2	2.2	1.6	2.4	2	2	1	1.8	2	1.5	1	1	1.4

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - RICET



DEANACADEMICS

Programme	Course code Name of the course	L	T	P	C
B.E	22MT3001 INDUSTRIAL MOTOR CONTROL LABORATORY	0	0	4	2
	The student should be made				
	1 To provide hands-on training for starters of electrical motors				
	2 To impart knowledge on control circuits for jogging and reversing operat	ions			
Course Objective	3 To understand solid state devices by conducting experiments				
Objective	4 To impart knowledge to conduct load test on D.C Machines				
	5 Exposed to the Load Test on Single and Three Phase Induction Motor				
Unit	Description		Ins	truct Houi	
1 Chambles	and control of materials DOI. Stanton mathed			~	

Unit	Description	Instructional Hours
1.	Starting and control of motor by DOL Starter method.	3
2	Wire and Test the Control Circuit for Semi-automatic and Automatic Star-Delta Starter	3
3	Wire and Test the Control Circuit for Jogging in Cage Motor and Single-Phase Preventer.	3
4	Study the effect of Forward and Reverse Operations control in cage motors.	3
5	Study of SCR characteristics	3
6	Study of MOSFET characteristics	3
7	Study of IGBT characteristics	3
8	Design and Implementation of Full Wave and Half Wave Rectifier using Diode	3
9	Load Test on D.C. Shunt Motor.	3
10	Load Test on D.C. Series Motor	3,
11	Load Test on Single Phase Induction Motor.	3
12	Load Test on Three phase Induction Motor.	3
Cor Oute	(O) Analyse solid state switches	s 45

PO& PSO	POI	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
CO1	3		1	1				1	2	2		2	1	1
CO2	2		1	1				1	2	2		2	1	1
CO3	3	2	1	1			v	1	2	2		2	1	1
CO4	2	2	1	1				1	2	2		2	1	1
CO5	3	2	1	1				1	2	2 ,		2	ĺ	1
Avg	2.6	2	1	1				1	2	2		2	1	1

Chairman - BoS MCT - HiCET



Dean (Academicscs)

Dean (HiCET

Programme	Course code	Name of the course	1.	T	P	C
B.E	22MT3002	SOLID AND FLUID MECHANICS & MACHINERY LABORATORY	0	0	4	2
	The student	should be made				
	1 To demons	strate various performance tests on engineering materials				
	2 To provide	knowledge on deflection test on materials				
Course	3 To impart	knowledge of various flow meters and the concept of fluid m	iechan	ics		
Objective	4 To obtain l	knowledge on the performance characteristics of pump				
	5 To impart	knowledge of Kaplan turbine				

Unit	t Description	Instructional Hours
1	Tension test on a Mild Steel Rod	3
2	Torsion test on a Mild Steel Rod	3
3	Deflection test on Beams	3
4	Compression test on Helical Springs	3
5	Impact test on Mild Steel Rod (Izod)	3
6	Impact test on Mild Steel Rod (charpy)	3
7	Hardness test on Metals by Brinell	3
8	Hardness test on Metals by Rockwell Hardness	3
9	Determination of Coefficient of Discharge by Venturimeter	$\frac{1}{2}$
10	Experimental and Verification of Bernoulli's Equation.	3
11	Conducting the experiments and drawing the characteristic curves of Centrifug	gal Pump 3
12	Conducting the experiments and drawing the characteristic curves of Kaplan 7	Turbine 3
	Total Instruc	
	CO1 Evaluate the different types of mechanical properties of engineering	ng materials
Cor	ourse CO2 Calculate the different stresses and strain of engineering materials	;
	tcome CO3 Apply the concepts of fluid energy in fluid flow applications	
Juit	CO4 Calculate the performance characteristics pump	
	CO5 Apply the measurement equipment for flow in turbine	

PO& PSO	POI	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
COI	3	1	2	3	.2	1	1	2		1		1	1	1
CO2	2	3	3	2	2	2	1	1		1		1	2	1
CO3	2	3	2	2	2	3	1			1		1	1	1
CO4	2	3	3	3	2	2	1	1		1		1	1	2
CO5	3	1	1	1				1		1		1	1	
Avg	2.4	2.8	2.2	2.2	1.6	1.6	1	í		1		1	1.2	1

Chairman - BoS MCT - HiCET



Progr	amme	Course Code	Course Title		L	T	P	C
В	E	22HE3071	Soft Skills and Aptitude - H		0	0	0	1
Cou Objec		2. Solve Quantitative3. Solve Verbal Ability	soning questions of easy to intermediate let Aptitude questions of easy to intermediate ty questions of easy to intermediate level ng skills while dealing with essays	vel : level				
Unit			Description			truct Hou		al
	Logica	al Reasoning				1104	15	
I	Clocks Bar Gi	s - Calendars - Directio aph - Data Sufficiency	n Sense - Cubes - Data Interpretation: Tab	les, Pie Chart,		9		
		itative Aptitud e					3	
II	Divisio Relativ	on of wages - Time, S /e speed, Problems base	ferent efficiencies, Pipes and cisterns, World beed and Distance: Basics of time, speed d on trains, Problems based on boats and stand n profit and loss - Averages - Weighted av	and distance, reams, - Profit		12		
	Verbal	Ability	process and took throughout the	erage				
111	Antece - Sent (signpo	edent Agreement, Verb 7 ence Completion and ost words, root words,	t-Verb Agreement, Modifiers, Parallelis fime Sequences, Comparisons, Prepositions Para-jumbles: Pro-active thinking, Reac prefix suffix, sentence structure clues), F	s, Determiners		7		
		red jumbles.						
IV		g skills for placements writing: Idea generation	for topics, Best practices, Practice and feed	dback		2		
			Total Instruc	ctional Hours		30		
	CC		d the various fallacies that can arise through	h the misuse of l	ogic.			
Course	e CC	methods.	pt for alternate methods to solve the pro					
Outcom	ie: CC	O3: Students will heig speaking	hten their awareness of correct usage of E	English grammar	in v	vritin	ig ar	nd
	CC		oncise and clear, using professional languag	ge for placements	s.			

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Programme	Course code	Name of the course	L	Т	P .	C
B.E	22MT3072	HOME AUTOMATION	0	0	4	2
	The student shou	ıld be made				
	1 To familiarize t	the basic introduction of automation process				
	2 To impart know	vledge on basics communication system				
Course	3 To study the ba	sic programming knowledge in automation				
Objective	4 To impart know	vledge on developing experimental model in au	tomation	1		
	5 To prepare the	product ideas from the real time problems				

Unit	Description	Instruction al Hours
1	Study of different types of Sensors and Actuators	3
2	Study of various Controllers	3
3	Study of Data Acquisition System	3
4	Study of Communication Protocols	3
5	LED Blink Using Arduino	3
6	Arduino based Light control with LDR Sensor	3
7	FAN ON/OFF control using PIR sensor	3
8	Speed control of a FAN with a analog sensor	3
9	Security control with biometric sensor	3
10	Floor cleaning BOT	3
11	Gas Leakage Indication system	3
12	Tank Level control	3
Cou Outc	11 / 1 general grant in age in determination	45

PO& PSO	POI	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO1	PSO2
COI	3				3	2		2	2	2	2	2	3	2
CO2	3	3	3	3	3	2		2	2	2	2	2	3	3
CO3	3	2	3	3	3	2		2	2	2	2	2	3	3
CO4	3	3	3	3	3	2		2	2	2	2	2	3	3
CO5	3	3	3	3	3	2		2	2	2	2	2	3	3
Avg	3	2.75	3	3	3	2		2	2	2	2	2	3	2.8

Chairman - BoS MCT - HiCET



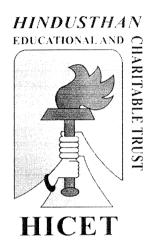
HINDUSTHAN COLLEGE OF ENGINEERING AND TECHNOLOGY

(An Autonomous Institution Affiliated to Anna University, Chennai)

(Approved by AICTE, New Delhi, Accredited by NAAC with 'A'Grade)

Coimbatore - 641 032.

B.E. MECHATRONICS ENGINEERING



CHOICE BASED CREDIT SYSTEM

Revised Curriculum and Syllabus for the odd semester
Academic year 2023-24
(Academic Council Meeting Held on 19.06.2023)



CURRICULUM R2019





Hindusthan College of Engineering and Technology (An Autonomous Institution, Affiliated to Anna University, Chennai Approved by AICTE. New Delhi & Accredited by NAAC with 'A' Grade) Valley Campus, Pollachi Highway, Coimbatore, Tamil Nadu.



DETAILS OF CHANGES CARRIED OUT IN CURRICULUM & SYLLABUS

CBCS PATTERN

UNDERGRADUATE PROGRAMMES

B.E. MECHATRONICS ENGINEERING(UG)

REGULATION-2019

For the students admitted during the academic year 2021-2022 and onwards

The course code 21 indicates that the students joined in the academic year 2021

SEMESTER I

S.No.	Course	Course Title	Т	Y	T	В		GL	Por	mom
3.110.	Code	Course Title	Type	L	T	P	C	CIA	ESE	TOTAL
	-	ТНЕО	RY	-				1		
1.	21HE1101	Technical English	HS	2	1	0	3	40	60	100
2.	21MA1102	Calculus and Linear Algebra	BS	3	1	0	4	40	60	100
		THEORY & LAB	COMPO	NEN'	T	-				
3.	21PH1151	Applied Physics	BS	2	0	2	3	50	50	100
4.	21CY1151	Chemistry for Engineers	BS	2	0	2	3	50	50	100
5.	21CS1151	Python Programming and Practices	ES	2	0	2	3	50	50	100
6.	21ME1152	Engineering Drawing	ES	1	0	4	3	50	50	100
				L			L		l	
7.	21HE1701	Language Competency Enhancement Course - I	HS	0	0	2	1	100	0	100
8.	21HE1072	Career Guidance – Level I Personality, Aptitude and Career Development	EEC	2	0	0	0	100	0	100
9.	21HE1073	Entrepreneurship & Innovation	EEC	ı	0	0	0	100	0	100
			Total:	15	2	11	20	550	350	900
As l	Per AICTE No	rms 3 Weeks Induction Programme i	s Added	in Th	ie Fi	rst Se	mest	er as an	Audit (Course

SEMESTER II

	SENIESI								
Course Code	Course Title	Type	L	Т	P	C	CIA	ESE	TOTAL
	THEO	RY						1	
21HE2101	Business English for Engineers	HS	2	1	0	3	40	60	100
21MA2101	Differential Equations and Complex Variables	BS	3	1	0	4	40	60	100
21ME2101	Engineering Mechanics	ES	3	0	0	3	40	60	100
	THEORY & LAB	COMPO	NEN'	Γ					
21PH2151	Material Science	BS	2	0	2	3	50	50	100
21CY2151	Environmental Studies	BS	2	0	2	3	50	50	100
21MT2153	Basics of Mechatronics Engineering	ES	2	0	2	3	50	50	100
	PRACTIC	MLS			-				
21GE2001	Engineering Practices Lab	CAG	0	0	4	2	60	40	100
21HE2701	Language Competency	n Egy	0	0	1	1	100	0	100
	Code 21HE2101 21MA2101 21ME2101 21PH2151 21CY2151 21MT2153	Course Code Course Title THEO 21HE2101 Business English for Engineers Differential Equations and Complex Variables 21ME2101 Engineering Mechanics THEORY & LAB Of Complex Indicates 21PH2151 Material Science 21CY2151 Environmental Studies 21MT2153 Basics of Mechatronics Engineering 21GE2001 Engineering Practices Laborates 21HE2701 Language Competency	Course Code Code Course Title Type THEORY 21HE2101 Business English for Engineers HS 21MA2101 Differential Equations and Complex Variables 21ME2101 Engineering Mechanics ES THEORY & LAB COMPO 21PH2151 Material Science BS 21CY2151 Environmental Studies BS 21MT2153 Basics of Mechatronics Engineering ES 21GE2001 Engineering Practices Lab 21HE2701 Language Competency	Code Code Code Code Course Title Type L THEORY 21HE2101 Business English for Engineers HS 2 21MA2101 Differential Equations and Complex Variables 21ME2101 Engineering Mechanics ES 3 THEORY & LAB COMPONENT 21PH2151 Material Science BS 2 21CY2151 Environmental Studies BS 2 21MT2153 Basics of Mechatronics Engineering ES 2 21GE2001 Engineering Practices Lab S 0 21HE2701 Language Competency F 14 0	Course Course Title Type L T	Course Course Title Type L T P	Course Course Title Type L T P C	Course Course Title Type L T P C CIA	Course Code

		MANDATOR	Y COURS	ES						
9.	21HE2072	Career Guidance Level – II Personality, Aptitude and Career Development	EEC	2	0	0	0	100	0	100
			Total:	16	2	11	22	475	425	900

SEMESTER III

		SEME	ESTER II	I						
S.No	Course Code	Course Title	Type	L	Т	P	С	CIA	ESE	TOTAL
		T	HEORY							
1.	21MA3101	Fourier Series and Statistics	BS	3	1	0	4	40	60	100
2.	21MT3201	Mechanics of solids	PC	3	1	0	4	40	60	100
3.	21MT3202	Industrial Motor Control	PC	3	0	0	3	40	60	100
4.	21MT3203	Digital Electronics in Mechatronics Systems	PC	3	0	0	3	40	60	100
		THEORY AND	LAB CO	MP	ONE	NT				1
5.	21MT3251	Production Technology	PC	2	0	2	3	50	50	100
		PRA	CTICAL	S		Annual Annua				***************************************
6.	21MT3001	Computer Aided Drafting Laboratory	PC	0	0	3	1.5	60	40	100
7.	21MT3002	Industrial Motor Control Laboratory	PC	0	0	3	1.5	60	40	100
		MANDAT	ORY CO	URS	ES					
8.	21MC3191	Indian Constitution	MC	2 '	0	0	0	100	0	100
9.	21HE3072	Career Guidance Level – III Personality, Aptitude and CareerDevelopment	EEC	2	0	0	0	100	0	100
10.	21HE3073	Leadership Management Skills	EEC	l	0.	0	0	100	0	100
	1	,	Total	19	2	8	20	630	370	1000

SEMESTER IV

S.No	Course Code	Course Title	Тур	e L	Т	P	С	CI	Α	ES	E	TOTAL
		T	HEOR	Y						-		
1.	21MA4101	Numerical Methods	BS	. 3	1	0	4	4	0	60)	100
2.	21MT4201	Microcomputer Systems and Microcontroller	PC	3	0	0	3	4	0	60)	100
3.	21MT4202	Thermodynamics and Fluid Engineering	PC	3	1	0	4	4	0	60)	100
4.	21MT4203	Theory of Machines	PC	3	1	0	4	4	0	60)	100
		THEORY AND	LAB C	COMPO	NEN	T						
4.	21MT4251	Sensors and Signal Conditioning		PC	2	0	2	3	5	50	50	100
		PRA	CTIC	ALS							,	
6.	21MT4001	Assembly Programming and Interfacing Laboratory		PC	0	0	3	1.5	ϵ	50	40	100
7.	21MT4002	Solid and Fluid Mechanics & Machinery Laboratory	ic co	PC	0	0	3	1.5	6	50	40	100
		MANDÂP	ORY	SOURS	ES							
8.	21MC4191	Essence of Indian tradition knowledge/Value Education	J.Kn	ın j	2	0	0	0	1	00	0	100

		Career Guidance Level – IV				100 - 000				
9.	21HE4072	Personality, Aptitude and Career	EEC	2	0	0	0	100	()	100
		Development	220	_				1	:	100
10.	21HE4073	Ideation Skills	EEC	2	0	0	0	100	0	100
			Total	20	2	10	21	630	370	100

SEMESTER V

,		SEMESTER	v							
S. No	Course Code	Course Title	Category	L	Т	P	С	CIA	ESE	Total
1.	21MT5201	Machine Design	PC	3	1	0	4	40	-60	100
2.	21MT5202	Industrial Automation and Control	PC	3	0	0	3	40	60	100
3.	21MT5203	Control of Mechatronics Systems	PC	3	0	0	3	40	60	100,
4.	21MT53XX	Professional Elective - I	· PE	3	0	0	3	40	60	100
		THEORY WITH LAB C	OMPONEN	T			•			
7.	21MT5251	Fluid Power Systems	PC	2	0	2	3	50	50	100
8.	21MT5252	Object Oriented Programming	PC	2	0	2	3	50	50	100
		PRACTICAL	LS						L	
9.	21MT5001	Computer Aided Machine Drawing Laboratory	PC	0	0	3	1.5	60	40	100
10.	21MT5002	Industrial Automation and Control Laboratory - I	PC	0	0	3	1.5	60	40	100
		MANDATORY CO	URSES							
11.	21HE5071	Soft Skills - I	EEC	1	0	0	1	100	0	100
12.	21HE5072	Design Thinking	EEC	1	0	0]	100	0	100
- Commence of the Commence of			TOTAL	18	1	10	24	580	420	1000

SEMESTER VI

		SEMESTER VI								
S. No	Course Code	Course Title	Category	L	Т	P	С	CIA	ESE	Total
		THEORY				1				
1.	21MT6181	Total Quality Management	HS	3	0	0	3	40	60	100
2.	21MT6201	Design of Mechatronics Systems	PC	3	0	0	3	40	60	100
3.	21MT6202	CNC Technology	PC	3	0	0	3	40	60	100
4.	21MT63XX	Professional Elective - II	PE	3	0	0	3	40	60	100
5.	21XX6401	Open Elective – I	OE	3	0	0	3	40	60	100
		THEORY WITH LAB COM	IPONENT			1	1	1		
6.	21MT6251	Vetronics	PC	2	0	2	3	50	50	100
		PRACTICALS								
7.	21MT6001	CNC Laboratory	PC	0	0	3	1.5	60	40	100
8.	21MT6002	Industrial Automation and Control Laboratory - II	PC	0	0	3	1.5	60	40	100
9.	21MT6701	Inplant Training / Internship *	EEC	0	0	0	1	60	40	100
		MANDATORY COUR	RSES							
10.	21HE6071	Soft Skill II	EEC	1	0	0	1	100	0	100

11.	21HE6072	Intellectual Property Rights (fPR)	EEC 1	0 0	1	100	0	100
			TOTAL 16	0 8	24	630	470	1100

S.No.	Course Code	Course Title	Туре	L	Т	P	С	CIA	ESE	TOTAL
A PARTIE A P	-	PROFESSIO	ONAL EL	ECTI	VEI				1	
1	21MT5301	Engineering Metrology and Measurements	PE	.3	0	0	3	40	60	100
2	21MT5302	Non-Traditional Machining Techniques	PE	3	0	0	3	40	60	100
3	21MT5303	Automobile Systems	PE	3	0	0	3	40	60	100
4	21MT5304	Operational Research	PE	3	0	0	3	40	60	100
5	21MT5305	Materials Science and Applications	PE	3	0	0	3	40	60	100
		PROFESSION	NAL ELE	CTIV	ΕII					
1	21MT6301	Embedded System	PE	3	0	0	3	40	60	100
2	21MT6302	Discrete Event System Simulation	PE	3	0	0	3	40	60	100
3	21MT6303	Product Design and Development	PE	3	0	0	3	40	60	100
4	21MT6304	Non-Destructive Testing Techniques	PE	3	0	0	3	40	60	100
5	21MT6305	Distinctive Electrical Machines	PE	3	0	0	3	40	60	100

OPEN ELECTIVE

S.No.	Course Code	Course Title	Type	L	Т	P	C	CIA	ESE	TOTAL
1.	21MT6401	Industrial Safety and Environment	OE	3	0	0	3	40	60	100

SEMESTER VII

	Course Title Category I T D C CIA FCF T-4-1													
S. No	Course Code	Course Title	Category	L	Т	P	С	CIA	ESE	Total				
		THEORY		·····, ···		1								
1.	21MT7201	Virtual Instrumentation and Human Machine Interface	PC	3	1	0	4	40	60	100				
2.	21MT7202	Machine Vision Systems	PC	3	0	0	3	40	60	100				
3.	21MT73XX	Professional Elective - III	PE	3	0	0	3	40	60	100				
4.	21XX7401	Open Elective – II	OE	3	0	0	3	40	60	100				
		THEORY WITH LAB CO	OMPONENT	ſ										
5.	21MT7251	Industrial Robotics	PC	2	0	3	3.5	50	50	100				
		PRACTICAL	S											
6.	21MT7001	CAE Laboratory	PC	0	0.	3	1.5	60	40	100				
	PROJECT WORK													
7.	21MT7901	Project Phase – I	EEC	0	0	4	2	60	40	100				
		CITY	TOTAL	14	1	10	20	330	370	700				

SEMESTER VIII

S.No	Course Code	Course Title	Type	L	T	P	C	CIA	ESE	TOTAL
			THEORY					Automotive and an artist and an artist and artist artist and artist and artist artis		
1.	21MT83XX	Professional Elective - IV	PE	3	0	0	3	40	60	100
2.	21MT83XX	Professional Elective - V	PE	3	0	0	3	40	60	100
		PR	ACTICAL				-			
3.	21MT8901	Project Work – Phase II	EEC	0	0	16	- 8	100	0	100
			TOTAL	6	0	16	14	180	120	300

PROFESSIONAL ELECTIVE III

		1 KO11	ESSIONAL	ELL	CIII	LIII				
S.No.	Course Code	Course Title	Type	L	T	P	С	CIA	ESE	TOTAL
1.	21MT7301	Mobile Robotics	PE	3	0	0	3	40	60	100
2.	21MT7302	Textile Automation	PE	3	0	0	3	40	60	100
3.	21MT7303	Medical Mechatronics	PE	3	0	0	3	40	60	100
4.	21MT7304	Disaster Management	PE	3	0	0	3	40	60	100.
5.	21MT7305	Factory Automation	PE	3	0	0	3	40	60	100
		PROFESSĮ	ONAL ELI	ECTI	VE I	V				-
1.	21MT8301	Rapid Prototyping and Reverse Engineering	PE	3	0	0	3	40	60	100
2.	21MT8302	Industrial IoT	PE	3	0	0	3	40	60	100
3.	21MT8303	Artificial Intelligence for Mechatronics Engineering	PE	3	0	0	3	40	60	100
4.	-21MT8304	MEMS and Nano Technology	PE	3	0	0	3	40	60	100
5.	21MT8305	Information System for Engineers	PE	3	0	0	3	40	60	100
		PROFESSI					1			
S.No.	Course Code	Course Title	Type	L	T	P	C	CIA	ESE	TOTAL
1.	21MT8306	Machineries in Agricultur		3	0	0	3	40	60	100
2.	21MT8307	Industrial Diagnostics and Maintenance Techniques	d PE	3	0	0	3	40	60	100
3.	21MT8308	Engineering Economics and Cost Analysis	PE	3	0	0	3	40	60	100
4.	21MT8181	Principles of Managemer	nt PE	3	0	0	3	40	60	100
5.	21MT8182	Professional Ethics in Engineering	PE	3	0	0	3	40	60	100

LIST OF OPEN ELECTIVES – MECHATRONICS ENGINEERING

	DIST OF OTEN ELECTIVES - MECHATRONICS ENGINEERING										
S.No.	Course Code	Course Title	Type	L	Т	P	С	CIA	ESE	TOTAL	
1.	21MT6401	Industrial Safety and Environment	OE	3	0	0	3	40	60	100	
		LIFE S	KILL CO	OURS	ES				•		
1.	21LSZ401	General Studies for Competitive Examination	OUNC	3	0	0	3	40	60	100	
2.	21LSZ402	Human Rights, Women Rights and Gender Equality	DA SE	3	0	0	3	40	60	100	

3.	21LSZ403	Indian Ethos and Human Values	OI.	3	0	0	3	40	60	100
4.	21LSZ404	Indian Constitution and Political System	OF	3	0	0	3	40	60	100
5.	21LSZ405	Yoga for Human Excellence	OE.	3	0	0	3	40	60	100

Enrollment for B.E. / B. TECH. (HONOURS) / Minor Degree (optional)

A student can also optionally register for additional courses (18 credits) and become eligible for the award of B.E. / B. Tech. (Honours) or Minor Degree. For B.E. / B. Tech. (Honours), a student shall register for the additional courses (18 credits) from semester V onwards. These courses shall be from the same vertical or a combination of different verticals of the same programme of study only. For minor degree, a student shall register for the additional courses (18 credits) from semester V onwards. All these courses have to be in a particular vertical from any one of the other programmes.

Clause 4.10 of Regulation 2022 is applicable for the Enrolment of B.E. / B. TECH. (HONOURS) / Minor Degree (Optional).

VERTICALS FOR MINOR DEGREE

• Heads are requested to provide one vertical from their program to offer for other program students to register for additional courses (18 Credits) to become eligible for the B.E./B.Tech. Minor Degree. Note: Each programme should provide verticals for minor degree

S. NO.	COURSE		CATE GORY	1	ERIO R WE		TOTAL CONTACT	CREDITS
	0002	COURSE TITLE	GONT	L	T	P	PERIODS	
1.	21MT5601	Sem 5: Basics of Mechatronics System	MDC	3	0	0	3	3
2.	21MT6601	Sem 6: Sensors and Interfacing	MDC	3	0	0	3	3
3.	21MT6602	Sem6: Hydraulics and Pneumatics	MDC	3	0	0	3	3
4.	21MT7601	Sem 7: PLC and SCADA	MDC	3	0	0	3	3 -
5.	21MT7602	Sem 7: Industrial Robotics	MDC	3	0	0	3	3
6.	21MT8601	Sem 8: Design of Mechatronics System	MDC	3	0	0	3	3

^{*}MDC - Minor Degree Course

In addition to the above the following additional courses for Minor Degree can also be given to the student's common to all the branches.

Vertical I	Vertical II	Vertical III				
Fintech and Block Chain	Entrepreneurship	Environment and Sustainability				
Financial Management	Foundations of Entrepreneurship	Sustainable infrastructure Development				
Fundamentals of Investment	Team Building & Leadership	Sustainable Agriculture and Environmental				
undamentals of investment	Management for Business	Management				
Banking, Financial Services	Creativity & Innovation in	Containable Dis March				
and Insurance	Entrepreneurship	Sustainable Bio Materials				
Introduction to Blockchain and	Principles of Marketing	Marailla Car Francis Control 1999				
its Applications	Management for Business	Materials for Energy Sustainability				
Fintech Personal Finance and	Human Resource Management for	Correct Testing I				
Payments	Entrepreneurs	Green Technology				
Introduction to Fintech	Financing New Business Ventures	Environmental Quality Monitoring and				
miroduction to 1 micen	i maneing ive was to the way with the second	Analysis				

VERTICALS FOR HONOURS DEGREE

Vertical I Industrial Automation	Vertical II Medical Mechatronics	Vertical III Applied Robotics
21MT5204 Concepts of Machines and Mechanisms	21MT5205 Robotics in Medicine	. 21MT5206 Robots and Systems in Smart Manufacturing
21MT6203 Drives and Actuators for Automation	21MT6205 Brain Computer Interface and its Applications	21MT6207 Medical Robotics
21MT6204 Power Electronics	21MT6206 Digital Image Processing	21MT6208 Agricultural Robotics and Automation
21MT7203 Advanced PLC	21MT7205 Radiological Equipment	21MT7207 Collaborative Robotics
22MT7204 Distributed Control System	21MT7206 Biomaterials	21MT7208 Robot Operating Systems
22MT8201 HMI & SCADA	22MT8202 Bionics	22MT8203 Humanoid Robotics

B Tech (Hons) Mechatronics Engineering Specialization in Industrial Automation

S.No.	Course Code	Course Title	Category]	Perio W	ds pe eek	r	ТСР	CIA	ESE	Total
				L	T	P	C			-	
1	21MT5204	Sem 5: Concepts of Machines and Mechanisms	PC	3	0	0	3	3	40	60	100
2	21MT6203	Sem 6: Drives and Actuators for Automation	PC	3	0	0	3	3	40	60	100
3	21MT6204	Sem 6: Power Electronics	PC	3	0	0	3	3	40	60	100
4	21MT7203	Sem 7: Advanced PLC	PC	. 3	0	0	3	3	40	60	100
5	21MT7204	Sem 7: Distributed Control System	PC	3	0	0	.3	3	40	60	100
6	21M\(\frac{1}{2}\)8201	Sem 8: HMI & SCADA	PC	3	0	0	3	3	40	60	100

B Tech (Hons) Mechatronics Engineering Specialization in Medical Mechatronics

S.No.	Course Code	Course Title	Category]	Perio W	ds po eek	er	ТСР	CIA	ESE	Total
	Code			L	T	P	C				
1.	21MT5205	Sem 5: Robotics in Medicine	PC	3	0	0	3	3	40	60	100
2.	21MT6205	Sem 6: Brain Computer Interface and its Applications	РС	3	- 0	0	3	3	40	60	100
3.	21MT6206	Sem 6: Digital Image Processing	PC.	3	0	0	3	3	40	60	100
4.	21MT7205	Sem 7: Radiological Equipments	PC	3	0	0	3	3	40	60	100
5.	21MT7206	Sem 7: Biomaterials	PE	3	0	0	3	3	40	60	100
6.	21MT8202	Sem 8: Bionics	295	1	0	0	3	3	40	60	100

B Tech (Hons) Mechatronics Engineering with Specialization in Applied Robotics

S.No.	Course Code	Course Title	Category	I	Perio W	ds p eek	er	ТСР	CIA	ESE	Total
				L	T	P	C	1			
1.	21MT5206	Sem 5: Robots and Systems in Smart Manufacturing	PC	3	0	0	3	3	40	60	100
2.	21MT6207	Sem 6: Medical Robotics	PC	3	0	0	3	3	40	60	100
3.	21MT6208	Sem 6: Agricultural Robotics and Automation	РС	3	0	0	3	3	40	60	100
4.	21MT7207	Sem 7: Collaborative Robotics	PC	3	. 0	0	3	3	40	60	100
5.	21MT7208	Sem 7: Robot Operating Systems	PC	3	0	0	3	3	40	60	100
6.	21MT8203	Sem 8: Humanoid Robotics	PC	3	0	0	3	3	40	60	100

Note: Each programme should provide verticals for Honours degree

SEMESTER-WISE CREDIT DISTRIBUTION

	B.E. / B.TECH. PROGRAMMES													
S.No.	Course		Credits per Semester											
3.110.	Area	. 1	II	Ш	IV	· V	VI	VII	VIII					
1	HSC	4	. 4	-	-	-	3	-	-	11				
2	BSC	10	10	4	4	-	-	-	-	28				
. 3	ESC	3	8	-	-	-	-	-		11				
4	PCC	-	· -	16	17	19	. 12	12	-	76				
5	PEC	-	-		-	3	3	3	6	15				
6	OEC	-	-	-	_	-	3	3	-	6				
7	EEC	3	- 1	-	_	2	3	2	8	18				
8	MCC		· 🗸 ·	✓	✓									
	Total	20	22	20	21	24	24	20	14	165				

CREDIT DISTRIBUTION R2019(BATCH 2021-2025)

Semester	I	II	· III	IV	V	VI	VII	VIII	Total
Credits	20	22	20	21	24	24	20	14	165

Chairman BoS

Chairman - BoS MCT - HICET

Dean Academics

Dean (Academics)

Programme	Course Code	Name of the Course	L	T	P	C
BE	21MT5201	MACHINE DESIGN	3	1	0	4
		(Approved Design Data Book is Permitted)				
	 To familiarize t 	he fundamentals involved in design process				
	2. To learn fundar	nental approaches to failure prevention for static a	nd repeated loa	ding		
Course Objective	To interpret the	types of gears and principles of gear tooth action				
Objective		damentals of brakes and chain drives				
	5. To impart the k	nowledge in selection of bearings and springs for d	lifferent applica	ations		
		n.		Ins	structio	onal
Unit			scription		Hours	š
		BEHAVIOR OF MATERIALS				
I		Optimum Design - Mechanical Properties of Mater			9+3	
		ic, Varying, Thermal, Impact and Residual - Facto	rs of Safety			
		ress Concentration Factors. AND WELDED JOINTS				
II		ow Shafts - Based on Strength, Rigidity and Defle	ection-		9+3	
11	Torsional Rigidity - Desi		etton .		7:5	
	GEARS	en en manne 1 anne.				
III	Principles of Gear Tooth	Action - Gear Correction - Gear Tooth Failure M	odes -		9+3	
		nponent Design of Spur, Helical and Bevel gears.				
	BRAKES AND CHAIN					
IV	Design of Brakes -Types	- Band - Block - Chain Drives - Selection of Tran	ismission		9+3	
		ailure of Chain Drives-Design of Bolt - Design of	Nuts.			
* *	BEARINGS AND SPR		Doorings		9+3	
V	Design of Bearings - She Design of Springs - Type	ding Contact - Rolling Contact - Design of Journal	bearings -		9±3	
	Design of Springs - Type	3 Fiched and Lear.			45.15	
					45+15	=60
	On completion of the co	arse the students will be able to				
		stress, strain and deflection in simple machine election				
		fety factors of simple structures exposed to static a				
Course		ne performance requirements in the selection of co		ailable	: machi	ne
Outcome	elements suc	th as shaft, coupling, gears, bearings and springs en	ic.	noner	te and	
	CO4: Design and o	optimize the selection of brakes and clutches for an	nonouve com	ponen	15 and	
	macinne ele	nems				

TEXT BOOKS:

T1- R.B.Patil, "Design of Machine Elements", 1stEdition, McMillan Publications, India, 2017.

CO5: Decide an appropriate failure model

T2- S. Md. Jalaludeen, "Machine Design (Vol. 1 & II)", 4th Edition, Anuradha Publications, Chennai, 2014.

REFERENCE BOOKS:

- R1- V.B.Bhandari, "Design of Machine Elements", 3rd Edition, Tata McGraw Hill Publishing CompanyLimited, New Delhi, 2010.
- R2- PSG College of Technology, "Design Data Book of Engineers", KalaikathirAchchagam, Coimbatore, 2018.
- R3- Maitra.G.M., and Prasad.LN., "Hand Book of Mechanical Design", 2nd Edition, Tata McGraw Hill Publishing CompanyLimited, New Delhi, 2005.
- R4- Sundararajamoorthy T. V. Shanmugam .N, "Machine Design", Anuradha Publications, Chennai, 2015.

CHAIRMAN, BOARD OF STUDIES

Chairman - Bos MCT - HiCET



	Mapping of COs with POs and PSOs													
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
COI	3	3	3	3	3	2	1	2				2	2	2
CO2	3	3	3	3	3	2	production or state of the stat	2	The state of the s		and and any place of the party	2	2	2
CO3	3	3	3	3	3	2	Table of the Control	2		CONTROL OF THE CONTRO	And a second second	2	2	2
CO4	3	3	3	3	3	2	1	2			Mills about on Wanders to	2	2	2,
CO5	3	3	3	3	3	2		2	The state of the s		Transition and the second	2	2	2
AVG	3	3	3	3	3	2	1	2	_	TO THE REAL PROPERTY OF THE PARTY OF THE PAR		2	2	2

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET





THEORY COURSES

Programme BE	Course Code Name of the Course 21MT5202 INDUSTRIAL AUTOMATION AND CONTRO	OL 3	T 0	P 0	C 3
Course Objective	 To study the architecture. Hardware and Software wiring of progra To read the fundamentals of PLC programming instructions To explain the PLC programs to perform specified discrete sequent To develop the knowledge in real time application using PLC To learn basic knowledge on architecture of SCADA and HMI 				
Unit	Description			tructio Hours	
	PROGRAMMABLE LOGIC CONTROLLERS			110013	
I	Architecture of PLC -Principles of Operations - PLC size and Application - Discrete Modules - PLC Analog Modules - I/O Specifications-Memory Typ Cycle - PLC Programming Language - Fundamentals of Logics. PROGRAMMING INSTRUCTIONS			9	
II	Programming EXAMINE ON and EXAMINE OFF Instructions -Logical In Control Instructions - Data Manipulating Instructions - Math Instructions -I			9	
	I/O Instructions - PLC Ladder Diagram.				
III	TIMERS AND COUNTERS ON DELAY Timer - OFF DELAY Timer - Retentive Timer - Timer Applic Counter - DOWN Counter- UP/DOWN Counter - Counter Applications - Counter and Counter Functions. APPLICATIONS OF PLC			9	
IV	Water Level Control - Material Handling Application - StampingSystem - S Painting System - Bottle Filling System - Lift Elevator Control - Traffic Lig - Automatic car washing machine - Automatic lubrication of supplier Conve SCADA SYSTEMS	ght Control -		9	
V	Introduction and Definition of SCADA - Basic Architecture of SCADA - Machine Interface - Master Terminal Unit - Remote Terminal Unit - Stansfer through PLC - Communication Technologies - Communication Systems - Components.	CADA Data	·	9	
	Total Instruct	ional Hours		45	
Course Outcome	On completion of the course the students will be able to CO1: Demonstrate knowledge and understanding of PLC interfacing and CO2: Design and describe the operation of a PLC program CO3: Choose various Timers and Counters based on real time application CO4: Create PLC program to control typical industrial related processes CO5: Infer and control the Industrial Process using SCADA systems		techni	ques	

TEXT BOOKS:

- T1- Frank D. Petruzella, "*Programmable Logic Controllers*", 3rd Edition, Tata McGraw Hill Publishing CompanyLimited,NewDelhi, 2010.
- T2- Ronald L.Kurtz, "Securing SCADA System", 1st Edition, John Wiley & Sons, 2015.

REFERENCE BOOKS:

- R1- John W.Webb and Ronald A.Reis, "Programmable Logic Controllers-Principles and Applications", 4th Edition, PHI Learning Private Limited, NewJersey, 2003.
- R2- Stenerson, "Fundamentals of Programmable Logic Controllers, Sensors and Communication", 3rd Edition, PearsonEducation, Asia, 2005.
- R3- William T. Shaw, "Cybersecurity for SCADA systems", Penn Well Books, 2006
- R4- Gary Dunning, "Introduction to Programmable Logic Controllers", 3rd India edition, Cengage Learning, 2007

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HiCET



	Mapping of COs with POs and PSOs													
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
CO1	1	0.00	2				And the state of t]	1	1	1	1	
CO2			3									1	2	
CO3			2	A STATE OF THE STA	1								2	
CO4			3						Application of the Control of the Co	MANAGER IN INCREMENT IN INCREMENT			3	
CO5	1		1									1	1	And the second s
AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	1.8	-

• 1-low, 2-medium, 3-high, '-"- no correlation

• Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN BOARD OF STUDIES

Chairman - BoS MCT - HICET



THEORY COURSES

Programme BE	Course Code 21MT5203	Name of the Course CONTROL OF MECHATRONIC		T ()	_	C 3
Course Objective	 To dis To sk To de 	tve the fundamental concepts of control systems the concept of time response of the stetch the plot for frequency response of systems and analysis state variable model ect the controller for mechatronics applied	ystem and error tem and stability analysis	odelir	ig of the system	m ·
Unit		Description		ı	nstructional	Hours
I .	Introduction and No Loop Systems - Tra	SENTATION AND MODELLING cod for Control Systems with Examples - unsfer Function Model - Mathematical Motor Block Diagram Reduction - Signal Flow	odeling of Mechanical.		9+3	
П	Standard Test Sign Domain Specificat Error.	als - Time Response – First order and S ions- Error Coefficients – Generalized			9+3	
III	compensation.	LYSIS Bode Plot - Polar Plot –Effects of Lag, I th Hurwitz Criterion - Root Locus constru	-		9+3	
IV	Function - Transfe	State Variables and State Models - State r Model. State Space Representation of Decomposition of Transfer Function - Co	f Dynamic Systems, State		9+3	
V	P, PI, PD and PID (Controller – Feed Forward Control - Tunin ributed Control System - Case study: Cor			9+3	
	•		Total Instructional Hours	s	45+15=60	
Course Outcome	CO1: Inter and itsTransf CO2: Desc CO3: Anal CO4: Solv	pret different physical, mechanical, electrer functions. The response of different order system yze the stability of the system using different system equations in state-variable form tify controller concepts used in industry	ns for and error series	quivale	ent models	,

TEXT BOOKS:

- T1- A. Nagoorkani, "Control systems Engineering", 3rd Edition, RBA Publications, Chennai, 2017.
- T2- Curtis D. Johnson, "Process Control Instrumentation Technology", 8th Edition, PHI Learning Private Limited, New Delhi, 2005.

REFERENCE BOOKS:

- R1- Katsuhiko Ogata, "Modern Control Engineering", 5th Edition, PHI Learning Private Limited, New Delhi, 2010.R2- M Gopal, "Control Systems-Principles and Design", 4th Edition, McGraw Hill Education, New Delhi, 2012.
- R3- Norman S. Nise, "Control Systems Engineering", 6th Edition, John Wiley Sons Inc., New York, 2010.R4- S.K.Bhattacharya, "Control System Engineering", 3rd Edition, Pearson, 2013.

WEB REFERENCES:

1. http://instrumentationtools.com/difference-between-dcs-plc-systems

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



NOT AMERICAN STREET	·	*	·	,	Марр	ing of C	Os with	POs and	PSOs	T				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
COI	1		2							1	1	1		- 1
CO2			3							-		1	N and a second	2
CO3			2		1				Military state and a state and					2
CO4			3					The state of the s						3
CO5	. 1		1					-	The state of the s			1		l
AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	_	1.8

• 1-low, 2-medium, 3-high, '-"- no correlation

• Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



THEORY CUM PRACTICALCOURSES

Programme BE	Course Code 21MT5251	Name of the Course FLUID POWER SYSTEMS	L 2	T 0	P 2	C 3
	To familiarize the fundamer	ntals of fluid power Principles, characteristics of the flui	d nowe	er syste	m	
C	components	,	[,		
Course Objective		m components for various applications				
Objective		uits for various Mechatronics systems				
		pneumatic system components for various application ions based on fluid power system	circuits	5		
Unit		Description			uction ours	al
	FLUID POWERSYSTEMS AND I	FUNDAMENTALS				
1				. 4	6	
II	Hydraulic Cylinders - Single Acting Rodless - Telescopic - Cushioning N				6	
	DESIGN OF HYDRAULIC CIRC					
111		ts: Direction Control Valve - 3/2 Way Valve - 4/2 W				
III			ve,		6	
		of Air - Compressors - Filter, Regulator and Lubricator				
IV	Unit - Fluid Power Circuit Design Sequential Circuit Design for Simple	- Speed Control Circuits, Synchronizing Circuit, e Applications using Cascade Method.			6	
	APPLICATION, MAINTENANCE					
V		tic Circuits Applied to Machine Tools - Presses - notive Systems - Maintenance and Trouble Shooting of s	of		6	
		Total Instructional House	rs		30	
	<u>LABOR</u>	ATORY COURSES HYDRAULICS	٠			
1	Design and Testing of the Following a. Pressure Control b. Flow Control	Hydraulic Circuits:	*		2	
2.		Directional and Semi-Rotary Motor System.			2	
3.	Design and Testing of Hydraulic Cylisoftware and PLC.	inder Sequencing System using fluid power simulation			2	
4.	Design and Testing of a Double Actin Control and PLC.	ng Cylinder using Sensor Based Elevtro Hydraulic			3	
5.	Design and Testing of Single Acting	PNEUMATICS Cylinder using of 3/2 Way Direction Control Valves.			2	
5. 6.		Cylinder and also Speed Control using Flow Control			2	
0.	Valves.				2	
7.	AND, OR logic Elements.	ole Acting Cylinder using 3/2 and 5/2 Way Valves,			2	
	Total Instructional Hours			15+3	30=45	
	On completion of the course the stude CO1: Explain the fundament	ents will be able to tal concepts of fluid power system				
Course Ou		oncepts into pumps and valves				
		uits for different applications				
		of pneumatic systems and its components				
	CO3. Manipulate the knowle	edge in fluid power system maintenance and troublesho	otingt	echniqi	ues	

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HiCET



DEANACADENICS

TEXT BOOKS:

- T1- Anthony "Esposito, Fluid Power with Applications", 6th Edition, PHI Learning PrivateLimited, New Delhi, 2009
- T2- R.Srinivasaan, "Hydraulics and Pneumatics Control". 2nd Edition, Mcgraw Hill India Pvt. Ltd, 2008

REFERENCE BOOKS:

- R1- Andrew *Parr, "Hydraulics and Pneumatics"*. 7th Edition, Jaico Publishing House, 2008R2- "FESTO, "Fundamentals of Pneumatics", Vol. I. II, III
- R3- S.R.Majundar, "Oil Hydraulic Systems- Principles and Maintenance", 2nd Edition, McgrawHill India Pvt. Ltd. 2008.
- R4- S.R.Majundar, "Pneumatic Systems- Principles and Maintenance", 2nd Edition, Mcgraw HillIndia Pvt. Ltd. 2007.

	Mapping of COs with POs and PSOs														
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2	
COI	3	2	2	2	2	1						2	2	3	
CO2	3	2	2	3	3	1						2	2	3	
CO3	3	2	3	3	3	1			-			2	2	3	
CO4	3	2	2	3	3	1	-					2	2	3	
CO5	3	2	2	3	3	1						.2	2	3	
AVG	3`	2	2.2	2.8	2.8	1	-	-	-	-	-	2	2	3	

• 1-low, 2-medium, 3-high, '-"- no correlation

• Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



THEORY CUM PRACTICAL COURSES

Programme BE	Course Code 211T5251	Name of the Course OBJECT ORIENTED PROGRAMMING	L 2	T 0	P 2	C 3
	1 True Language 41	Section of the sectio				
		ne concepts of object oriented programming the fundamental concepts of core JAVA				
Course	•	y various types of inheritance				
Objective	4. To develop	p the application programming based on exception handling				
	5. To develop	p the program using multithread THEORY				
				Inst	ruction	ıal
Unit		Description			Hours	
	2	TS OF OBJECT ORIENTED PROGRAMMING				
I		ogramming Concepts - Objects - Classes - Methods and Messages			6	
	OVERVIEW OF	ncapsulation - Inheritance - Polymorphism				
		gramming, Data Types, Variables and Arrays, Operators,				
II		- Classes, Objects and Methods - Constructors – This keyword -			6	
	PACKAGES AND	INTERFACES				,
III	Inheritance - Metho	od Overriding - Abstract Class - Final keyword - Java API			6	
		Conventions - Creating, Accessing, Using Packages - Interfaces: g, Implementing Interfaces.			U	
	EXCEPTION HA	NDLING				
IV	- Nested Try - Thro	Uncaught Exceptions - Using Try and Catch -Multiple Catch ws - Finally - Built in Exceptions - Throwing own			6	
	exceptions - Chaine	•				
		PROGRAMMING				
V		ding Thread - Stopping and Blocking Thread - Life Cycle -Using iority - Synchronization - Runnable Interface - Interactions.			6	
		Instructional Hour	rs		30	
		PRACTICAL			50	
1	Create class and obj	ject using Java program to display first 100 prime numbers				
2		plement Method overloading and random number				
3	Java program using	to implement Inheritance i) single inheritance ii) multilevel inheritance using super keyword	tance			
4		to implement method overriding and dynamic dispatch				
5	Java program to pri	nt Odd and Even Numbers from an Array				
6	Java program to cre	ate a thread, multi thread program				
7	Java program for in	nplement a Stack concept using Classes and Object				
8	Java program for pr	oducer consumer application				
		Instructional Hour Total Ho			15 45	
	On completion of the	he course the students will be able to				
Course	CO1: Describe the	concepts of objects, classes and inheritance				
Outcome		ncepts of data, array and structures				
	and polymorphism		1 funct	ions	1	
÷		ception handling application using programs program using the concepts of multithread				
			V	7	MAKETERS	

CHAIRMAN, BOARD OF STUDIES
Chairman - Bos
MCT - HiCET



TEXT BOOKS:

- T1: Herbert Schild, "Java the Complete Reference", 8th Edition, McGraw Hill Education, New Delhi, 2011.
- T2: Ali Bahrami, "Object Oriented Systems Development". 18 Edition, Pearson Education, New Delhi, 2008. **REFERENCE BOOKS:**
 - R1: E Balagurusamy, "Programming with JAVA", 5th Edition, McGraw Hill Education, New Delhi, 2015.
 - R2: Michael Blaha, James Rumbaugh, "Object Oriented Modeling and Design With UML", 2ndEdition, Pearson Education, New jersey, 2008.
 - R3: Paul Deitel, Harvey Deitel, "Java, How to Program", 8th Edition. PHI Publications, 2010.
 - R4: Ken Arnold, James Gosling. David Holms, "The java Programming Language", Pearson Education, 2003.

	Mapping of COs with POs and PSOs														
СО/РО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2	
CO1	3	2	3	2	3							2	2	1	
CO2	3	2	3	2	3		A STATE OF THE STA					2	2	ı	
CO3	3	2	3	2	3							2	2	1	
CO4	3	2	3	2	3			-				2	2	1	
CO5	3	2	.3	2	3		-					2	2	1	
AVG	3	2	3	2	3	_	_	-	_	-		2	2	1	

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES
Chairman - Boss
MCT - HiCET



DEANACADEMICS

Programme	Course code	Name of the course	L	T	P	C
B.E	21MT5001	COMPUTER AIDED MACHINE DRAWING LABORATORY	0	0	3	1.5
	The student s	hould be made				
	1 To develop s	kills on 2D drafting and 3D modeling using CAD softwar	e systei	ns		
Carre	2 To apply con	structional drawing techniques in Engineering field				
Course	3 To provide th	ne importance of computer aided machine drawing in vari-	ous app	licati	ons	
Objective	4 To assemble	various components to achieve the desire mechanisms.				
	5 To expose str	idents to gain knowledge in machine design elements				

Unit		Description	tructional Hours
1	Study	of Welding Symbols and Riveted Joints	3
2 -	Study	of Limits, Fits and Tolerances	3
3	Study	of Screw Threads and Threaded Fasteners	3
4	Assen	nbly Drawing of sleeve coupling	3
5	Assen	nbly Drawing of Protected Flange Coupling	3
6	Assen	nbly Drawing of Universal Coupling	3
7	Assen	nbly Drawing of Knuckle Joint	3
8	Assen	nbly Drawing of Screw Jack	3
9	Assem	nbly Drawing of Stuffing Box	3
10	Assen	nbly Drawing of Plummer Block	3
11	Assen	nbly Drawing of Connecting Rod	3
12	Assem	nbly Drawing of Machine Vice	3
		Total Instructional Hours	45
	, (CO1 Develop 2D, 3D models using modeling software	
Con		CO2 Design and model the constructional features in Engineering field	
Cou	(CO3 Apply the design skills in computer aided machine drawing	
Outc	ome (CO4 Demonstrate the machine drawings in assembly operations	
	(CO5 Design and model the given machine elements	

:	Mapping of COs with POs and PSOs														
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2	
CO1	2	2	2 .	2	2	2	2	2	2	2	2	2	1	1	
CO2	3	1	2	1	_	-	-	-	-	-	_	-	2	2	
CO3	-	3	3	2	-	-	-	-	1	_	-	-	3	3	
CO4	-	1	- 1	_	-	-	-	-	-	-	-	-	-1	1	
CO5	2	2	2	2	-	-	-	-	_	-	-	1	2	2	
AVG	2.3	1.8	2	1.75	2	2	2	2	1.5	· 2	2	1.5	1.8	1.8	

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCLI



DEAN ACADEMICS

Dean (Academics)

HiCET

Programme	Course code	Name of the course	L	T	P	C
B.E	21MT5001	INDUSTRIAL AUTOMATION AND CONTROL LABORATORY -I	0	0	3	1.5
Course	1 To acquire 2 To impart the	should be made knowledge onPLC hardware and software ne knowledge about the basic instruction set of PLC				
Objective	4 To create I applications	the PLC wiring with field devices adder logic diagrams for digital I/O's and interface with basics of SCADA	PLC	for	indu	strial

Unit	Description	Instructional
	·	Hours
1	Implementation of Logic Instruction using PLC Basic Operations.	3
2	Implementation of Math Instruction using PLC Basic Operations	3
3	Programming with PLCfor the Lamp Circuit.	3
4	Programming with PLC for Actuating Single Acting Cylinder.	3
5	Programming with PLC for Water Level Control of Two Different Water Tanks.	3
. 6	Programming with PLC for Material Handling System.	3
7	Programming with PLC for StampingSystem.	3
8	Programming with PLC for Spray Painting System.	3
9	Programming with PLC for Bottle Filling System.	3
10	Programming with PLC for Lift Elevator Control.	3
11 ~	Programming with PLC for Traffic Light Control.	3
12	Study of SCADA System.	3
	Total Instructional Hours	45
	CO1 Demonstrate the working knowledge of PLC for a real time process	
	CO2 Develop the program in PLC Software and interface with different	nt controlled
Cou		
Outco	ome CO3 Develop hard wiring with PLC and field digital I/Os	
	CO4 Create the ladder logic for industrial applications	
	CO5 Explain the uses of SCADA	

	Mapping of COs with POs and PSOs													
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
CO1			2										l	
CO2	1		1		2				. 1		3		2	
CO3	2		3		1				2		3		2	
CO4	1		3		3				3		2	,	3	
CO5			I									-	1	
AVG	0.8	-	2	_	1.2	-	-	-	1.2	-	1.6	-	1.8	-
		• 1-lc	ow, 2-me	dium, 3-	high, '-"-	no corre	elation		I	L	,		-	

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

							•
BE	21HI	E5071	SOFT SKILLS - I	1	0	0	1
Course Objectives:	2.To en 3.To in	rich students' num terpret things objec	enhance employability and ensure workplace and career success. erical ability of an individual and is available in technical flavor. ctively, to be able to perceive and interpret trends to make general ns behind an argument/statement.	izatic	ons a	nd b	e
Uniț	Description			Instructional Hours			
I		are of the Soft Skil	roduction- Objective -Hard vs Soft Skills - Measuring Soft lls -Self Management-Critical Thinking-Reflective thinking and	3	uis		
II	-Paraphrasing	g - Feedback - No	Communication - Effective Communication - Active listening on-Verbal Communication - Roles-Types- How nonverbal How to Improve nonverbal Communication - Importance of	4			
III	World of Tea self-confidence	ams: Self Enhance ce – developing en	nding with feelings in communication. ment - importance of developing assertive skills- developing notional intelligence - Importance of Team work – Team vs. ful team – Barriers involved - Working with Groups – Dealing	3			
IV	with People- Group Decision Making. Quantitative Aptitude: Averages - Profit and loss - Partnerships - Time and work - Time, Speed and Distance - Problems based on trains - Problems based on boats and streams						
\mathbf{V}	Logical Reasoning: Clocks - Calendars - Direction Sense - Data Interpretation: Tables, Pie Chart, Bar Graph - Data Sufficiency						
	COI:	Students will have with a chosen care	clarity on their career exploration process and to match their skil eer path.				
	CO2:	Students will deve their ability to wor	lop knowledge, skills, and judgment around human communication k collaboratively with others	on th	at fa	cilita	te

Students will understand how teamwork can support leadership skills

Students will be able to make sense of problems, develop strategies to find solutions, and persevere

Students will demonstrate an enhanced ability to draw logical conclusions and implications to solve

Course Title

CHAIRMAN, BOARD OF STUDIES

Programme

Course

Outcome:

CO3:

CO4:

CO5:

in solving them.

logical problems.

Course Code

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

PROFESSIONAL —ELECTIVES

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS
Dean (Academics)
HiCET

Course Code	Name of the Course L T						
21MT5301	ENGINEERING METROLOGY AND	.3	0	0	3		
2. To discu3. To identi4. To familIndustria	be the principle of dimensional metrology ss various linear and angular measurements fy the various types of errors using different instruments arize the principles, techniques and devices used for quality lenvironment	control i	n mode	ern			
	21MT5301 1. To descri 2. To discus 3. To identi 4. To famili Industria	21MT5301 ENGINEERING METROLOGY AND MEASUREMENTS 1. To describe the principle of dimensional metrology 2. To discuss various linear and angular measurements 3. To identify the various types of errors using different instruments	21MT5301 ENGINEERING METROLOGY AND 3 MEASUREMENTS 1. To describe the principle of dimensional metrology 2. To discuss various linear and angular measurements 3. To identify the various types of errors using different instruments 4. To familiarize the principles, techniques and devices used for quality control i Industrial environment	21MT5301 ENGINEERING METROLOGY AND 3 0 MEASUREMENTS 1. To describe the principle of dimensional metrology 2. To discuss various linear and angular measurements 3. To identify the various types of errors using different instruments 4. To familiarize the principles, techniques and devices used for quality control in mode Industrial environment	21MT5301 ENGINEERING METROLOGY AND 3 0 0 MEASUREMENTS 1. To describe the principle of dimensional metrology 2. To discuss various linear and angular measurements 3. To identify the various types of errors using different instruments 4. To familiarize the principles, techniques and devices used for quality control in modern Industrial environment		

Unit	Description	Instructional Hours
	BASICS OF MEASUREMENTS	Hours
I	General Concept of Measurement - Need for Measurement - Methods of Measurement - Units and Standards - Sensitivity - Stability - Range - Accuracy - Precision - Tolerance - Fits - Errors - Types of Errors - Interchangeability. LINEAR AND ANGULAR METROLOGY	9
II	Linear Metrology: Vernier Caliper - Micrometer - Dial Indicator - Slip Gauges and Classification - Optical Flats - Limit Gauges - Comparators - Mechanical, Pneumatic and Electric Types. Angular Metrology: Sine Bar - Optical Bevel Protractor - Auto Collimator - Angle Decker - Taper Measurements. FORM AND SURFACE MEASUREMENTS	9
Ш	Screw Thread Terminologies - Errors in Thread - Drunkenness - Measurement of Various Elements of Thread - Two and Three Wire Method, Gears Measurement: Gear Errors - Constant Chord and Base Tangent Method - Parkinson Gear Tester - Gleason Gear Testing Machine.Surface Finish Measurement: Elements of Surface Texture - Analysis of Surface Finish - Stylus Probe Instrument - Talysurf Method.	9
IV ,	ADVANCED TECHNIQUES IN METROLOGY Coordinate Measuring Machine - Constructional Features - Types and Application, Machine Vision Systems, Profile Projector, Universal Measuring Machine, Laser principles - Laser Interferometer - Types - DC and AC Laser Interferometer. APPLICATIONS OF MEASUREMENTS	9
V	Applications - Flow Measurements in Chemical Pipelines - Vehicle Tyre Pressure Measurement. Temperature Measurement in Furnace - Force Measurements in Brake Pedal and Torque Measurements in Motors.	9
	Total Instructional Hours	45
Course Outcome	On completion of the course the students will be able to CO1: Analyze the uncertainties in dimensional metrology and use the measurement st CO2: Apply geometric tolerances in design of engineering components CO3: Choose the proper method to find the errors in surface and screw threads CO4: Measure the complex profile using advanced measurement techniques CO5: Select the right measuring tool with decided accuracy for a given application	andards

TEXT BOOKS:

- T1- Ernest O Doebelin, "Measurement Systems Applications and Design", 4th Edition, Tata McGraw Hill Publishing CompanyLimited, New Delhi, 2008.
- T2- R. K. Jain, "Engineering Metrology", 20th Edition, Khanna Publishers, New Delhi, 2013.

REFERENCE BOOKS:

- R1- Thomas G Beckwith, Lienhard, Roy D. Marangoni, John H. Lienhard V "Mechanical Measurements", 6thEdition Addison Wesley, 2009.
- R2- Anand K Bewoor, Vinay A Kulkarni, "Metrology and Measurement", 1st Edition. Tata McGraw Hill Publishing CompanyLimited, New Delhi, 2009.
- R3- Connie Dotson et.al, "Fundamentals of Dimensional Metrology", Thomas Asia, Singapore, 2003.
- R4- Groover.M.P, "Automation, Production system and computer integrated manufacturing", Prentice Hall Publishing, New Delhi, 2003.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

		,	1	-	Марр	ing of C	Os with	POs and	PSOs					
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
COI	3	2	2										3	2
CO2	3		2			2							3	2
CO3		1	2	2		-								3
CO4	3		2											3
CO5	1	3	3	3								2		3
AVG	2	1.2	2.2	1	_	0.4	-	-	-	-	-	0.8	1.2	2.6

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES
Chairman, BOARD OF STUDIES
Chairman, BOARD OF STUDIES
MCT - HICET



Programme	Course Code Name of the Course L		Т	P	C
BE	+ 21MT5302 NON-TRADITIONAL MACHINING TECHNIQUES 3		0	0	3
Course Objective	 To select the process parameters of different advanced manufacturing processes To express their knowledge of electrical based manufacturing processes over convolation. To list the chemicals used in the manufacturing process To choose the suitable thermal techniques to achieve the high precision on the mac To examine the surface coating processes 			•	
Unit	Description			ructio	nal
	MECHANICAL ENERGY BASED PROCESSES		ļ	Hours	
1	Introduction - Modern Machining Process - Need - Advantages & Applications - Abrasive Jet Machining (AJM) - Working Principles - Process Parameters - Applications - Water Jet Machining (WJT) - Working Principles - Process Parameters - Applications - Ultrasonic Machining (USM) - Working Principles - Process Parameters - Applications - Applications.	3		9	
	ELECTRICAL ENERGY BASED PROCESSES				
II	Electric Discharge Machining (EDM) - Working Principles - Equipments - Process Parameters - Material Removal Rate - Tool - Dielectric - Flushing - Wire Cut EDM and its Applications - Electric Discharge Grinding - Working Principle - Equipment - Process Parameters - Applications.	; l		9	
	CHEMICAL AND ELECTRO CHEMICAL ENERGY BASED PROCESSES				
Ш	Chemical Machining (CHM) - Etchants - Maskant - Techniques of Applying Maskant Process Parameters - Material Removal Rate - Applications - Electro Chemical Machinin (ECM) - Principles of ECM - Equipments - Material Removal Rate - Process Parameters - Electro Chemical Grinding (ECG) and Electro Chemical Honing (ECH) - Applications. THERMAL ENERGY BASED PROCESSES	g		9	
	Laser Beam Machining (LBM) - Principles - Equipment - Applications - Plasma Arc				
IV	Machining (PAM) - Principles - Equipment - Types - Beam Control Techniques - Applications - Electron Beam Machining (EBM) - Principles - Equipment - Types - Beam Control Techniques - Applications.			9	
	SURFACE COATING AND HARDENING PROCESS				
V	Classification - Removal Processes - Conversion Coatings - Thermal Treatments - Metal Coatings - Physical Vapour Deposition (PVD) - Chemical Vapour Deposition (CVD) - Ion Plating - Galvanizing - Electroplating - Organic Coatings - Surface hardening - Laser hardening.			9	
	Total Instructional Hours			45	
Course Outcome	On completion of the course the students will be able to CO1: List the process parameters of different manufacturing process CO2: Operate the advanced electrical machining operation on the given component CO3: Select the appropriate chemical process based on the product material CO4: Interpret how a thermal techniques to be carried out CO5: Analyse and improve manufacturing processes through surface coating			- <u>-</u>	

TEXT BOOKS:

T1- Benedict. G.F, "Non Traditional Manufacturing Processes", 2nd Edition, Taylor, CRC Press, NewYork, 2021.

T2- Kaushik kumar, J, Paulo Darim Divya Zindani, "Advanced Machining and Manufacturing Processes", 1st Edition, Springler Nature, 2018. REFERENCE BOOKS:

R1- V. K. Jain, "Advanced Machining Processes",4th Edition, Allied Publishers, 2009. R2- E Weller, "Non Traditional Machining Process", 2nd Edition, 2006.

R3- P.C.Pandey, "Modern Machining Process", Mcgraw Hill Education, 2017. R4- "Advance Analysis of Non Traditional Machining", Springer, DRC 2012.

Chairman, BOARDBOSTUDIES
Chairman MCT - HICET



DEAN ACADEMICS

I second to shape	Mapping of COs with POs and PSOs													
СО/РО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
COI	3	2	3	2	3		1		The state of the s			2	2	2
CO2	3	2	3	2	3		1		The state of the s	-		2	2	3
CO3	3	2	3	2	3		l					2	2	2
CO4	3	2	3	2	3		1					2	2	2
CO5	3	2	3	2	3		1					2	2	3
AVG	3	2	3	2	3	-]	-	_	-	-	2	2	2.4

• 1-low, 2-medium, 3-high, ---- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEANACADEMICS

THEORY COURSES

Programme BE	Course Code 21MT5303	L 3	T	P 0	C 3	
Course Objective	 To define v dismantling To describe To classify 	knowledge about various automobile components and subsystemations transmission systems of automobiles and to have the prago of engine parts the mechanisms involved in the steering systems and braking different suspension systems used in automobile tout Electrical system and accessories used in automobiles	ictice for			
Unit		Description			tructio Hours	
I	Two Stroke and Fo Sump - Manifolds -	gines - Engine Terminology - Types of Engines: Petrol & Di ur Stroke - Engine Components: Cylinder Block - Cylinder F Gaskets - Cylinder - Piston - Rings - Connecting Rod - Piston rings - Valves - Mufflers. Engine Cooling and Lubrication syste	łead - Pins		9	
ΪΙ	Clutch - Construction Gear Boxes: Manual Torque Converter -	on of Electromagnetic - Mechanical - Hydraulic - Vacuum clu al and Automatic - Over Drives - Transfer Box - Fluid Flyw Propeller Shaft - Slip Joint - Universal Joints - Differential and n Lightweight Chassis.	heel -		9	
Ш	linkages and layou Alignment Paramet		- Wheel		9	
IV	Basic Requirements Independent Suspen suspension - Troubl	- Functions - Types of Suspension Springs - Plastic, Air and sion System - Shock Absorbers - Air suspension - Hydrolastic			9	
V	Circuit - Head Light	Construction, Operation and Maintenance - Lighting - Wiring is - Switches - Indicating Lights - Trouble Shooting - Direction reen Wiper - Horn - Speedometer - Heaters - Air conditioner.	1		9	J
		Total Instructional I	lours		45	
Course Outcome	CO1: Explain CO2: Describe CO3: Apply th CO4: Design a	various components in automobiles and also compare petrol and the working of manual and automatic transmission e steering mechanism in developing a new vehicle and develop a suspension vehicle system various electrical systems and accessories with vehicle battery		engin	e	

TEXT BOOKS

- T1- Kirpal Singh, "Automobile Engineering Vol. 1 and 2", 7th Edition, Standard Publishers. New Delhi, 2011.
- T2- H. M. Sethi, "Automobile Technology", 1st Edition, Tata McGraw Hill Publishing Company Limited, NewDelhi, 2007.

REFERENCE BOOKS:

- R1- Jain K.K. and Asthana .R.B, "*Automobile Engineering*", 2nd Edition, Tata McGraw Hill Publishing Company Limited, NewDelhi, 2002.
- R2- William H crouse, Donald T Anglin, "Automotive Mechanics", 10th Edition, Butterworth Publishers, 2017.
- R3- Joseph Heitner, "Automotive Mechanics," 2nd Edition, East-West Press, 2199.
- R4- Ganesan V, "Internal Combustion Engine", 3rd Edition, Tata McGraw Hill Publishing, NewDelhi, 2012.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

	-/				Марр	ing of C	Os with	POs and	l PSOs		THE RESERVE OF THE PARTY OF THE		(1) the last desired as a second of the last desired d	
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO10	PO11	PO12	PSO-1	PSO-2
CO1	- 1		2					~	1	1	l	1	1	
CO2	1		3									I	2	
CO3			2	,	1								2	
CO4			3										3	
CO5	1		1									ì	I	
AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	1.8	_

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

THEORY COURSES

Programme BE	Course Code 21MT5304	Name of the Course OPERATIONS RESEARCH	L 3	T 0	P 0	C 3
Course Objective	 To expose va To familiariz To learn basi 	te in modeling, solving and analyzing problems using line triety of problems such as transportation and trans-shipmed the students with assignment models c inventory control techniques. about maintenance and replacement schedule against fair	ent	ning		
Unit		Description		Ins	structio Hours	
1	Research - Models in Making, Methods of S Programming Problem	of Operations Research(OR) - Characteristics of Coperations Research - Role of Operations Research in Solving OR Problems - Scope of OR. Steps of Formulating (LPP) - Graphical Method - Special Cases in LP - Simple Case - Degeneracy in LP.	Decision ng Linear		9+3	
П	Formulation of General Solving Transportation	al Transportation Problems - Types of Transportation Pro n Problem - Loops in Transportation Method - Transport Distribution Method - Stepping Stone Method.			9+3	
III					9+3	
IV	Models of inventory-C purchase inventory mo stock level- Empirical	Operation of inventory-Quality discount-Implementation odel-Multiple item model with storage limitation-Determ queuing model.			9+3	
V	Types of Maintenance	ND MAINTENANCE ANALYSIS - Types of Replacement Problem - Determination of Ecolors of Interest Formulae - Examples - Simple Probabilistic pletely Fail.			9+3	
		Total Instruction	nal Hours	4	5+15=6	0
Course Outcome	CO1: Formulate a distribution CO2: Build and so CO3: Perform mo CO4: Understand	course the students will be able to and solve linear programming problem for a physical situal of goods and economics. The older of the control plan and workout stock level. It is a various replacement models and apply them for arriving				

TEXT BOOKS:

- T1- Nita H Shah, Ravi M.Gor and HardikSoni, "Operations Research". 1st Edition, PHI Learning Private Limited, New Delhi, 2007.
- T2- R.Panneerselvam, "Operations Research", 2nd Edition, PHI Learning Private Limited, New Delhi, 2010.

REFERENCE BOOKS:

- R1- Hamdy A Taha, "Operations Research", 8th Edition, Pearson Education, New Delhi, 2008.
- R2- S.Jaishankar, "Operations Research: Decision Models Approach", 1st Edition, Excel Books, New Delhi, 2010.
- R3- Taha.H A, "Operations Research", 6th Edition, PHI Learning Private Limited, New Delhi, 2003.
- R4- Bazara M J and Sherail H, "Linear programming and Network Flows", John Wiley, 2009.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEANACADEMICS

	Mapping of COs with POs and PSOs													
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1	PSO-1	PSO-
CO1	3	3	3	2 .	***************************************	1				THE REAL PROPERTY AND ADDRESS OF THE PERSON ADDRESS OF THE PERSON AND ADDRESS OF THE PERSON AND ADDRESS OF THE PERSON ADDRESS OF THE PERSO	1	1	3	1
CO2	3	3	2	-	1	1					1	1	2	1
CO3	3	3	2	Firms	1	1					, land	1	2	1
CO4	3	3	2	1	1	1					-1	1	1	1
CO5	3	3	2	1	I	1					1	1	ì	1
AVG	3	3	2.2	1.2	1	1	-	-	-	-	1	1	1.8	1

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

Chairman - Bos MCT - HICET



DEAN ACADEMICS

Dean (Academics)

HiCET

THEORY COURSES

1. To impart knowledge in mechanical properties of metals and non metals 2. To provide knowledge on effect of alloys in engineering materials To identify the difference of the state of t	
Objective 3. To identify the different types of heat treatment processes 4. To impart knowledge in production of composites materials 5. To learn the different field of applications of materials and composites	
Unit Description Instruction	
MATERIALS AND ITS PROPERTIES Hours	;
Introduction - Types of Materials - Metallic - Composite - Polymeric - Ceramic - Materials - Recent Advances in Materials. Mechanical Properties - Thermal Properties, Chemical Properties - Factors Affecting Mechanical Properties. Factors in Selection of Materials - Applications in Field of Automotive - Medical and Aero Space.	
METALS AND NON METALS Metallic Materials - Effect of Alloying Additions on Steel - Stainless and Tool Steels HSLA - Maraging Steels - Cast Iron - Grey and white - Copper and Copper Alloys - Aluminium and Aluminium Alloys - Brass - Bronze - Ni-based Super Alloys and Titanium Alloys. Non Metallic Materials - Polymers - Types of Polymer - Commodity and Engineering Polymers - Properties and Applications - Engineering Ceramics - Types of Ceramics - Properties and Applications.	
PROCESSING AND HEAT TREATMENT OF MATERIALS Processing of Ferrous and Non Ferrous Metals-Processing of Ceramics - Metals - Processing of Polymers - Introduction-Annealing, Stress Relief - Recrystallization and Spheroidising-Normalizing - Hardening, Case Hardening and Tempering of Steel - Chemical Vapor Deposition(CVD) - Physical Vapor Deposition(PVD). COMPOSITE MATERIALS	
Introduction - Classification of Composite Materials - Particle Reinforced Composites - IV Fibre Reinforced Composites - Fibre Glass Reinforced Composites - Hydrid Composites - Structural Composites - Protective Coatings - Adhesives - Concrete Polymer Composities.	
PROCESSING AND APPLICATIONS OF COMPOSITES Manufacturing of Polymer Matrix Composites (PMCs) - Pultrusion, Resin Transfer V Moulding (RTM) - Manufacturing of Metal Matrix Composites (MMCs) - Solid State - Liquid State - Vapour State Processing - Manufacturing of Ceramic Matrix Composites (CMCs) - Hot Pressing - Applications and Case Studies - Automotive - Aerospace - Commercial Applications.	
Total Instructional Hours 45	
On completion of the course the students will be able to	
CO1: Identify the properties of different ferrous and nonferrous metals	
Course CO2: Select appropriate materials based on the application	
Outcome CO3: Choose the suitable heat treatment process for changing the properties of materials	
CO4: Explain the properties composite materials	
CO5: Identify the production process in different fields of application	
EXT BOOKS: T1 George P. Correspond Dieter Tillman "Machanical Matallanan" 21d Fibian McCons Will File via N. W. J.	

TE

- T1- George P. Carney and Dieter Tillman, "Mechanical Metallurgy", 3rd Edition, McGraw Hill Education, New York,
- T2- Sidney H. Avner, "Physical Metallurgy", 2nd Edition, Tata McGraw Hill Education, New York, 2012.

REFERENCE BOOKS:

- R1- Robert M. Jones, "Mechanics of Composite Materials", 1st Edition, 2nd Edition Taylor and Francis Group, 2006.
- R2- Lawrence H. Van Vlack, "Elements of Material Science and Engineering" 6th Edition, Pearson Publication, Australia,
- R3- Williams D Callister, "Material Science and Engineering" Revised Indian Edition, Wiley India Pvt. Ltd., New Delhi,
- R4- O P kanna, "A Text Book of Material Science and Metallurgy", 5th Edition, Dhanpat Rai Publications, 2001.

CHAIRMAN, BOARD OF STUDIES

Chairman - Bos MCT - HiCET



Dean (Académics)

	Mapping of COs with POs and PSOs													
СО/РО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1 2	PSO-1	PSO-2
CO1	3	3	2	2	2	-			1	At 10 the party and a second s		2	2	1
CO2	3	3	2	2	2	_			1	OF THE PARTY OF TH		2	2	1
СОЗ	3	3	2	2	2				1			2	2	1
CO4	3	3	2	2	2				1			2	2	1
CO5	3	3	2	2	2				Total Transition of the Control of t			2	2	1
AVG	3	3	2	2	2	-	-	-	1	-	-	2	2	1

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HiCET



DEAN ACADEMICS

Dean (Academics)

HiCET

MINOR DEGREE SEM V

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Dean (Academics)

HiCET

.,,	ramn 3. E	ie (L 3	T 0	P 0	C 3		
	ourse ective	1 2 3	To apply the To impart kn To provide k	ald be made owledge on basic measurements and its principles basic laws used in Electrical circuits and the different compowledge on construction and working of DC nowledge on the fundamentals of semiconductor devices are the basic introduction of sensors & actuators			olicati	ions
Unit				Description			tructi Hour	
I	Unit Mea	s and sureme		dibration Techniques - Errors in Measurement – General Itmeter - Ammeter - Multimeter - Meter Protection	alized		9	
II	Curr and I Mesl	ent - V Paralle n Analy	'oltage - Power l Circuit - Kirch ysis.	- Resistor - Pullup and Pull down resistor - Ohms Law - S hoff's Voltage Law - Kirchhoff's Current Law - Nodal Anal			9	
Ш	Prince phase DC N	ciples c e) - Syr Motor -	nchronous mach Stepper Motor	characteristics of DC machines - Transformers (Single and ines - Three phase and Single phase Induction motors - Brus - Servo Motor			9	
IV	Char Halfv TRI	acteris wave a AC & I	nd Fullwave Re GBT.	ion Diode - Zener Effect - Zener Diode and its characterisctifiers - Voltage Regulation - Study of Switching devices			9	
V	Princ – Res	iples – sistive	Transducer – In	RS of Transducers – Parameters – Criteria for Transducers sele ductive Transducer – capacitive Transducer -Types of actu s- Examples and applications			9	
Cou Outco		CO2 CO3 CO4 CO5	Apply the KVL Explain the cor Identify electro	Total Instructional He devices for measurement. and KCL in electrical circuits astructional features of AC and DC machines. nics components and use of the mode sign circuits a diagram and explain about the sensors and actuators functions.		:	30+15	5
			Arayind Mittle	"Basic Flectrical Engineering" Tota McGray II	melas	ti a m	C	

- VN Mittle, Aravind Mittle, "Basic Electrical Engineering", Tata McGraw HillEdition, Second edition, New Delhi, 2009.
- AK Sawney, Puncet Sawney, "A Course in Electrical and Electronic Measurements and T2 Instrumentation",2nd Edition, Dhanpat Rai & Company,2010.

REFERENCES:

- Shanmugam G and Palanichamy MS," Basic Civil and Mechanical Engineering", Tata McGraw Hill Publishing Co., New Delhi, 3rd Edition, 2010.
- Muthu Subramanian R.Salivahanan S and Muraleedharan KA," Basic Electrical, Electronics and Computer R2 Engineering", Tata McGraw Hill, Second Edition, 2010
- R3 Musa Jouaneh and Christopher M Shott, "Fundamentals of Mechatronics", Global Engineering Publications, Second Edition, 2013.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



DEAN ACADEMICS

-					Марр	ing of C	'Os with	n POs a	nd PSO	s				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1	PSO-1	PSO-2
CO1	3	2	1	0	0	0	0	0	0	0	0	1	3	2
CO2	3	3	1	0	0	0	0	0	0	0	0	2	2	2
CO3	2	0	3	0	1	0	0	0	0	0	0	1	3	3
CO4	2	0	3	2	0	0	0	0	0	0	0	1	3	3
CO5	3	0	0	0	2	0	1	0	0	0	0	2	2	1
AVG	2.6	1	1.6	0.4	0.6	0	0.2	0	0	0	0	1.4	2.6	2.2

• 1-low, 2-medium, 3-high. '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HiCET



DEAN ACADEMICS

Program B.E	E 21CS5602 FINANCIAL MANAGEMENT						C 3
Course Objective	2. To learn th3. To describe4. To discuss	ne various sources on e about capital bud on how to construc	the decision areas in finance. of Finance geting and cost of capital ct a robust capital structure and dividend policy of tools on Working Capital Management.				
Unit			Description	In	stru Ho		ıal
I Defi	nition and Scop		MANGEMENT tions - Objectives of Financial Management - Profit n- Time Value of money- Risk and return concepts)	
II Lon Mer	its and Demeri	of Finance -Equity ts. Short term so	Shares – Debentures - Preferred Stock – Features – purces - Bank Sources, Trade Credit, Overdrafts, posits, Money market mutual funds etc		ğ)	
Inve III Bud Spec mean	geting — Paybac rific Sources of surement of cost	is: capital budgetin ck -ARR – NPV – Capital - Equity of capital - Weight	ng – Need and Importance – Techniques of Capital - IRR –Profitability Index. Cost of Capital - Cost of -Preferred Stock- Debt - Reserves - Concept and ted Average Cost of Capital.		Ç)	
Oper IV deter Aspe	rating Leverage rminants of Capit	tal structure- Desig	everage- EBIT-EPS analysis. Capital Structure – ming an Optimum capital structure. Dividend policy – nsideration - forms of dividend policy Determinants		ç)	
V Wor Dete	king Capital Ma rminants of Wor	king capital. Cash	ng Capital Management - concepts - importance - Management: Motives for holding cash - Objectives ceivables Management: Objectives - Credit policies		9)	
	601		Total Instructional Hours		4	5 .	
Course Outcome EXTBOOK:	CO2: learn t CO3: descri CO4: constr CO5: develo	the various sources be about capital buruct a robust capital	of the decision areas in finance. of Finance idgeting and cost of capital structure and dividend policy g of tools on Working Capital Management.				

TE

- T1 .Y. Khan and P.K.Jain Financial management, Text, Tata McGraw Hill.
- T2 M. Pandey Financial Management, Vikas Publishing House Pvt. Ltd

REFERENCES:

- James C. Vanhorne –Fundamentals of Financial Management– PHI Learning. **R**1
- R2 Prasanna Chandra, Financial Management
- R3 Srivatsava. Mishra, Financial Management, Oxford University Press, 2011.

Chairman, BOARD OF STUDIES Chairman - BoS MCT - HICET



DEANACADEMICS

Dean (Academass)
HiCET

Programi	ne Course Code	Course Code Name of the course					
BE	21BA5601	Foundations of Entrepreneurship	3	0	0	3	
Cours Objecti	e CO2: To make stude CO3: To provide kn CO4: To enable stude	dents gain insights on entrepreneurship. ents understand the sources of product & business ideas. owledge on business opportunity identification. dents to develop business plan lents to prepare feasibility reports and understand trends in entrepre		•			
Unit		Description			iction: ours	al	
I	entrepreneurship in India. I impact; Entrepreneurial grow	reneurship: Entrepreneurial growth in India; sources of Entrepreneurship process; entrepreneurial mindset: concept and with strategies. Characteristics of an Entrepreneur – Qualities of an I success and failure - reasons and remedies.		9			
II	Ideas - Criteria for Selecting	oduction and Meaning of a Product – Sources of Business or Product a Product – Barriers to the successful development of New Products Technology - Considerations in selecting technology.		9			
,III		ification: Need and Importance - Steps in identification of Business narket Survey – Market Research Procedure.	i	9	1		
IV	Business Plan Development and Entrepreneurship: conce Elements of business planni	t: Business modelling: concept, types and functions: Innovation pt and challenges. The business plan as an entrepreneurial tool, ng. Objectives, Market analysis, development of Product/idea, ation and management, Ownership, Critical risk contingencies of		9			
V	Feasibility Report & trends: a feasibility report – Profo	: Contents of a feasibility report – Considerations while preparing rma of a feasibility report. Technical, Financial, Marketing, feasibility reports. Trends in entrepreneurship: Rural, Social and		9			
		Total Instructional Hours		45	5 .		
Course Outcome	CO2: Understand the conc CO3: Able to understand a CO4: Able to develop busi	es of entrepreneurship and its process. ept of product development and the role of technology. nd identify business opportunity ness plan / business model bility reports and understand the trends in entrepreneurship.					

TEXT BOOKS:

- T1- S.Anil Kumar, S.C.Poornima, Mini KAbraham, K.Jayashree "Entrepreneurship Development", New Age International Publishers.
- T2- Jasmer singh Sain, Entrepreneurship and small Business" Deep and Deep publication
- T3- Shankar Raj, "Entrepreneurship Theory and Practice" Vijay Nicole Imprints Pvt ltd.
- T4- Khanka, S.S, "Entrepreneurship Development", S. Chand & company
- T5- Vasant Desai, "Fundamentals of Entrepreneurship "Himalaya Publishing House.

REFERENCE BOOKS:

- R1- Khanna, S. S., Entrepreneurial Development, S. Chand, New Delhi.
- R2- Hisrich D. Robert, Michael P. Peters, Dean A. Sheperd, Entrepreneurship, McGraw-Hill, 6 ed.
- R3- Zimmerer W. Thomas, Norman M. Scarborough, Essentials of Entrepreneurship and Small Business Management, PHI, 4 ed.
- R4- Holt H. David, Entrepreneurship: New Venture Creation, Prentice- Hall of India, New Delhi, Latest edition.
- R5- Kuratko, F. Donald, Richard M. Hodgetts, Entrepreneurship: Theory, Process, Practice, Thomson, 7ed.
- R6- Desai, Vasant, Dynamics of Entrepreneurship: New Venture Creation, Prentice-Hall of India, New Delhi, Latest edition.
- R7- Patel, V. G., The Seven Business Crises and How to Beat Them, Tata McGraw-Hill, New Delhi, 1995.
- R8- Roberts, Edward B.(ed.), Innovation: Driving Product, Process, and Market Change, San Francisco: Jossey Bass, 2002,

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



Program	me Cou	rse Code	Name of the Course	L	T	P	ϵ
B.E.	210	CE5602	SUSTAINABLE INFRASTRUCTURE DEVELOPMENT	3	0	0	3
Cours Objecti	ive	To examine to To learn the constraints To explore the	wledge on concepts and socio-economic policies of sustain he strategies for implementing sustainable development p various sustainability and performance indicators, their a he different approaches for resource management for a sus d the principles of urban planning and built-in environme	orogrammes assessment stainable urb	techn	iiques	
Unit			Description			tructic Hours	
I	Definitions of Sustainal environmen approach to	and principles ble Developmo t – Millenniu development p	USTAINABLE DEVELOPMENT of Sustainable Development - History and emergence of the cent - Environment and Development linkages- Globalizm Development Goals: Status (global and Indian) Irresolicy and practice in India, future directions. STAINABILITY	zation and		9	
Ш	Land, Wate	er and Food	production - Moving towards sustainability: Energy Financing the environment and Sustainable Developmen			9	
III	Sustainabilit prerequisite developmen	s for sustaina t – Performa	ICATORS - Hurdles to Sustainability-Operational Guidelines-Interable development - Science and Technology for since indicators of sustainability and Assessment med resustainable development.	ustainable		9	
IV	Environmen Region, Managing th	t and Resourc	D ENVIRONMENT es, Sustainability Assessment, Future Scenarios, Form grated Planning, Sustainable Development.	of Urban		9	
V	Urban Form	, Land Use, Contegrated Urb	ompact Development, Principles of street design- comple an land use Planning, Guidelines for Environmental			9	
Course Outcom	The st CO1: 1 CO2: 1 CO3: 0 constraint	udents will be a Describe the confidence and Comprehend that the confidence and comprehend that the confidence are the confiden	Total Instruction able to: oncepts and socio-economic policies of sustainable developmentify the strategies for implementing sustainable development various sustainability and performance indicators, their ferent approaches for resource management for a sustaina	opment. lopment pro assessment	techr	iques	and

REFERENCE BOOKS:

R1. Gilg A W and Yarwood R," Rural Change and Sustainability-Agriculture, the Environment and Communities", CABI Edited by S J Essex, September 2005.

R2. Ganesha Somayaji and Sakarama Somayaji, "Environmental Concerns and Sustainable development: Some perspectives from India", Editors: publisher TERI Press, ISBN 8179932249.

R3. James H. Weaver, Michael T. Rock, Kenneth Kustere, "Achieving Broad-Based Sustainable Development: Governance, Environment, and Growth with Equity", Kumarian Press, West Hartford, CT. Publication Year, 1997.

R4. Kirkby. J, O'Keefe P. and Timberlake, "Sustainable development" Earth Scan Publication, London, 1996.

CO5: Illustrate the principles of urban planning and built-in environment.

R5. Kerry Turner. R, "Sustainable Environmental Management", Principles and Practice Publisher: Belhaven Press, ISBN:1852930039.

R6. Munier N, "Introduction to Sustainability", Springer2005

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS
Dean (Academics)
HICET

HONOURS DEGREE SEM 5

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HICET



DEAN ACADEMICS

Dean (Academics)

HiCET

Pro	gramı	ne	Course code	Name of the course	L	T	P	C
	B.E		21MT5204	CONCEPTS OF MACHINES AND MECHANISMS	3	0	0	3
		•	The student s	should be made				
			l Identify va	rious links in popular mechanisms				
c	Course			ne friction forces required to hold a system in static and dyna		nditi	on.	
	ojectiv	۰.		d the function of a flywheel and plot the various position of o	erank			
	Jecur	2		e Gyroscopic couple in different conditions				
		-	5 Identify the	e governors of different applications				
Unit				Description			tructi	
	LZINII	3 M A 5	FIC OF MEC				Hour	·s
			FIC OF MEC		٠.			
I				ions of Mechanism – Planar Mechanism – Spherical Mecha			0	
			· mechanism	dundant Parallel Mechanism - Velocity and Acceleration Po	iygons		9	
	FRIC							
				of Friction - Angle of Response - Minimum Force required t	o clide			
H				ontal and inclined plane - Screw Friction and Screw Jack - 7			9	
				the load by screw jack	orque			
				DIAGRAM & FLYWHEELS				
				m for Single Cylinder Double acting steam Engine, Four	Stroke			
Ш				ion Engine and Multi cylinder Engine – Fluctuation of En			9	
				f Punching Press	0,			
	GYR	osco	OPIC COUP	LE				
IV	Proces	ssiona	ıl Angular M	Motion - Gyroscopic couple - Effect of Gyroscopic coup	ole on			
1 V	Aerop	lane -	Effect of Gy	roscopic Couple on Ship - Stability of Four Wheel Drive M	loving		9	
	in a C	urved	Path - Stabili	ity of Two Wheel Vehicle Taking a turn				
	GOV							
V				ce Analysis of Porter and Hartnell Governors - Controlling F			9	
	Stabil	ity – S	Sensitiveness -	- Isochronism - Effort and Power of Porter and Hartnell Gove	rnors.			
		22.		Total Instructional l	Hours		45	
				working of different mechanism				
				etion as a force that impedes motion.				
		CO3		nerous factors to design an appropriate flywheel for the eng	ine to	mini	mize	the
Outo		CO4		variance during each cycle				
				knowledge of gyroscopic couple in engineering application	3			
TEV	T BO		10 recognise	the different types of governors and their applications				
			Pennock G R	R and Shigley, J.E., "Theory of Machines and Mechanisms"	Ovfo	ed H		
	Press,			and singley, s.e., Theory of Machines and Mechanisms	, Oxio	iu Oi	nvers	sity
				nics of Machines", Narosa Publishing House, 3rd edition 20	19			
				Machines", 14h Edition, S Chand, 2020.				
	EREN			,				
				Machines", Laxmi Publications Pvt Ltd., New Delhi, 20th ed	lition (2009		
D.O	D	0.0	(T) (N)	A 1' M At Ell' E NO NEW 2004				

CHAIRMAN, BOARD OF STUDIES

Chairman - Bos MCT - HICET

R2 Rattan, S.S, "Theory of Machines", 4th Edition, Tata McGraw-Hill, 2014.

Applications" Tata, McGraw-Hill Education Pvt Limited 2ndEdition, 2012.



M.P.Groover, M.Weiss ,R.N. Nagal, N.G.Odrey, "Industrial Robotics - Technology, programming and

DEAN ACADEMICS

	,		Nagarita anno anno anno anno anno anno anno an		Марр	ing of C	COs wit	h POs a	nd PSO	S				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1	PO1	PSO-1	PSO-2
CO1	3		3		Titlife range on addition				1	-		1	2	
CO2	3	2	A STATE OF THE STA							1			2	
CO3	1	. 3	2	The state of the s								ı	1	
CO4	1	1	2									. 1	1	
CO5	3	1	I	The state of the s	r							1]	
AVG	2.2	1.4	1.8	-	-	-	-	-	0.2	0.4	-	0.8	1.4	

• 1-low. 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - Bos MCT - HiCET



DEAN ACADEMICS

Dean (Academics)

HiCET

Programme	Course code	Name of the course	L	T	P	C
B.E	21MT5205	ROBOTICS IN MEDICINE	3	0	0	3
	The student shoul	d be made				
	1 Identify and des	cribe different types of medical robots and their pote	ential app	licati	ions.	
		cepts in kinematics. Dynamics, and control relevant				es :
Course Objective	Develop the An	alytical and Experimental skills necessary to Design oth minimally invasive surgery and Image guided in	and Imp	leme		
Objective		n the state of the art in applied medical robotics and			ics	
	5 Understand the	various roles that robotics can play in healthcare.				

Unit	Description	Instructional Hours
	INTRODUCTION	
I	Types of medical robots - Navigation - Motion Replication - Imaging - Rehabilitation and Prosthetics - State of art of robotics in the field of healthcare - DICOM	9
	LOCALIZATION AND TRACKING	
II .	Position sensors requirements - Tracking - Mechanical linkages - Optical - Sound based - Electromagnetic - Impedance-based - In-bore MRI tracking-Video matching - Fiber optic tracking systems - Hybrid systems	.9
	DESIGN OF MEDICAL ROBOTS	
Ш	Characterization of gestures to the design of robots - Design methodologies - Technological choices - Security.	9
	SURGICAL ROBOTICS	
IV -	Minimally invasive surgery and robotic integration - surgical robotic sub systems - synergistic control - Control Modes - Radio surgery - Orthopedic Surgery - Urologic Surgery and Robotic Imaging - Cardiac Surgery - Neurosurgery - case studies	9
	ROBOTS IN REHABILITATION AND MEDICAL CARE	
V	Rehabilitation for Limbs - Brain-Machine Interfaces - Steerable Needles - Assistive robots - Robots in Physiotherapy - case studies	9
	Total Instructional Hours	45
	CO1 Identify various medical robots and their potential applications	
	CO2 Recognize the position tracking and hybrid systems.	•
Cou	arse CO3 Apply Robotics and its concepts in Medical field	

TEXT BOOK:

T1 Achim Ernst FlorisSchweikard, "Medical Robotics", Springer, 2016.

Medical care

T2 Paula Gomes, "Medical robotics Minimally invasive surgery", Wood head, 2013

REFERENCES.

R1 Jaydev P Desai, Rajni V Patel, Antoine Ferreira; Sunil Kumar Agrawal, "The Encyclopedia of Medical Robotics", World Scientific Publishing Co. Pvt. Ltd, 2019.

Outcome CO4 Simulate a MIS procedure and be aware of the state of art in surgical and oncology robotics.

CO5 Design a medical robotic system given the specific requirements for Rehabilitation and

- R2 Jocelyne Troccaz, "Medical Robotics", John Wiley & Sons Incorporated, 2013.
- R3 VanjaBonzovic, "Medical Robotics", I-tech Education publishing, Austria, 2008.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

			Y-00-	****	Марр	oing of C	COs wit	h POs a	nd PSO	15				
CO/PO	PO1	PO2	РОЗ	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1	PO1	PSO-1	PSO-2
CO1	1		2						-	1	1	1		1
CO2	1		3							*		1		2
CO3			2		1									2
CO4	No.	177	3		-		·							3
CO5	1		-		-	-						1		1
AVG	0.6	-	2.2	-	0.2	-	-		0.2	0.2	0.2	0.6	-	1.8

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES
CHAIRMAN, BOARD OF STUDIES
MCTHIHLET



DEAN ACADEMICS

Pro	gramn	ie	Course code	Name of the course	L	Т	Р	C
	B. E		21MT5206	ROBOTS AND SYSTEMS IN SMART MANUFACTURING	3	0	0	3
	ourse jective	1 2	To enlist wit To familiar's To impart the		ling capaci	ty		
Unit				Description			Instruc	
I	Type hand	s of i	naterial transfer	- Load handling capacity - general considerations in Rc - machine loading and unloading - CNC machine tool lo	obotic mate ading – Re	erial obot	Hor	
П	SEL Facto Impa weldi	ECT ors inf ct of ing - S	ION OF ROBO luencing the chrobot on industrial	TTS AND OTHER APPLICATIONS Dice of a robot - robot performance testing - economics of ry and society. Application of Robots in continuous are wassembly operation - cleaning - robot for underwater applic	velding - S	on - Spot	9	
Ш	Conc conve conve vehic	epts o ention eyor s le sys	f material hand al material han systems -cranes	ing - principles and considerations in material handling systems - industrial trucks - monorails - rail guid and hoists - advanced material handling systems - autoed storage and retrieval systems(ASRS) - bar code techn	led vehicle	es - ided	12	2
IV	ROB Robo Penda robot APPI Appli Robot solder	otic we not Lication well cation as for ring —	EWELDING elding system, and through proding, Welding strions OF RO of robot in macar body's weld Applications in	Programmable and flexible control facility –Introduction gramming, Operating mode of robot, Jogging-Types, projection, Welding sequences. Profile welding BOTS IN WELDING AND ALLIED PROCESSES unufacturing: Exploration of practical application of robot ling, robots for box fabrication, robots for microelectronic nuclear, aerospace and ship building, case studies for simple	gramming ts in weldi	for ing:	8	
	applic	CO1	To Recognize	Total Instructions concepts of Industrial Robot.	ctional Ho	urş	45	
Cou Outc	ome	CO3 CO4	To Apply various To Learn about	oppropriate manufacturing procedure for Robots us manufacturing process in Robot manufacturing. the Welding operation and also related to Programming nanufacturing plan for developing a robot				
	BOOF	ζ:				_		
T1	Prenti	ce Ha	II India, New De					
T ₂ 2	Mikel Educa	P (tion, l	Groover, "Aut New York, 2019	omation, Production Systems, and Computer-Integrated	l Manufac	turin	g", Pea	rson

\mathbf{T}

- T
- Pires J N, Loureiro A, Bolmsjo G, "Welding Robots: Technology, System Issues and Application", Springer. London, 2010.

REFERENCES:

- Parmar R S, "Welding Processes and Technology", Khanna Publishers, New Delhi, 2nd Edition, 2013.
- John A. piotrowski, William T. Randolph, "Robotic welding: A Guide to Selection and Application, Welding Division, Robotics International of SME", Publications Development, Marketing Division, 1987.
- YoramKoren, "Robotics for Engineers", McGraw-Hill, 1987. R3
- Mikell P Groover, Mitchel Weiss, Roger N Nagel, N.G.Odrey, AshishDutta , "Industrial Robotics (SIE): Technology, Programming and Applications", 2nd Edition, McGraw Hill Education India Pvt Ltd, 2012.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



DEAN ACADEMICS Dean (Academies) HiCET

	**	VI			Марр	ing of C	COs wit	h POs a	nd PSO	ıs				
CO/PO	POI	PO2	PO3	PO4_	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1	PSO-1	PSO-2
CO1	1		2		Andread and a second a second and a second a			The state of the s		1	1	1		1
CO2	1		3	-							The state of the s	1		2
CO3			2		, 1									2
CO4	THE PERSON NAMED IN COLUMN NAM		- 3											3
CO5	ı		1									1		1
AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	-	1.8

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAD ACADEMICS (Academics)
HiCET

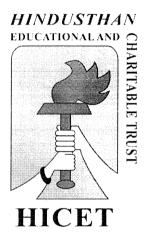
HINDUSTHAN COLLEGE OF ENGINEERING AND TECHNOLOGY

(An Autonomous Institution Affiliated to Anna University, Chennai)

(Approved by AICTE, New Delhi, Accredited by NAAC with 'A' Grade)

Coimbatore - 641 032.

B.E. MECHATRONICS ENGINEERING



CHOICE BASED CREDIT SYSTEM

Revised Curriculum and Syllabus for the odd semester

Academic year 2023-24

(Academic Council Meeting Held on 19.06.2023)



CURRICULUM R2019





Hindusthan College of Engineering and Technology

(An Autonomous Institution, Affiliated to Anna University, Chennai Approved by AICTE, New Delhi& Accredited by NAAC with 'A' Grade) Valley Campus. Pollachi Highway, Coimbatore, Tamil Nadu.



DETAILS OF CHANGES CARRIED OUT IN CURRICULUM & SYLLABUS

CBCS PATTERN

UNDERGRADUATE PROGRAMMES

B.E. MECHATRONICS ENGINEERING (UG)

REGULATION-2019

For the students admitted during the academic year 2020-2021 and onwards

SEMESTER I

S.No.	Course Code	Course Title	Type	L	T	P	C	ClA	ESE	TOTAL
		ТНЕО	RY	-						
1.	19HE1101	Technical English	HS	2	1	0	3	25	75	100
2.	19MA1102	Calculus and Linear Algebra	BS	3	1	0	4	25	75	100
		THEORY & LAB	COMPON	ENT			-			
3.	19PH1151	Applied Physics	BS	2	0	2	3	50	50	100
4.	19CY1151	Chemistry for Engineers	BS	2	0	2	3	50	50	100
5.	19CS1151	Python Programming and Practices	ES	2	0	2	3	50	50	100
6.	19ME1152	Engineering Drawing	ES	1	0	4	3	50	50	100
		PRACTI	CAL		4	l	* 7			
7.	19HE1071	Language Competency Enhancement Course-I	HS	0	0	2	1	100	0	100
		MANDATORY	COURSE	S	-					
8.	19HE1072	Career Guidance Level – I Personality, Aptitude and Career Development	EEC	2	0	0	0	100	0	100
9.	19HE1073	Entrepreneurship & Innovation	EEC	1	0	0	0	100	0	100
			Total:	15	2	11	20	550	350	900
	As Per AICTE N	Norms 3 Weeks Induction Programme i	s Added i	n The	First	Sem	ester	as an Au	ıdit Cou	rse

SEMESTER II

S.No.	Course Code	Course Title	Type	L	T	P	С	CIA	ESE	TOTAL
		THE	ORY			L				
1.	19HE2101	Business English for Engineers	HS	2	1	0	3	25	75	100
2.	19MA2101	Differential Equations and Complex Variables	BS	3	1	0	4	25	75	100
3.	19ME2101	Engineering Mechanics	ES	3	0	0	3	25	75	100
		THEORY & LAB	COMPO	NENT	7					
4.	19PH2151	Material Science	BS	2	0	2	3	50	50	100
5.	19CY2151	Environmental Studies	BS	2	0	2 ·	3	50	50	100



6.	19MT2153	Basics of Mechatronics Engineering	ES	2	0	2	3	50	50	100
		PRACTI	CALS		i		L	1	L	
7.	19ME2001	Engineering Practices Laboratory	ES	0	0	4	2	50	50	100
8.	19HE2071	Language Competency Enhancement Course-II	HS	0	0	2	1	100	0	100
		MANDATORY	COURS	ES	1	I	1			
9.	19HE2072	Career Guidance Level – II Personality, Aptitude and Career Development	EEC	2	0	0	0	100	0	100
			Total:	16	2	11	22	475	425	900

SEMESTER II

		SEMEST	EKIII							
S.No	Course Code	Course Title	Type	L	T	P	C	CIA	ESE	TOTAL
		THEO	ORY				-			
1.	19MA3101	Fourier Series and Statistics	BS	3	1	0	4	25	75	100
2.	19MT3201	Mechanics of solids	PC	3	1	0	4	25	75	100
3.	19MT3202	Industrial Motor Control	PC	3	0	0	3	25	75.	100
4.	19MT3203R	Digital Electronics in Mechatronics Systems	PC	3	0	0	3	25	75	100
		THEORY AND LA	В СОМР	ONEN	ΥТ	L		1	<u> </u>	
5.	19MT3251R	Production Technology	PC	2	0	2	3	50	50	100
-		PRACTI	CALS	-		1	1	1		
6.	19MT3001	Computer Aided Drafting Laboratory	PC	0	0	3	1.5	50	50	100
7.	19MT3002R	Industrial Motor Control Laboratory	PC	0	0	3	1.5	50	50	100
		MANDATORY	COURS	ES						
8.	19MC3191	Indian Constitution	MC	2	0	0	0	100	0	100
		Career Guidance Level – III							-	700
9.	19HE3072	Personality, Aptitude and Career Development	EEC	2	0	0	0	100	0	100
10.	19HE3073	Leadership Management Skills	EEC	1	0	0	0	100	0	100
	-	-	Total	19	2	8	20	550	450	1000

SEMESTER IV

S.No	Course Code	Course Title	Туре	L	T	P	С	CIA	ESE	TOTAL
			THEORY							
1.	19MA4101	Numerical Methods	BS	3	1	0	4	25	75	100
2.	19MT4201R	Microcomputer Systems and Microcontroller	PC	3	0	0	3	25	75	100
3.	19MT4202	Thermodynamics and Fluid Engineering	PC	3	1	0	4	25	75	100
4.	19MT4203R	Theory of Machines	PC	3	1	0	4	25	75	100



		THEORY AND	LAB CON	APON	ENT		The second secon		er en	
5.	19MT4251	Sensors and Signal Conditioning	PC	2	0	2	3	50	50	100
		PRA	CTICALS			-				
6.	19MT4001R	Assembly Programming and Interfacing Laboratory	PC	0	0	3	1.5	50	50	100
7.	19MT4002	Solid and Fluid Mechanics & Machinery Laboratory	PC	0	0	3	1.5	50	50	100
		MANDATO	ORY COU	RSES					·	
8.	19MC4191	Essence of Indian tradition knowledge Value Education	MC	2	0	0	0	100	0	100
9.	19HE4072	Career Guidance Level - IV Personality. Aptitude and Career Development	EEC	2	0	0	0	100	0	100
10.	19HE4073	Ideation Skills	EEC	1	0	0	0	100	0	100
			Total	18	3	8	21	450	450	900

SEMESTER V

S.	Course	Course Title		T.		Τ_		T.,		
No	Code	Course Title	Category	L	T	P	C	CIA	ESE	Total
1.	19MT5201	Machine Design	PC	3	l	0	4	25	75	100
2.	19MT5202	Industrial Automation and Control	PC	3	0	0	3	25	75	100
3.	19MT5203	Control of Mechatronics Systems	PC	3	0	0	3	25	75	100
4.	19MT53XX	Professional Elective - I	PE	3	0	0	3	25	75	100
		THEORY AND LAB C	OMPONENT		L	1				
5.	19MT5251	Fluid Power Systems	PC	2	0	2	3	50	50	100
6.	19MT5252	Object Oriented Programming	PC	2	0 .	2	3	50	50	100
		PRACTICAL	LS							
7.	19MT5001	Computer Aided Machine Drawing Laboratory	PC	0	0	3	1.5	50	50	100
8.	19MT5002	Industrial Automation and Control Laboratory - I	PC	0	0	3	1.5	50	50	100
	,	MANDATORY CO	URSES							
9.	19HE5071	Soft Skills - I	EEC	1	0	0	1	25	75	100
10.	19HE5072	Design Thinking	EEC	1	Ó	0	1	25	75	100
			TOTAL	18	1	10	24	500	500	1000



SEMESTER VI

		SEMESTER VI	·		T	,	Υ	T		,
S. No	Course Code	Course Title	Category	L	T	P	С	CIA	ESE	Total
		THEORY								
1.	19MT6181	Total Quality Management	HS	3	0	0	3	25	75	100
2.	19MT6201	Design of Mechatronics Systems	PC	3	0	0	3	25	75	100
3.	19MT6202R	CNC Technology	PC	3	0	0	3	25	75	100
4.	19MT63XX	Professional Elective - II	PE	3	0	0	3	25	75	100
5.	19XX6401	Open Elective – I	OE	3	0	0	3	25	75	100
		THEORY AND LAB COM	PONENT		•			•		
6.	19MT6251	Vetronics	PC	2	0	2	3	50	50-	100
		PRACTICALS								
7.	19MT6001	CNC Laboratory	PC	0	0	3	1.5	50	50	100
8.	19MT6002	Industrial Automation and Control Laboratory - II	PC	0	0	3	1.5	50	50	100
9.	19MT6701	Inplant Training / Internship *	EEC	0	0	0	1	100	0	100
		MANDATORY COUR	SES							
10.	19HE6071	Soft Skills - II	EEC	1	0	0	1	25	75	-100
11.	19HE6072	Intellectual Property Rights(IPR)	EEC	1	0	. 0	1	25	75	100
			TOTAL	19	0	8	24	575	525	1100

S.No.	Course Code	Course Title	Type	L	Т	P	C	CIA	ESE	TOTAL
		PROFESSIO	ONAL ELI	ECTIV	ΈI					
1.	19MT5301	Engineering Metrology and Measurements	PE	3	0	0	3	25	75	100
2.	19MT5302	Non-Traditional Machining Techniques	PE	3	0	0	3	25	75	100
3.	19MT5303	Automobile Systems	PE	3	0	0	3	25	75	100
4.	19MT5304	Operational Research	PE	3	0	0	3	25	75	100
5.	19MT5305	Materials Science and Applications	PE	3	0	0	3	25	75	100
		PROFESSION	NAL ELEC	CTIVE	П					
1.	19MT6301	Embedded System	PE	3	0	0	3	25	75	100
2.	19MT6302	Discrete Event System Simulation	PE	3	0	0	3	25	75	100



3.	19MT6303	Product Design and Development	PE	3	0	0	3	25	75	100
4.	19MT6304	Non-Destructive Testing Techniques	PE	3	0	. 0	3	25	75	100
5.	19MT6305	Distinctive Electrical Machines	PE	3	0	0	3	25	75	100

OPEN ELECTIVE

S.No.	Course Code	Course Title	Type	L	Т	P	С	ClA	ESE	TOTAL
1.	19MT6401	Industrial Safety and Environment	OE	3	0	0	3	25	75	100

SEMESTER VII

S. No	Course Code	Course Title	Category	L	T	P	С	CIA	ESE	Total
		THEORY				-		-		
1.	19MT7201	Virtual Instrumentation and Human Machine Interface	PC	3	1	0	4	25	75	100
2.	19MT7202	Machine Vision Systems	PC	3	0	0	3	25	75	100
3.	19MT73XX	Professional Elective - III	PE	3	0	0	3	25	75	100
4.	19XX7401	Open Elective – II	OE	3	0	0	3	25	75	100
		THEORY AND LAB COM	PONENT		<u> </u>					
5.	19MT7251	Industrial Robotics	PC	2	0	3	3.5	50	50	100
		PRACTICALS						1	1	
6.	19MT7001	CAE Laboratory	PC	0	0	3	1.5	50	50	100
		PROJECT WORK					L	<u> </u>		
7.	19MT7901	Project Phase – I	EEC	0	0	4	2	100	0	100
			TOTAL	14	1	10	20	300	400	700

PROFESSIONAL ELECTIVE III

S.No.	Course Code	Course Title	Type	L	T	P	С	CIA	ESE	TOTAL
1.	19MT7301	Mobile Robotics	PE	3	0	0	3	25	75	100
2.	19MT7302	Textile Automation	PE	3	0	0	3	25	75	100
3.	19MT7303	Medical Mechatronics	PE	3	0	0	3	25	75	100
4.	19MT7304	Disaster Management	PE	3	0	0	3	25	75	100
5.	19MT7305	Factory Automation	PE	3	0	0	3	25	75	100



OPEN ELECTIVE

S.No.	Course Code	Course Title	Type	L	T	P	C	CIA	ESE	TOTAL
1.	19MT7401	Project Management	OE	3	0	0	3	25	75	100

SEMESTER VIII

S.No	Course Code	Course Title	Туре	L	T	P	C	CIA	ESE	TOTAL
			THEORY		-					
1.	19MT83XX	Professional Elective - IV	PE	3	0	0	3	25	75	100
2.	19MT83XX	Professional Elective - V	PE	3	0	0	3.	25	75	100
		PI	RACTICAL	,				L		
3.	19MT8901	Project Phase – II	EEC	0	0	16	8	100	0	100
			Total	6	0	16	14	150	150	300

		Rapid Prototyping and							T -	100
1.	19MT8301	Reverse	PE	3	0	0	3	25	75	
		Engineering							, ,	100
		Introduction to Industry 4.0								
2.	19MT8309	and Industrial Internet of	PE	3	0	0	3	25	7.5	100
		Things (NPTEL)		-						
		Artificial Intelligence								
3.	19MT8303	for Mechatronics	PE	3	0	0	3	25	7.5	100
		Engineering								100
4.	19MT8304	MEMS and Nano	D.E.	2		_			 	-
7.	17/11/03/04	Technology	PE	3	0	0	3	25	75	100
5.	10MT9305	Information System for	DE			_		-		
<i>J</i> .	. 19MT8305	Engineers	PE	3	0	0	3	25	75	100

	PROFESSIONAL ELECTIVE V												
S.No.	Course Code	Course Title	Type	L	Т	P	С	CIA	ESE	TOTAL			
1.	19MT8306	Machineries in Agriculture	PE	3	0	0	3	25	75	100			
2.	19MT8307	Industrial Diagnostics and Maintenance Techniques	PE	3	0	0	3	25	75	100			
3.	19MT8308	Engineering Economics and Cost Analysis	PE	3	0	0	3	25	75	100			
4.	19MT8181	Principles of Management	PE	3	0	0	3	25	75	100			
5.	19MT8182	Professional Ethics in Engineering	PE	3	0	0	3	25	75	100			



		LIFE S	KILL COU	RSES						
1.	19LSZ401	General Studies for Competitive Examinations	OE	3	0	()	3	25	75	100
2.	19LSZ402	Human Rights, Women's Rights and Gender Equality	OE	3	0 .	0	3	25	75	100
3.	19LSZ403	Indian Ethos and Human Values	OE	3	0	0	3	25	75	100
4.	19LSZ404	Indian Constitution and Political System	OE	3	0	0	3	25	75	100
5.	19LSZ405	Yoga for Human Excellence	OE	3	0	0	3	25	75	100

SEMESTER-WISE CREDIT DISTRIBUTION

			S	RAMME	H. PROG	E. / B.TEC	В.		-	1101			
			r	er Semeste	Credits po				Course	S.No.			
	VIII	VII	VI	V	IV	III	IJ	I	Area	5.110.			
11	-	-	03	-	-	-	04	04	HS	1			
28	-	-	-	-	04	04	10	10	BS	2			
14	-	-	-	-	-	-	08	06	ES	3			
76		12	12	19	17	16	-	-	PC	4			
15	06	03	03	03	-	-	-	-	PE	5			
06	-	03	03	-	-	-	-	-	OE	6			
15	08	02	03	02	-	-	-	-	EEC	7			
165	Tatal 20 22 20 21 21												

CREDIT DISTRIBUTION R2019

Semester	I	II	III	IV	V	VI	VII	VIII	Total	1
Credits	20	22	20	19	24	24	20	14	165	1

Dean Academics

Chairman - BoS MCT - HiCET



Programme BE	Course Code Name of the Course L 19MT7201 VIRTUAL INSTRUMENTATION AND HUMAN 3 MACHINE INTERFACE	1			4
Course Objective	 Understand the basic components of virtual instrumentation system To develop a VI program using various techniques Identify elements of data acquisition for software and hardware installation To gain the knowledge about different types of common instrument interfaces To learn to develop applications based on virtual instrumentation system 				
Unit	Description]	Instruct Hou		ıal
I	VIRTUAL INSTRUMENTATION Conventional and Distributional Virtual Instrumentation(VI) - VI Vs Traditiona Instruments - Block Diagram and Architecture of a Virtual Instrument - Hardware and Software in VI - Virtual instrumentation for Test, Control and Design - Virtual instrument in Engineering Process - Graphical Programming in Data Flow - HMI /		9+3		
II	SCADA Software. VI PROGRAMMING TECHNIQUES Controlling Programs through Structures: For loops and While loops - Case and Sequence Structures: Flat sequence and Stacked sequence - Shift Register - Feedback Nodes - Formula Nodes - Arrays - Clusters - Error Handling - Waveform Charts and Waveform Graphs - XY Graphs - Strings - File I/O. DATA ACQUISITION BASICS	ĸ	9+	3	
· III	Concepts of Data Acquisition - Data Acquisition in LabVIEW - Hardware Installation and Configuration - Components of DAQ - DAQ Signal Accessory - DAQ Assistant - DAQ Hardware - DAQ Software. INTERFACING		9+3	3	
IV	Common Instrument Interfaces: RS 232 / RS485 - GPIB - VISA standard - Bus Interfaces: USB-PCI - PCI - X - PXI - PCMCIA - SCXI-VXI - LXI.		9+3	3	
	APPLICATIONS Application of Virtual Instrumentation: Digital Stop Watch using Lab VIEW - BCD t Seven Segment Decoder - Cruise Control - PID Controller - Client Server Application				
V	in LABVIEW - Notifiers, Simple Read Only Server, Two Way Communication, Rea Write Server.		9+3	3	
	The students can design anyone of the following 1. Design a Simulator Barometer using LabVIEW. 2. Design a LabVIEW Program to Simulate Virtual Joystick.				
	Total Instructional Hour	S	45+15	=60)
Course Outcome	On completion of the course the students will be able to CO1: Demonstrate the basic concepts about virtual instrumentation CO2: Develop programming through LabVIEW graphical programming environment CO3: Experiment with data acquisition hardware and LabVIEW software CO4: Apply the knowledge of common instrument interfaces and bus interfaces CO5: Design and develop the industrial applications using LabVIEW	nt			

TEXT BOOKS:

- T1- Jovitha Jerome, "Virtual Instrumentation using LabVIEW", PHI Learning Private Limited, 2012.
- T2- S.Sumathi&P.Surekha, "Virtual Instrumentation with LabVIEW", ACME Learning Private Limited, 2011.

REFERENCE BOOKS:

- R1- Sanjay Gupta & Joseph John, "Virtual Instrumentation using LabVIEW", McGraw Hill Education, NewYork, 2010.
- R2- Gary Johnson & Richard Jennings, "LabVIEW Graphical Programming", 4th Edition, McGraw Hill Education, NewYork, 2006.
- R3- Jeffrey Travis & Jim Kring, "Labview for Everyone", PHI Learning Private Limited, 3rd Edition, 2007.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



	_	-			Марр	oing of C	Os wit	h POs a	nd PSO	s				
СО/РО	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1	PSO-1	PSO-2
CO1	3				1							1	3 -	2
CO2	3	3	3	2	1		To the state of th	3	2		2	2	2	2
CO3	3	3	3	2	2			2	3			2	2	2
CO4	3				2				2			2	1	2
C05	. 3	3	3	2	2			1	2		2	2	- 2	2
AVG	3	1.8	1.8	1.2	1.6			1.2	1.8	_	0.8	1.8	2	• 2

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Programme BE	Course Code 19MT7202	Name of the Course MACHINE VISION SYSTEM	L 3	T 0	P 0	C 3
Course Objective	 To study To review To study 	be known basic principles of Machine Vision System the Image Acquisition and Lighting techniques Image processing techniques for Computer Vision Mathematical Transforms necessary for Image Processing. Some applications of Machine Vision Algorithms				,
Unit		Description			tructio Hours	
I	INTRODUCTION Human vision – Ma Block diagram and Machine Vision Sys IMAGE ACQUISI		ision – Iustrial		9	
II	Lighting Technique Specifications and Interface Architectu	s – Types and Selection – Machine Vision Lenses and Opt Selection – Imaging Sensors – CCD and CMOS, Speci res – Analog and Digital Cameras – Digital Camera Computer Interfaces.	ical Filters, fications –		9	
III	Fundamentals of Di Thresholding- Gray Detection – Binary	gital Image – Spatial and Frequency Domain – image segrescale Stretching –Image Smoothing and Sharpening – Edge Morphology.	nentation- e		9	
IV	Template Matching Making.	 Region Features, Shape and Size Features - Texture and Classification - 3D Machine Vision Techniques 	Analysis – – Decision		9	
. V	Machine vision App	N APPLICATIONS olications in Manufacturing, Electronics, Printing. Pharmac s in Metrology and Gauging–Bio medical Field, Surveillar	nce, Bio-		9	
		Total Instructio	nal Hours		45	
Course Outcome	CO1: Impleme CO2: Evaluate CO3: Develop CO4: Interpret	the course the students will be able to the fundamental required for Machine Vision the techniques for Camera Lighting Interface. Image Processing techniques for Machine Vision System Image Segmentation and Representation Techniques an applications using Machine Vision Techniques				

T1- A. Alexander Hornberg, "Handbook of Machine Vision", First Edition, 2006.

Milan Sonaka, Vaclav hlavac, Roger Boyle, Image processing, analysis and machine vision" First edition 2007.

REFERENCE BOOKS:

R1- E.R.Davies, "Machine Vision", Third edition, 2006.

Rafael C.Gonzales, Richard.E. Woods, "Digital Image Processing Publishers", Fourth Edition 2007. R2-

Emanuel Trucco, Alessandro Verri, "Introductory Techniques for 3D computer vision", 1st Edition, PHI Learning Private R3-

Herbert Freeman, "Machine Vision Algorithms, Architecture and Systems", Academic Press, Inc. 2012. R4-

CHAIRMAN, BOÁRD OF STUDIES

Chairman - BoS MCT - HICET



DEAN ACADEMICS Dean (Academics)
HiCET

anners de serviciones de la companya de la company	-			,	Марр	ing of C	Os witl	i POs a	nd PSO	s				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1	PO1 2	PSO-1	PSO-2
CO1	3		2		3	The second secon			3	3	3	3	1	1
CO2	1		3	·					1	l	1	1	2	1
CO3	1		2		3				1	1	1	1	2	2
CO4	1	-	3										3	2
CO5	1		1									1	1	2
AVG	1.4	-	2.2	-	1.2	-	-	-	1	1	1	1.2	1.8	1.6

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Program BE	ıme	Course Code 19MT7251	Name of the Course INDUSTRIAL ROBOTICS	L 2	T	P	C
				2	U	3	3.5
_		1. To outline the evolu-	ution of robots and its anatomy				
Cours Objecti		3. To illustrate the pri	ious kinematics and inverse kinematics of robot motions neiple of robot end effectors				
Objecti	• •	4. To acquire knowled	dge about basics of robot programming				
		5. To discuss the appl	ications of robots in industries				
Unit			Description			tructio Hours	
		FUNDAMENTALS (
I		Robot Coordinates - W Robot Actuators and Di ROBOT KINEMATI	ICS	es.		6	
II		Introduction to Robot k - Denavit - Hartenberg Planning.	inematics - Homogeneous Transformations - Forward Kiner (D-H) Representation - Inverse kinematics. Basics of Tra	natics ejectory		6	
		ROBOT END EFFEC					
III		Robot End effectors: In	troduction - Types of End Effectors - Mechanical Gripper	- Types		6	
		Considerations - Tools a ROBOT PROGRAM!	- Other Types of Grippers - Special Purpose Grippers - as End Effector - Robot End Effector Interface. MING	Design		O	
IV		- Classification of Robo	pes – Lead through and Textual Programming – Robot Lang t Language - Computer Control and Robot Software.	uages		6	
		Val system and languag APPLICATIONS OF 1					
			ROBOT pots in Manufacturing and Non - Manufacturing Application				
V		Medical Applications -	Automation and Mechatronics Applications	IS -		6	
			Total Instructional H	ours		30	
c			LABORATORY COURSES				
	1	Programming for Point-to	-Point Operation and Continuous Path Operation.				
	2	Programming for Pick and	Place Operation with and without delay.				
	3	Programming for Estimati	on of Accuracy of a Robot.				
	4	Programming for Estimati	on of Repeatability and Resolution of a Robot.				
	5		on of work volume for different configuration of Robot.				
	6		and Unloading Operations with Different Cycles.				
	7	Create a Model to Find the	e Force in Spring Damper at Static Equilibrium and Simulate	eusing A	DAM	1S Soft	ware.
	8		fft Mechanism and then Set the Constraints of the Model an				
			Total Prac	tical Ho	urs 2	20	
			T	otal Ho	urs :	50	
		On completion of the cou	urse the students will be able to				
~			asic concepts and working of robot.				
Course		CO2. Amplements also les					

CHAIRMAN, BOARD OF STUDIES

Outcome

Chairman - BoS MCT - HICET



CO2: Analyze the kinematics of robot motions for a given problem

CO5: Design a robot for real world problems and applications

CO4: Write programs for the given applications

CO3: Evaluate and construct a robot end effector for specific applications

T1 - Mikell P. Groover, Mitchell Weiss, Roger N. Nagel Nicholas G. Odrey, "Industrial Robotics Technology, Programming and Applications ", 2nd Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2012.

T2 - Saeed B.Niku "Introduction to Robotics: Analysis, Systems, Applications", 2nd Edition, John Wiley & Sons Ltd.. NewDelhi, 2012.

REFERENCE BOOKS:

R1- Deb. S.R., "Robotics Technology and Flexible Automation". 2nd Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2010.

R2- Klafter R.D., Chimielewski T.A., Negin M., "Robotic Engineering - An integrated approach", PHI Learning Private Limited, New Delhi, 2003.

R3- Fu K.S. Gonzaleaz R.C. and Lee C.S.G., "Robotics Control Sensing, Vision and Intelligence", Tata McGraw Hill Publishing Company Limited, New Delhi, 2008. R4- John. J. Craig, "Introduction to Robotics: Mechanics & control", Pearson Publication, Fourth edition, 2018.

	-				Марр	ing of C	Os with	h POs a	nd PSO	s				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1	PO1 .	PSO-1	PSO-2
CO1	1		2						1	1	1	1		1
CO2	1		3									1		2
CO3			2		ı									2
CO4			3											3
CO5	1		1									1		1
AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	-	1.8

1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



Programme	Course code	Name of the course	L	T	P	C						
B.E	19MT7001	COMPUTER AIDED ENGINEERING LABORATORY	0	0	3	1.5						
	The student sh	ould be made										
	1 To introduce fi	undamentals of the analysis software, its features and a	applicatio	ns								
Connec	2 To learn the basics of Finite Element analysis.											
Course	3 To study the various failure modes of engineering components											
Objective		owledge on various loads and stresses acting on structu	ares and c	ompo	nents							
		students to different applications of simulation and ana										

Unit	Description	Instructional Hours
1	Stress analysis of a plate with a circular hole.	3
2	Stress analysis of rectangular L bracket	3
3	Stress analysis of an axi-symmetric component	3 ,
4	Stress analysis of Cantilever beam	3
5	Stress analysis of Simply supported beam	3
6	Stress analysis of Fixed beam	3
7	Mode frequency analysis of a 2D component	3
8	Mode frequency analysis of Cantilever beam	3
9	Mode frequency analysis of Aircraft wing	3
10	Thermal stress analysis of a 2D component	3
11	Conductive heat transfer analysis of a 2D component	3
12	Convective heat transfer analysis of a 2D component	3
	Total Instructional Hours	45
	CO1 Execute stress calculations for various load conditions	
Cou	CO2 Perform the stress and deformation analysis of different components	
Outco	ome CO3 Analyze and simulate deformation plot for structural and thermal loads	
	CO4 Model and analyze the real world system	
	CO5 Evaluate the performance of real world system	

		·			Марр	ing of C	COs with	h POs a	nd PSO	s				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1	PO1	PSO-1	PSO-2
CO1	2	2	2	2	2	2	2	2	2	2	2	2	1	1
CO2	3	1	2	1.	-	-	-	-	-	-		-	2	2
CO3	-	3	3	2	-	-	-	-	1	-	-	-	3	3
CO4	-	1	1	-	-	-	-	-	-	-	-	-	1	1
CO5	2	2	2	2	-	-	-	-	-	-	-	1	2	2
AVG	2.3	1.8	2	1.75	2	2	2	2	1.5	2	2	1.5	1.8	1.8
\				medium e averag					for pro	gram art	iculatio	n matrix	. /	

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS
Dean (Academics)
HiCET

LAB COURSES

Programme	Course Code	Name of the Course	L	T	P	C
BE	19MT7901	PROJECT PHASE I	0	()	4	2
Course Objective	literature review	ability to solve a specific problem right from its identitient till the successful solution of the same. lents in preparing project reports and to face reviews a				

The student in a group of 3 works on a topic approved by the head of the department under the guidance of a faculty member and prepares a comprehensive project report after completing the work to the satisfaction of the supervisor. The progress of the project is evaluated based on a minimum of three reviews. The review committee may be constituted by the Head of the Department. A project report is required at the end of the semester. The project work is evaluated based on oral presentation and the project report jointly by external and internal examiners constituted by the COE / Head of the Department.

Course On completion of the course the students will be able to in a position to take up any challenging practical problems and find solution by formulating proper methodology

CHAIRMAN, BOARD OF STUDIES

CHARAIL TAMS



DEAN ACADEMICS

Programme Bl:	Course Code 19MT7301	Name of the Course MOBILE ROBOTICS	L 3	Ť 0	P 0	3
Course Objective	 Develop the Path Identify the Robot Locate the Robot 	matic modeling of Mobile robots and Trajectory for the Robot t performance characteristics through Sensors and Mapping in Path Planning and Navigation				
Unit	·	Description		Inst	ructio	nal
	MOBILE ROBOT			l	lours	
·	Locomotion. Mobile Robo	n, Classification - Legged. Wheeled. Aerial. Key of Kinematics - Kinematic Model - Forward Kinem ion, Wheel Kinematic Constraints and Robot Kinem	natic		9	
	ROBOT MANEUVERAI	BILITY AND WORKSPACE				
Ii	Degree of Mobility - Degree Freedom - Holonomic Rob Open Loop Control and Fe PERCEPTION	ee of Steerability - Robot Maneuverability - Degrees ots - Path and Trajectory Considerations - Motion (edback Control.	of . Control -		9	
Ш	Range Sensors - Vision Sensors	- Classification, Performance, Uncertainty in Senso Accelerometers - Inertial Measurement - Motion isor - Basics of Computer Vision, Image Processing tion - Image, Range Data Location Recognition.	Sensor -		9	
IV	Major Challenges, Localiza Representation, Probabilist Map Building. PLANNING AND NAVIO	ation Based Navi <mark>gatio</mark> n. Belief Representation, Map ic Map - Examples of Localization Systems - Auton	omous		9	
V	Planning and Reaction - Pa	th Planning - Graph search, Potential field - Obstacl n, Histogram, Curvature Velocity Techniques - Nav	le igation		9	
Course Outcome	On completion of the cours CO1: Design and Modeli CO2: Model the Trajecto CO3: Interpret various Se CO4: Prepare Localizing CO5: Develop the Naviga	ry Path of the Robot nsors used for Perception and Mapping the Robot	al Hours		45	

- Siegwart, Nourbakhsh, "Introduction to Autonomous Mobile Robots", 2nd Edition, MIT Press, 2011.
- Siciliano. et.al, "Robotics: Modelling, Planning and Control". 4th Edition, Springer, 2013.

REFERENCE BOOKS:

- Choset Et. al, "Principles of Robot Motion: Theory, Algorithm & Implementations", 3rd Edition, MIT Press, 2011. R1-
- R2-Siciliano, Khatib, Eds., "Handbook of Robotics", 4th Edition, Springer, 2008.
- Thrun, Burgard, Fox, "Probabilistic Robotics", 1st Edition, MIT Press, 2010.
- Roland Siewart et al, "Introducton to Autonomous Mobile Robotics", 2nd Edition, PHI Learning Pvt Ltd, 2011.

WEB REFERENCES:

- http://www.intechopen.com/books/mobile robots current trends http://www.telegraph.co.uk/lifestyle/pets/10200202/Official studies strengthen case for electric collar ban saysdog - group.html
- http://cw.routledge.com/textbooks/eresources/9780750651868/casestudies 12.doc

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HICET



					Mapp	ing of C	Os wit	h POs a	nd PSO	S				
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1 2	PSO-1	PSO-2
CO1	1		2						1	1	ı	1		1
CO2	1		3	TOTAL	Market Control of the					The state of the s	- 100 C C C C C C C C C C C C C C C C C C	1	The state of the s	2
CO3			2		1									2
CO4		:	3				·							3
CO5	1		l											l
AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	-	1.8

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Programme BE	Course Code 19MT7302	Name of the Course TEXTILE AUTOMATION	L 3	T	P ()	C 3
Course Objective	2. To familiari3. To interpret4. To operate t	ize the Basic concepts and list the Basic proce ze with the Basics of Spinning the Basics of Weaving Process and its Variab he Automated Spinning Machines he knowledge about the Basics of Waving Machines	les	ology		
Unit		Description		Ins	tructio	nal
	BASICS OF PRO				Hours	
I ,	History of Textile Overview of Textil Objectives and Pro	Technology and its Advancements - Introduce Manufacturing - Introduction to Automatio occss Variables in Processing Machines - ng - Mercerizing - Dyeing - Printing - Finishir	n in Textile Industries - Singeing - Desizing -		9	
11	Spinning Process F	low Chart - Objectives and Process Variables ng - Blow Room - Carding - Draw Frame - Co or Spinning.	of Textile Spinning ombing - Speed Frame		9	
III	Weaving Process Fl Preparatory Windin in Weaving - Drawi	owchart - Objectives and Process Variables i g, Warping, Sizing and Beaming - Objectives ng In, Knotting, Denting and Weaving. N SPINNING MACHINERY	n Weaving - s and Process Variables		9	
IV :	Machinery Material Levelers - Safety S Length Monitors - E Rotor Spinning - CA	Flow and its Variation Controls - Feeders & witches - Production and Quality Monitors Data Acquisition System for Spinning Prepara AD / CAM / CIM in Spinning. WEAVING MACHINERY	- Full Doff and Preset		9	
V	Yarn Cleaner Contr Monitors and Contr Drawing In and Kno	ols - Knotter / Splicer Carriage Controls - Wols - Sizing Machine Monitors and Control titing Machine Monitors and Controls - Data y and Weaving - Humidification Systems - V	ols - Auto Reaching / Acquisition System in		9	
		Tota	l Instructional Hours		45	
Course Outcome	CO1: Evaluate Te CO2: Describe va CO3: List out the CO4: Explain vari	e course the students will be able to xtile Technology and Manufacturing with Te rious process involved in Spinning various process involved in Weaving ous stages of Automation scopes in Spinning role of computers in Automated Weaving Manufacture of computers in Automated Weaving Manufacture in Automated Weaving Manufacturing in Automated Weaving Manufacturing in Automated Weaving Manufacturing with Technology and M	Machinery			

- T1- Ashok Kumar.L, Senthil Kumar., "Automation in Textile Machinery: Instrumentation and Control System Design Principles", 1st Edition, CRC Press, USA, 2018.
- T2- J Chattopadhyay R, "Advances in Technology of Yarn Production", 1st Edition, NCUTE, IIT Delhi, 2002...

CO5: Outline the role of computers in Automated Weaving Machinery

REFERENCE BOOKS:

- R1- Krishna Kant, "Computer Based Industrial Control". 2nd Edition, PHI Learning Private Limited, New Delhi, 2011.
- R2- Oxtoby E, "Spun Yarn Technology", New Edition, Butter Worth"s, London, 2012.
- R3- R Shishoo, "The Global Textile and Clothing Industries", 1st Edition, Woodhead Publications, 2012.
- R4- P V Vidhyasagar, "Encyclopedia of Textiles" Mittal Publications, New Delhi, 2000.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Dean (Academ...)
HiCET

	***	· ·			Марр	ing of C	Os wit	h POs a	nd PSO	s				- 1865 E. S.
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1	PO1	PSO-1	PSO-2
CO1	1		2					A. Life P. Lie and M. College and M.	1	1	1	l	1	
CO2	1		3								The state of the s	1	2	
CO3			2		1								2	
CO4			3										3	
CO5	1 .		1									1	1	
-AVG	0.6	-	2.2	-	0.2	-	-	-	0.2	0.2	0.2	0.6	1.8	

• 1-low, 2-medium, 3-high, '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Dean (Academics)

HiCET

Programme	Course Code	Name of the Course	7	p	C
BE	19MT7303	MEDICAL MECHATRONICS 3	()	()	3
Course Objective	 To introduce t To learn diffe To discuss the 	the Role of Instrumentation in Medical Applications he various Sensing and Measurement devices rent types of Amplifiers and Filters need and technique of Electrical Safety in Hospitals dvanced equipments in Medicine			
Unit		Description		ructio Iours	
	MEDICAL EQUIPA	MENTS	r	iours	
I	Cell Structure - Elect Action Potential - Ele Description - Method	rode - Electrolyte Interface, Electrode Potential, Resting and actrodes for their Measurement, ECG, EEG, EMG, Machine s of Measurement.		9	
•	SENSORS AND TR	ANDUCERS IN BIO-MEDICAL APPLICATIONS			
II	Photoelectric, Chemic Feature Applicable fo	nciples - Types - Resistive, Inductive, Capacitive, Fiber - Optic. cal, Active and Passive Transducers and their Description and r Biomedical Instrumentation - Bio, Nano Sensors and		9	
	Application.				
III	Input Isolation, DC A Amplifier - Feedback	RECORDING AND DISPLAY OF BIOSIGNALS Implifier, Charge Amplifier, Power Amplifier and Differential Operational Amplifier - Electrometer Amplifier, Carrier It Power Supply, Basis of Signal Conversion and Digital Filtering.		9	
IV	Measurement by Elec Method - Vector Card	urement: by Ultrasonic Method - Plethysmography - Blood Flow tromagnetic Flow Meter Cardiac Output Measurement by Dilution liography. Heart Lung Machine - Artificial Ventilator - Anesthetic cemaker - DC - Defibrillator- Patient Safety - Electrical Shock		9	
		TUDIES IN MECHATRONICS			a
V	Smart Probe for Detec	ting Kidney Stones, Smart Probe for Breast Cancer, Ankle tic Knee, Smart System for Cardiovascular Plaque Detection.		9	
		Total Instructional Hours		45	
Course Outcome	CO1: Select modern CO2: Select differen CO3: Describe the si CO4: Identify differe	course the students will be able to engineering and Information Technology tools for Engineering Practit sensors and transducers for Biomedical Instrumentation gnal conditioning circuits used in Biomedical Engineering ent measurement techniques used in physiological parameters measure oblems in various fields of Medical Practices.			

- T1- Khandpur, R.S., "*Handbook of Biomedical Instrumentation*", 3rd Edition, Tata McGraw Hill Publishing CompanyLimited, NewDelhi, 2014.
- T2- Siamak Najarian, Javad Darghai, Goldis Darbemamieh, Siamak H. Farkoush, "Mechatronics in Medicine A Biomedical Engineering Approach", 1st Edition, Tata McGraw Hill Publishing CompanyLimited, New Delhi, 2012.

REFERENCE BOOKS:

- R1- Tompkins W.J., "Biomedical Digital Signal Processing", 1st Edition, PHI Learning Private Limited, New Delhi, 2000.
- R2- Cromwell, Weibell and Pfeiffer, "Biomedical Instrumentation and Measurements", 2nd Edition, PHI Learning Private Limited, New Delhi, 2010.
- R3- Arumugam, "Bio Medical Instrumentation", Anuradha Agencies Publications, 2002.
- R4- Geddes L.A., and Baker, L.E., "Principles of Applied Bio-medical Instrumentation", 3rd Edition, John Wiley and Sons. 2010

Chairman, Board of Studies

Chairman - Bos

MCT - HiCET



DEANACADEMICS

Doesn'A (Academics)
HINCET

	Mapping of COs with POs and PSOs														
CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1 2	PSO-1	PSO-2	
CO1	3	1	2	2	and the second s				PALL			2	2	2	
CO2	2	3	2	2	2	A DESCRIPTION OF THE PERSON OF						1	2	1	
CO3	.3	2	2	2	1			The state of the s		The state of the s		3	3	3	
CO4	2	2	2	1	1				Police	1		2	3	2	
CO5	2	2	3	2	1				1	2	3	2	3	3 .	
AVG	2.4	2	2.2	1.8	1	-	-	-	0.6	0.6	0.6	2	2.6	2.2	

1-low, 2-medium, 3-high, '-"- no correlation Note: The average value of this course to be used for program articulation matrix.

Chairman - Bos MCT - HiCET



Programme BE	Course Code 19MT7304	Name of the Course DISASTER MANAGEMENT	I. T	P	_
				0	3
	 To provide stude To understand th 	ents an exposure to disasters, their significance and types.			
Course		relationship between vulnerability, disaster prevention coaches of psychological impact of disasters	k ikreduction		
Objective	I	isk management with respect to India			
	5. To understand th	e technological disaster			
Unit		Description	Instrue	tional	Hanna
	INTRODUCTION	TO DISASTERS			Hours
· I	economic, political, caste, class, gender	Hazard, Vulnerability, Resilience, Risks - Disasters: T de, Flood, Drought, Fire - Classification, Causes, Impact environmental, health, psychosocial, etc Differential in age, location, disability - Global trends in disasters emergencies, Climate change- Dos and Don'ts during	s including social pacts in terms of the urban disaster.	al, of 9	
	APPROACHES TO	DISASTER RISK REDUCTION (DRR)			
II	Disaster cycle - Pha: based DRR, Structu Panchayati Raj Instit holders- Institutiona	ses, Culture of safety, prevention, mitigation and prepare ral-non-structural measures, Roles and responsibilitie autions/Urban Local Bodies (PRIs/ULBs), States, Centre, 1 Process and Framework at State and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity(SDMA) - Early Warning System - Advisories from the state and Central Leverity (SDMA) - Early Warning System - Advisories from the state and Central Leverity (SDMA) - Early Warning System - Advisories from the state and Central Leverity (SDMA) - Early Warning System - Advisories from the state and Central Leverity (SDMA) - Early Warning System - Advisories from the state and Central Leverity (SDMA) - Early Warning System - Advisories from the state and Central Leverity (SDMA) - Early Warning System - Advisories (SDMA)	s of- community and other stake el- State Disaste	y, - 9	
		IMPACT OF DISASTERS			
III	Introduction – Appro Special Intervention	paches and Diagnostic Issues –Principles of psychosociall techniques – Stress Reduction Techniques.	ntervention -	9	
		ANAGEMENT IN INDIA			
IV IV	Sanitation, Shelter, I Response and Prepar plans, programmes a	bility profile of India, Components of Disaster Relief Health, and Waste Management, Institutional arrangement edness, Disaster Management Act and Policy - Other and legislation - Role of GIS and Information Technology sponse and Recovery Phases of Disaster - Disaster Dama	ents Mitigation, related policies,	9	
		DISASTER AND CASE STUDIES			
V	Technological disaste of GIS Technology-	er - Industrial hazards -Fire hazards - Role of remote sen Accidental Disaster, Case Studies, Space Based Ing gement and field works related to disaster management.	sing -Application outs for Disaste	n 9	
		Total Instructi	onal Hour	45	
Course Outcome TEXT BOOKS:	CO1: Differentiate the the CO2: Assess vulnerabil CO3: Interpret the psyc CO4: Express the know	course the students will be able to types of disasters, causes and their impact on environmenty and various methods of risk reduction measures as we hological impact and its reduction techniques. ledge disaster management with respect to India dustrial hazard and its management.	t and society. Il as mitigation.		
	ID "Diseate: M				
T2- Tushar E 1259007 T3- KapurAr REFERENÇE I R1- Gupta A 2011R2- Go	Bhattacharya, "Disaster Sc 367,ISBN-13: 978-12590 nu Vulnerable India: A Ge B OOKS: Anil K, Sreeja S. Nair.I ovt. of India: Disaster N	cographical Study of Disasters. IIAS and Sage Publishers, Environmental Knowledge for Disaster Risk Manage Management Act, Government of India, New Delhi.	vt. Ltd., 2012. IS New Delhi, 2010 ement NIDM	SBN-10 0.): ·
R3- Govern R4- R Subra	ment of India, Nationa amanian,, "Disaster Ma	l Disaster Management Policy,2009. magement", Vikan Publishers, New Delhi, 2018.		Λ	7

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



DEAN ACADEMICS

Dean (Academ...,

Manning	of COs	with POs	and PSOs

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	PO7	PO8	PO9	PO1 0	PO1 1	PO1 2	PSO-1	PSO-2
CO1	3	3	2.2	1.2	l		_	-	TO STATE OF THE PARTY OF THE PA	-	1	1	1.8	1
CO2	3	3	2.2	1.2	1	I	-	-	-	-	1	1	1.8	I
CO3	3	3	2.2	1.2	1	1	-	-	-	-	1	1	1.8	1
CO4	3	3	2.2	1.2	1	1	-	-	-	-	1	1	1.8]
CO5	3	3	2.2	1.2	1	1	_	-	-	-	1	. 1	1.8]
AVG	3	3	2.2	1.2	- 1	1	-	-	-	-	1	1	1.8	1

• 1-low, 2-medium, 3-high. '-"- no correlation

Note: The average value of this course to be used for program articulation matrix.

CHAIRMAN, BOARD OF STUDIES

Chairman - Bos

MCT - HICET



DEAN ACADEMICS

Programme BE	Course Code 19MT7305	Name of the Course FACTORY AUTOMATION	L.	T 0	P 0	C 3
Course Objective	2. To clas 3. To stuc 4. To lear	art knowledge of automation in manufacturing industries saffy material handling system and AGVs by various storage methods and its equipments about manufacturing cells and automated assembly lines out different assembly methods in industries				
Unit		Description			tructio Hours	
. 1	of an Automated S Hardware Compon	AUTOMATION duction Systems - Automation Principles and Strategies - El system - Advanced Automation Function - Levels of Automa sents for Automation and Process Control. ANSPORT SYSTEM	ements tion -		9	
11	Introduction - Mate - Industrial trucks Vehicles - Convey - Conveyor Analys		9			
III	STORAGE SYST Introduction - Perficult Equipment - Autor Analysis of Storage MANUFACTURI	ormance - Strategies - Conventional Storage Methods and nated Storage System - Carousel Storage System - Engineer e System.	ing		9	
IV	Components of Ma	unufacturing System - Single Station Manufacturing Cells, M Automated Production Lines - Automated Assembly Systems	lanual s.		9	
V	Robotic Assembly. Compliance and Ro Assembly System.	Automation - Parts Presentation Methods - Assembly Opera emote Centre Compliance (RCC) Device - Adaptable Progra	tions - ımmable		9	
		Total Instruction	al Hours		45	
Course Outcome	CO1: Apply the a CO2: Develop dif CO3: Propose the CO4: Compare m	he course the students will be able to utomation principles in manufacturing systems ferent material handing mechanisms for industries benefits of automated storage systems anual assembly lines and automated assembly lines different assembly operations in industries				

- T1- Groover, M.P. "Automation, Production Systems, and Computer Integrated Manufacturing", 3rd Edition, Pearson Education, 2008.
- T2- C.Ray Asfahl, "Robtos and Manufacturing automation", 2nd Edition, John Wiley and Sons Ltd., New Delhi, 2011.

REFERENCE BOOKS:

- R1- Groover, M.P. and Simmers, E.W. "Computer Aided Design and Manufacturing", Pearson Education, New Delhi, 2009.
- R2- Nand K. Jha. "Handbook of Flexible Manufacturing Systems", Academic Press, Orlando, 2006.
- R3- Groover, M.P., "Fundamentals of Modern Manufacturing", Pearson Education, New Delhi. 2004.
- R4- Daniel E Kandray P E, "Programmable Automation", Industrial Press Publications, New Delhi, 2008.

WEB REFERENCES:

- $1. \quad http://een.iust.ac.ir/profs/Shamaghdari/Mechatronics/Resources/3Shetly_Mechatronics\%20System\%20Design.$
- 2. http://mte401.weebly.com/uploads/1/4/0/7/14075053/2hr15sep14.pdf

CHAIRMAN, BOARD OF STUDIES

Chairman - BoS MCT - HiCET



Mannino	of CO	cwith Po	Os and	PSO ₅

CO/PO	PO1	PO2	PO3	PO4	PO5	PO6	РО7	PO8	PO9	PO1 0	PO1 1	PO1 2	PSO-1	PSO-2
CO1	3	3	2.	2	3	-			-	2	1	3	2	2
CO2	3	3	2	2	3	_			-	2	1	. 3	2	2
CO3	3	3	2	2	3	-			_	2	1	3	2	2
CO4	3	3	2	2	3	-			_	2	1	3	2	2
CO5	3	3	2	2	3	-				2	1	3	2	. 2
AVG	3	3	2	2	3	-	_	_	_	2	1	3	2	2

- 1-low, 2-medium, 3-high. '-"- no correlation
- Note: The average value of this course to be used for program articulation matrix.

Chairman, Board of Studies
Chairman - Bos
MCT - HiCET



DEAN ACADEMICS

Programme	Course Code	Name of the Course	L	Т	P	C						
BE	19MT7401	PROJECT MANAGEMENT	3	0	0	3						
Course Objective	2. To learn the 3. To acquire to Software Pr 4. To discuss to	how to plan and manage the projects at each stage of the successful projects that support organization is Strategothe knowledge about the activities necessary to successful projects the various categories of risk involved in Project Development the knowledge about Organizational Behavior and Teach	gic Goals sfully complete :			fe						
Unit		Description			ructio							
	SOFTWARE PRO	JECT MANAGEMENT			Hours							
I	Introduction - Need	for Software Project Management - Activities by Software Project versus Other Projects - Categories of Soft	ware Project ware		9							
II	Project Evaluation: Individual Projects - Programme Manage Programme Manage Benefits Manageme	PROJECT EVALUATION AND PROGRAMME MANAGEMENT Project Evaluation: Introduction - Project Portfolio Management - Evaluation of Individual Projects - Cost Benefit Analysis and Evaluation Techniques. Programme Management: Managing the Allocation of Resources - Strategic Programme Management - Creating a Programme - Aids to Programme Management -										
III	Sequencing and Sc	ty Planning - Project Schedules, Projects and Activities cheduling Activities, Network Planning Modes entifying Critical Path, Identifying Critical Activities.	Formulating		9	•						
IV	Introduction – Risk and Identification - Risk Applying the PERT	and categories of risk - Framework for Dealing with R Assessment - Risk Planning - Evaluating Risks to the Technique - Monte Carlo Simulation. EMENT AND TEAM ORGANIZATION	isk - Risk Schedule -		9							
V	Managing People: U Right Person for the Taylorist model - Str Decision Making - C	n based on		9								
		Total Instruc	tional Hours		45							
Course Outcome	CO1: Integrate orga CO2: Plan and man CO3: Analyze betw CO4: Describe vari	anizational needs to the most effective Software Developme reproducts at each stage of the Software Developme reen planning modules that address Real World Manage ous types of Risk, Risk Identifications and planning in the forward response to the software reproductive response to the software reproductive reproductive response to the software reproductive reproductive response to the software reproductive	lopment Model nt Life Cycle gement Challeng volved in Projec	es et Man	agemer	nt						

T1- Bob Hughes, Mike Cotterel, Rajib Mall, "Software Project Management", 6th Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2017.

CO5: Applying skill of working as a team and as a decision maker in an Organization

T2- Gopalaswamy Ramesh, "Managing Global Software Projects", 1st Edition, Tata McGraw Hill Publishing Company Limited, New Delhi, 2005.

REFERENCE BOOKS:

- R1- Dick Billows, "Essentials of Software Project Management", 1st Edition, Hampton Group Inc., 2004.
- R2- Donald J.Reifer, "Software Management", 7th Edition, John Wiley & Sons Ltd., New Delhi, 2006.
- R3- Robert K. Wysocki "Effective Software Project Management" Wiley Publication, 2011.
- R4- Walker Royce: "Software Project Management"- Addison-Wesley. 1998.

CHAIRMAN, BOARD OF STUDIES
Chairman - BoS
MCT - HiCET

